Design Of Low-Power High-Speed Truncation-Error Tolerant Adder And Its Application In Digital Signal Processing

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Abstract

In conventional digital VLSI design, one usually assumes that a usable circuit/system should always provide definite and accurate results. But in fact, such perfect operations are seldom needed in our non digital worldly experiences. The world accepts "analog computation," which generates "good enough" results rather than totally accurate results [1]. The data processed by many digital systems may already contain errors. In many applications, such as a communication system, the analog signal coming from the outside world must first be sampled before being converted to digital data. The digital data are then processed and transmitted in a noisy channel before converting back to an analog signal. During this process, errors may occur anywhere. Furthermore, due to the advances in transistor size scaling, factors such as noise and process variations which are previously insignificant are becoming important

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Keyword's— VLSI, Communication, digital data, digital IC design

I.Introduction

In conventional digital VLSI design, one usually assumes that a usable circuit/system should always provide definite and accurate results. But in fact, such perfect operations are seldom needed in our nondigital worldly experiences. The world accepts "analog computation," which generates "good enough" results rather than totally accurate results. The data processed by many digital systems may already contain errors. In many applications, such as a communication system, the analog signal coming from the outside world must first be sampled before

being converted to digital data. The digital data are then processed and transmitted in a noisy channel before converting back to an analog signal. During this process, errors may occur anywhere. Furthermore, due to the advances in transistor size scaling, factors such as noise and process variations which are previously insignificant are becoming important in today's digital IC design. Based on the characteristic of digital VLSI design, some novel concepts and design techniques have been proposed. The concept of error tolerance (ET) and the PCMOS technology are two of them. According to the definition, a circuit is error tolerant if: 1) it contains defects that cause internal and may cause external errors and

2) The system that incorporates this circuit produces acceptable results the "imperfect" attribute seems to be not appealing. However, the need for the error-tolerant circuit was foretold in the 2003 International

Technology Roadmap for Semiconductors (ITRS). To deal with error-tolerant problems, some truncated adders/multipliers have been reported, but are not able to perform well in its speed, power, area, or accuracy. The "flagged prefixed adder" performs better than the non flagged version with a 1.3% speed

enhancement but at the expense of 2% extra silicon area. As for the "low-error area-efficient fixed-width multipliers", it may have an area improvement of 46.67% but has average error reaching 12.4%. Of course, not all digital systems can engage the error-tolerant concept. In digital systems such as control systems, the correctness of the output signal is extremely important, and this denies the use of the error tolerant circuit. However, for many digital signal processing (DSP) systems that process signals relating to human senses such as hearing, sight, smell, and touch, e.g., the image processing and speech processing systems, the error-tolerant circuits may be applicable. The rest of the paper is organized as follows.

Ii. Existing System

Increasingly huge data sets and the need for instant response require the adder to be large and fast. The traditional ripple-carry adder (RCA) is therefore no longer suitable for large adders because of its low-speed performance. Many different types of fast adders, such as the carry-skip adder (CSK), carry-select adder (CSL) , and carry-look-ahead adder (CLA) [18], have been developed. Also, there are many low-power adder design techniques that have been proposed [19]. However, there are always trade-offs between speed and power. The error-tolerant design can be a potential solution to this problem. By sacrificing some accuracy, the ETA can attain great improvement in both the power consumption and speed performance.

Iii. Proposed System:

In a conventional adder circuit, the delay is mainly attributed to the carry propagation chain along the critical path, from the least significant bit (LSB) to the most significant bit (MSB). Meanwhile, a significant proportion of the power consumption of an adder is due to the glitches that are caused by the carry propagation. Therefore, if the carry propagation can be eliminated or curtailed, a great improvement in speed performance and power consumption can be achieved. In this paper, we propose for the first time, an innovative and novel addition arithmetic that can attain great saving in speed and power consumption. This new addition arithmetic can be illustrated via an example shown in Fig. 1. We first split the input operands into two parts: an accurate part that includes several higher order bits and the inaccurate part that is made



Fig 1: Block diagram

A. Need For Error-Tolerant Adder

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The error-tolerant design can be a potential solution to this problem. By sacrificing some accuracy, the ETA can attain great improvement in both the power consumption and speed performance.

B. Proposed Addition Arithmetic

In a conventional adder circuit, the delay is mainly attributed to the carry propagation chain along the critical path, from the least significant bit (LSB) to the most significant bit (MSB). Meanwhile, a significant proportion of the power consumption of an adder is due to the glitches that are caused by the carry propagation. Therefore, if the carry propagation can be eliminated or curtailed, a great improvement in speed performance and power consumption can be achieved. In this paper, we propose for the first time, an innovative and novel addition arithmetic that can attain great saving in speed and power consumption.



We first split the input operands into two parts: an accurate part that includes several higher order bits and the inaccurate part that is made up of the remaining lower order bits. The length of each part need not necessary be equal. The addition process starts from the middle (joining point of the two parts) toward the two opposite directions simultaneously.

In the example of Fig. 1, the two 16-bit input operands, "1011001110011010" (45978) and \Box "0110100100010011" (26899), are divided equally into 8 bits each for the accurate and inaccurate parts. The addition of the higher order bits (accurate part) of the input operands is performed from right to left (LSB to MSB) and normal addition method is applied. This is to preserve its correctness since the higher order bits play a more important role than the lower order bits. The lower order bits of the input operands (inaccurate part) require a special addition mechanism. No carry signal will be generated or taken in at any bit position to eliminate the carry propagation path. To minimize the overall error due to the elimination of the carry chain, a special strategy is adapted, and can be described as follow: 1) check every bit position from left to right (MSB to LSB); 2) if both input bits are "0" or different, normal one-bit addition is performed and the operation proceeds to next bit position; 3) if both input bits are "1," the checking process stopped and from this bit onward, all sum bits to the right are set

to "1." The addition mechanism described can be easily understood from the example given in Fig. 1 with a final result of "10001110010011111" (72863).

Iv. Design Of A 32-Bit Error-Tolerant Adder

A. Strategy of Dividing the Adder The first step of designing a proposed ETA is to divide the adder into two parts in a specific manner. The dividing strategy is based on a guess-and-verify stratagem, depending on the requirements, such as accuracy, speed, and power. With this partition method defined, we then check whether the accuracy performance of the adder meets the requirements preset by designer customer. This can be checked very quickly via some software

programs. For example, for a specific application, we require the minimum acceptable accuracy to be 95% and the acceptance probability to be 98%. The proposed partition method must therefore have at least 98% of all possible inputs reaching an accuracy of better than 95%. If this requirement is not met, then one bit should be shifted from the inaccurate part to the accurate part and have the checking process repeated. Also, due to the simplified circuit structure and the elimination of switching activities in the inaccurate part, putting more bits in this part yields more power saving. Having considered the above, we divided the 32-bit adder by putting 12 bits in the accurate part and 20 bits in the inaccurate part.

Design of the Accurate Part

In our proposed 32-bit ETA, the inaccurate part has 20 bits as opposed to the 12 bits used in the accurate part. The overall delay is determined by the inaccurate part, and so the accurate part need not be

a fast adder. The ripple-carry adder, which is the most power-saving conventional adder, has been chosen for the accurate part of the circuit.

Design of the Inaccurate Part

The inaccurate part is the most critical section in the proposed ETA as it determines the accuracy, speed performance, and power consumption of the adder. The inaccurate part consists of two blocks: the arryfree addition block and the control block. The carry-free addition block is made up of 20 modified XOR gates, and each of which is used to generate a sum bit. The block diagram of the carry-free addition block and the schematic implementation of the modified XOR gate are presented. In the modified XOR gate, three extra transistors, M1, M2, and M3, are added to a conventional XOR gate. CTL is the control signal coming from the control block of Fig. 6 and is used to set the operational mode of the circuit. When M1 and M2 are turned on, while M3 is turned off, leaving the circuit to operate in the normal XOR mode. When M1 and M2 are both turned

off, while M3 is turned on, connecting the output node to VDD, and hence setting the sum output to "1." The function of the control block is to detect the first bit position when both input bits are "1," and to set the control signal on this position as well as those on its right to high. It is made up of 20 control signal generating cells (CSGCs) and each cell generates a control signal for the modified XOR gate at the corresponding bit position in the carry-free addition block. Instead of a long chain of 20 cascaded GSGCs, the control block is arranged into five equal-sized groups, with additional connections between every two neighbouring groups. Two types of CSGC, labelled as type I and II, are designed, and the schematic implementations of these two types of CSGC are provided. The control signal generated by the leftmost cell of each group is connected to the input of the leftmost cell in next group. The extra connections allow the propagated high control signal

to "jump" from one group to another instead of passing through all the 20 cells. Hence, the worst case propagation path consists of only ten cells.

V. Experimental Results

To demonstrate the advantages of the proposed ETA, we simulated the ETA along with four types of conventional adders, i.e., the RCA, CSK, CSL, and CLA, using HSPICE. All the circuits were implemented using Chartered Semiconductor Manufacturing Ltd's CMOS process. The input frequency was set to 100 MHz, and the simulation results are all tabulated in Table I. HSPICE software was used to construct the models of our proposed ETA and the conventional adders. 100 sets of inputs were randomly created using the C program "random ()" function. For each set of input, we ran the simulation for each adder and recorded the power consumption. With 100 sets of results, average power consumption was determined. The worst case input was calculated and used to simulate the delay. The transistor count was derived directly from the HSPICE software.

Comparing the simulation results of our proposed ETA with those of the conventional adders (see Table I), it is evident that the ETA performed the best in terms of power consumption, delay, and Power- Delay Product (PDP). The PDP of the ETA is noted to be 66.29%, 77.44%, 83.70%, and 75.21% better than the RCA, CSK, CSL, and







Fig. 4. Control block. (a) Overall architecture and (b) schematic implementations of CSGC

Table I

Simulation Result For Eta Versus Conventional Adders

Type of Adder	Power (mW)	Delay (ns)	PDP (pJ)	PDP saving (%)	Transistor Count
RCA	0.22	4.04	0.89	66.29	896
CSK	0.46	2.90	1.33	77.44	1728
CSL	0.60	3.06	1.84	83.70	2176
CLA	0.51	2.37	1.21	75.21	2208
ETA	0.13	2.29	0.30	N.A.	1006

CLA, respectively. As for transistor count, the proposed ETA is almost as good as the RCA.

Vi. Application Of Error-Tolerant Adder In Digital Signal Processing

In image processing and many other DSP applications, fast Fourier transformation (FFT) is a very important function. The computational process of FFT involves a large number of additions and multiplications. It is therefore a good platform for embedding our proposed ETA. To prove the feasibility of the ETA, we replaced all the common additions involved in a normal FFT algorithm with our proposed addition arithmetic. As we all know, a digital image is represented by a matrix in a DSP system, and each element of the matrix represents the color of one pixel of the image. To compare the quality of images processed by both the conventional FFT and the inaccurate FFT that had incorporated our

proposed ETA, we devised the following experiment. An image was first translated to a matrix form and sent through a standard system that made used of normal FFT and normal reverse FFT. The matrix output of this system was then transformed back to an image and presented in Fig. The matrix of the same image was also processed in a system that used the inaccurate FFT and inaccurate reverse FFT, where both FFTs had incorporated the 32-bit ETA, with the processed image given. Although the two resultant matrices of the same image were different, the two pictures obtained look almost the same. Figure is slightly darker and contains horizontal bands of different shades of gray. With a MAAsetting of 95%, the AP of the matrix representation of Figure is 98.3% as compared to the matrix representation of Fig. 7(a). The comparison between the two images in Fig. 7 shows that the quality loss to the image using our proposed ETA is negligible and can be completely tolerated by human eyes. These simulation results have proven the practicability of the ETA proposed in this paper.







Fig. Images after FFT and inverse FFT. (a) Image processed with conventional adder and (b) image processed with the proposed ETA.

Vi. Conclusion

In this paper, the concept of error tolerance is introduced in VLSI design. A novel type of adder, the error-tolerant adder, which trades certain amount of accuracy for significant power saving and performance improvement, is proposed. Extensive comparisons with conventional digital adders showed that the proposed ETA outperformed the conventional adders in both power consumption and speed performance. The potential applications of the ETA fall mainly in areas where there is no strict requirement on accuracy or where superlow power consumption and high-speed performance are more important than accuracy. One example of such applications is in the DSP application for portable devices such as cell phones and laptops.

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