RESEARCH ARTICLE

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Design And Verification of AMBA APB Protocol

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ABSTRACT:

Advanced microcontroller bus architecture (AMBA) is a well established open specification for the proper management of functional blocks comprising system-on-chips (SOCs). A Memory Controller is designed to cater to this problem. This design presents an intellectual property (IP) for inter-Advanced peripheral bus (APB) protocol. The Memory Controller is a digital circuit which manages the flow of data going to and from the main memory. It can be a separate chip or can be integrated into the system chipset. This paper revolves around building an Advanced Microcontroller Bus Architecture (AMBA) compliant Memory Controller as an Advanced High-performance Bus (AHB) slave. The work involved is of APB Protocol and its slave Verification. The whole design is captured using VHDL, simulated with ModelSim and configured to a FPGA target device belonging to the Virtex4 family using Xilinx.

I. INTRODUCTION

In the realm of processing, these elements perform different tasks in order to realize an overall solution. Consider a set-top box for television (TV) sets as an example [1]. A set-top box must generate inputs for a particular television channel from the received digital satellite signal. The entire process incorporates several phases. The first is to split the incoming digital signal into its component video and audio data streams. The next phase is to convert the video data stream into its actual television signal. Also, the audio data stream has to be changed into audio signal for the TV set. Besides, an additional job to look after will be to handle the user input for changing the channel when the remote control will be pressed. All these operations have to be completed not only simultaneously but within a certain time frame. The cost of not accomplishing these within the stipulated time frame or deadline will be manifested in the form of blank screen or audible noises. This is obviously unacceptable and hence, it is necessary to always deliver the data within real-time deadlines. The needed computational elements here will be either general-purpose or special-purpose processors (such as signal processors). Nowadays, multitudes of these devices are integrated in the form of an SOC. A processor needs to interact with other processors, memories or input/output (I/O) devices to complete a task. Currently, bus systems are used to interconnect the intellectual property (IP) blocks.

Many SoCs comprise Application Specific Integrated Circuits (ASICs) that are offered by several companies. The Advanced RISC Machines (ARM) microprocessor is very popular for SoC solutions. Today it is fair to say that the ARM Embedded Technology is universally recognized as an industry standard for ASIC design for portable applications. Creating and applying powerful, portable and at the same time re-usable intellectual Property (IP), capable of enhancing an ARM core is therefore of utmost importance to any ASIC design centre.

Description Of Amba Ahb Bus.

An AMBA AHB design may include one or more bus masters, typically a system would contain at least the processor and the test interface. However, it would also be common for a Direct Memory Access (DMA) or Digital Signal Processor (DSP) to be included as bus masters. The external memory interface, the Advanced Peripheral Bus (APB) Bridge and any internal memory are the most common AHB slaves. Any other peripheral in the system could also be included as an AHB slave. However, lowbandwidth peripherals typically reside on the APB.



Fig. 1 A typical AMBA architecture.

Before an AMBA AHB transfer can commence the bus master must be granted access to the bus. This process is started by the master asserting a request signal to the arbiter. Then the arbiter indicates when the master will be granted use of the bus. A granted bus master starts an AMBA AHB transfer by driving the address and control signals. These signals provide information on the address, direction and width of the transfer, as well as an indication if the transfer forms part of a burst. Two different forms of burst transfers are allowed: incrementing bursts, which do not wrap at address boundaries; and wrapping bursts, which wrap at particular address boundaries. A write data bus is used to move data from the master to a slave, while a read data bus is used to move data from a slave to the master.



Fig.2 An AMBA AHB design with three masters and four slaves.

Apb Block Diagram:

The APB is the member of the AMBA 3 protocol family which implements a low cost interface which minimizes the power consumption and reduces the interface complexity. Since APB has unpipelined protocol. Therefore, it interfaces to the low bandwidth peripherals that do not demand the high performance of the pipelined bus interface. All the signal transitions are associated with the rising edge of the clock which makes it simple to integrate APB peripherals into any design flow. APB can interface with the AMBA AHB-Lite and AMBA Advanced Extensible Interface (AXI). APB can also be used to access the programmable control registers of the peripheral devices.



Fig3: Interfacing of APB Master & Slave.

Table	1.	List	of A	٩PB	signa	ls

Table 1. Elst of AT D signals			
Signal	Signal Description		
PCLK	Clock. The rising edge of PCLK		
	times all transfers on the APB.		
PRESET	System bus equivalent Reset. The		
	APB reset signal is active LOW.		
PADDR	32 bit. address bus		
PSEL	The slave device is selected and		
	that a data transfer is required.		
PENABLE	Enable. This signal indicates the		
	second and subsequent cycles of		
	an APB transfer.		

PWRITE	Access when HIGH.		
PWDATA	32 bits. Write data .PWRITE is		
	HIGH.		
PREADY	Ready. To extend an APB		
	transfer.		
PRDATA	32 bits. Read data. PWRITE is		
	LOW.		
PSLAVERR	Slave error. This signal indicates		
	a transfer failure,		

Idle is the normal state of the APB. When a Transfer is necessary the bus relocates into the Setup state, where the suitable select signal, Pselx, is asserted.



Fig3: State diagram.

The bus only waits in the SETUP state for one clock cycle and always moves to the ACCESS state on the next rising edge of the clock. ACCESS will enable signal, PENABLE, is asserted in the ACCESS state. The write, write data signals, select, and address must remain stable during the transition from the SETUP to ACCESS state. ACCESS state is controls when to exit by the PREADY signal from the slave.

These are the conditions one is if PREADY is held LOW by the slave then the peripheral bus remains in the ACCESS state another is PREADY is driven HIGH by the slave then the ACCESS state is exited and the bus returns to the IDLE state if no more transfers are required after that it will start the same cycle.



Fig6: RTL Schematic diagram of APB Master Slave Burst.

Write cycle

At T1, a write transfer starts with PADDR, PWDATA, PWRITE, and PSEL, being registered at the rising edge of PCLK. It is called the SETUP cycle. At the next rising edge of the clock T2 it is called ACCESS cycle, PENABLE, and PREADY, are registered. When asserted, PENABLE indicates starting of Access phase of the transfer. When asserted, PREADY indicates that the slave can complete the transfer at the next rising edge of PCLK. The PADDR, PWDATA, and control signals all remain valid until the transfer completes at T3, the end of the Access phase. The PENABLE, is disabled at the end of the transfer. The select signal PSEL is also disabled unless the transfer is to be followed immediately by another transfer to the same peripheral.



Read cycle

During read operation the PENABLE, PSEL, PADDR PWRITE, signals are asserted at the clock edge T1 (SETUP cycle). At the clock edge T2, (ACCESS cycle), the PENABLE, PREADY are asserted and PRDATA is also read during this phase. The slave must provide the data before the end of the read transfer.





Simulation Results





II. CONCLUSION

This paper gives an outline of the AMBA bus architecture and explains the APB bus in detail. The design has taken care of balance between area overhead and speed. The read write operation is accomplished with zero wait states from the external ROM and the write operation with zero states to the external RAM. The APB bus is designed using the Verilog HDL according to the specification and is verified using Xilin x.

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