

A Survey on Visual Content-Based Video Indexing and Retrieval

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ABSTRACT Video indexing and retrieval have a wide spectrum of promising applications, motivating the interest of researchers worldwide. This paper offers a tutorial and an overview of the landscape of general strategies in visual content-based video indexing and retrieval, focusing on methods for video structure analysis, including shot boundary detection, key frame extraction and scene segmentation, extraction of features including static key frame features, object features and motion features, video data mining, video annotation, video retrieval including query interfaces, similarity measure and relevance feedback, and video browsing. Finally, we analyze future research directions.

Index Terms—Feature extraction, video annotation, video browsing, video retrieval, video structure analysis.

I. INTRODUCTION

MULTIMEDIA information indexing and retrieval [44] are required to describe, store, and organize multimedia information and to assist people in finding multimedia resources conveniently and quickly. Dynamic video is an important form of multimedia information. Videos have the following characteristics: 1) much richer content than individual images; 2) huge amount of raw data; and 3) very little prior structure. These characteristics make the indexing and retrieval of videos quite difficult. In the past, video databases have been relatively small, and indexing and retrieval have been based on keywords annotated manually. More recently, these databases have become much larger and content-based indexing and retrieval are required, based on the automatic analysis of videos with the minimum of human participation. Content-based video indexing and retrieval have a wide range of applications such as quick browsing of video folders, analysis of visual electronic commerce (such as analysis of interest trends of users' selections and orderings, analysis of correlations between advertisements and their effects), remote instruction, digital museums, new service analysis [96], intelligent management of web videos (useful video search and harmful video tracing), and video surveillance. It is the broad range of applications that motivates the interest of researchers worldwide. The following two examples of research activity are particularly noteworthy. 1) Since 2001, the National Institute of Standards and Technology has been sponsoring the Annual Text Retrieval Conference (TREC) Video Retrieval Evaluation (TRECVID) to promote progress in video analysis and retrieval. Since 2003, TRECVID has been independent of TREC. TRECVID provides a large scale test collection of videos, and dozens of participants apply their content-based video retrieval algorithms to the collection [260], [263], [266]. 2) The goal of video standards is to ensure

compatibility between description interfaces for video contents in order to facilitate the development of fast and accurate video retrieval algorithms. The main standard

for videos are the moving picture experts group (MPEG) and the TV Anytime Standard [254]. There exist many investigations that adopt the MPEG7 to extract features to classify video contents or to describe video objects in the compressed domain [78].

A video may have an auditory channel as well as a visual channel. The available information from videos includes the following [66], [67]: 1) video metadata, which are tagged texts embedded in videos, usually including title, summary, date, actors, producer, broadcast duration, file size, video format, copy-right, etc.; 2) audio information from the auditory channel; 3) transcripts: Speech transcripts can be obtained by speech recognition and caption texts can be read using optical character recognition techniques; 4) visual information contained in the images themselves from the visual channel. If the video is included in a web page, there are usually web page texts associated with the video. In this paper, we focus on the visual contents of videos and give a survey on visual content-based video indexing and retrieval.

The importance and popularity of video indexing and retrieval have led to several survey papers, which are listed in Table I, together with the publication years and topics. In general, each paper covers only a subset of the topics in video indexing and retrieval. For example, Smeaton et al. [263] give a good review of video shot boundary detection during seven years of the TRECVID activity. Snoek and Worring [262] present a detailed review of concept-based video retrieval. They emphasize semantic concept detection, video search using semantic

concepts, and the evaluation of algorithms using the TRECVID databases. Ren et al. [278] review the state of the art of spatiotemporal semantic information-based video retrieval. Schoeffmann et al. [261] give a good review of interfaces and applications of video browsing systems.

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TABLE I
SURVEYS ON VIDEO INDEXING AND RETRIEVAL

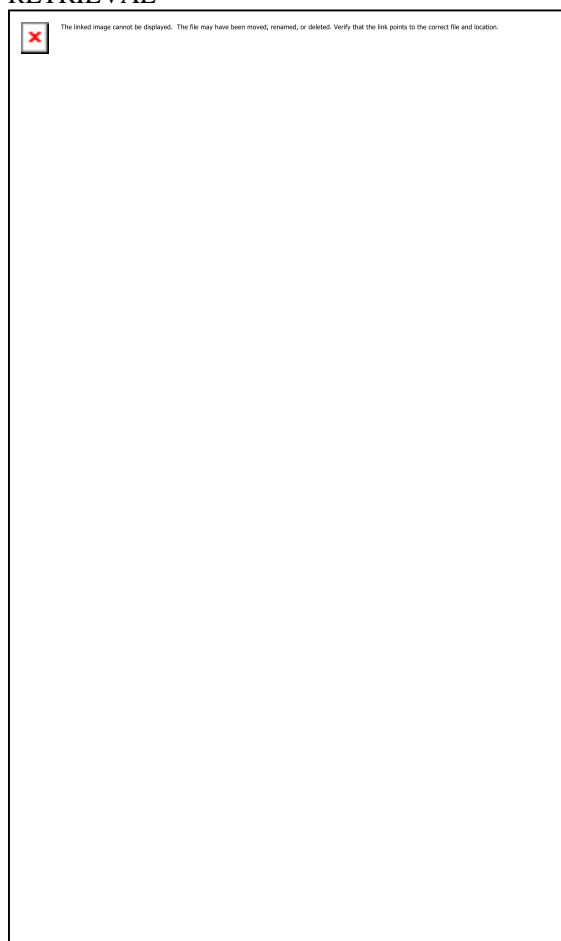


Fig.1. Generic framework for visual content-based video indexing and retrieval.

Unlike previous reviews, we give a more general overview on the overall process of a video indexing and retrieval framework which is outlined in Fig. 1. The framework includes the following: 1) structure analysis: to detect hot boundaries, extract key frames, and segment scenes; 2) feature extraction from segmented video units (shot or scenes): These features include static features in key frames, object features, motion features, etc.; 3) video data mining using the extracted features; 4) video annotation: using extracted features and mined knowledge to build a semantic video index. This semantic index together with the high-dimensional index of video feature vector

constitutes the total index for video sequences that are stored in the database;

5) query: the video database is searched for the desired videos using the index and the video similarity measures; 6) video browsing and feedback: The videos found in response to a query are returned to the user to browse in the form of a video summary, and subsequent search results are optimized through relevance feedback. In this paper, we review recent developments and analyze future open directions in visual content-based video indexing and retrieval. The main contributions of this survey are as follows.

1) Video indexing and retrieval components are discussed in a clearly organized hierarchical manner, and interlinks between these components are shown.

2) To examine the state of the art, each task involved in visual content-based video indexing and retrieval is divided into subprocesses and various categories of approaches to the subprocesses are discussed. The merits and limitations of the different approaches are summarized. For the tasks for which there exist surveys, we focus on reviewing recent papers as a supplement to the previous surveys. For the tasks that have not yet been specially surveyed, detailed reviews are given.

3) We discuss in detail future directions in visual content-based video indexing and retrieval.

The aforesaid contributions clearly distinguish our survey from the existing surveys on video indexing and retrieval. To our knowledge, our survey is the broadest.

The remainder of this paper is organized as follows: Section II briefly reviews the work related to video structure analysis. Section III addresses feature extraction. Section IV discusses video data mining, classification, and annotation. Section V describes the approaches for video query and retrieval. Section VI presents video summarization for browsing. Section VII analyzes possible directions for future research. Section VIII summarizes this paper.

II. VIDEO STRUCTURE ANALYSIS

Generally, videos are structured according to a descending hierarchy of video clips, scenes, shots, and frames. Video structure analysis aims at segmenting a video into a number of structural elements that have semantic contents, including shot boundary detection, key frame extraction, and scene segmentation.

A. Shot Boundary Detection

A shot is a consecutive sequence of frames captured by a camera action that takes place

between start and stop operations, which mark the shot boundaries [10]. There are strong content correlations between frames in a shot. Therefore, shots are considered to be the fundamental units to organize the contents of video sequences and the primitives for higher level semantic annotation and retrieval tasks. Generally, shot boundaries are classified as cut in which the transition between successive shots is abrupt and gradual transitions which include dissolve, fade in, fade out, wipe, etc., stretching over a number of frames. Cut detection is easier than gradual transition detection.

The research on shot boundary detection has a long history, and there exist specific surveys on video shot boundary detection [16], [263]. For completeness, we only briefly introduce the basic categories of methods for shot boundary detection and their merits and limitations, and review some recent papers as a supplement to [16] and [263].

Methods for shot boundary detection usually first extract visual features from each frame, then measure similarities between frames using the extracted features, and, finally, detect shot boundaries between frames that are dissimilar. In the following, we discuss them in three steps in shot boundary detection: feature extraction, similarity measurement [113], and detection. The features used for shot boundary detection include color histogram [87] or block color histogram, edge change ratio, motion vectors [85], [163], together with more novel features such as scale-invariant feature transform [83], corner points [82], information saliency map [77], etc. Color histograms are robust to small camera motion, but they are not able to differentiate the shots within the same scene, and they are sensitive to large camera motions. Edge features are more invariant to illumination changes and motion than color histograms, and motion features can effectively handle the influence of object and camera motion. However, edge features and motion features as well as more complicated features cannot in general outperform the simple color histograms [16].

To measure similarity between frames using the extracted features is the second step required for shot boundary de-

tection. Current similarity metrics for extracted feature vectors include the L norm cosine dissimilarity, the Euclidean distance, the histogram intersection, and the chi-squared similarity [11], [12],

[191], as well as some novel similarity measures such as the earth mover's distance [87] and mutual information [68], [72], [207]. These similarity measures include pairwise similarity measures that measure the similarities between consecutive frames and window similarity measures that measure similarities between frames within a window [191]. Window-based similarity measures incorporate contextual information to reduce the influence of local noises or disturbances, but they need more

computation than the pairwise similarity measures. Using the measured similarities between frames, shot boundaries can be detected. Current shot boundary detection approaches can be classified into threshold-based and statistical learning-based.

1) Threshold-Based Approach: The threshold-based approach detects shot boundaries by comparing the measured pairwise similarities between frames with a predefined threshold [47], [180]: When a similarity is less than the threshold, a boundary is detected. The threshold can be global, adaptive, or

global and adaptive combined. 1) The global threshold-based algorithm uses the same threshold, which is generally set empirically, over the whole video, as in [180]. The major limitation of the global threshold-based algorithm is that local content variations are not effectively incorporated into the estimation of the global threshold, therefore influencing the boundary detection accuracy. 2) The adaptive threshold-based algorithms [77], [87], [207] compute the threshold locally within a sliding window. Detection performance is often improved when an adaptive threshold is used instead of a global threshold [65]. However, estimation of the adaptive threshold is more difficult than estimation of the global threshold and users are required to be more familiar with characteristics of videos in order to choose parameters such as the size of the sliding window. 3) Global and adaptive combined algorithms adjust local thresholds, taking into account the values of the global thresholds. Quenot et al. [264] define the thresholds for cut transition detection, dissolve

transition detection, and flash detection as the functions of the global threshold that are obtained from a trade-off between recall and precision. Although this algorithm only needs to tune the global thresholds, the values of the functions are changed locally. The limitation of this algorithm is that the functional relations between the global thresholds and the locally adaptive thresholds are not easy to determine.

2) Statistical Learning-Based Approach: The statistical learning-based approach regards shot boundary detection as a classification task in which frames are classified as shot change or no shot change depending on the features that they contain.

Supervised learning and unsupervised learning are both used.

a) Supervised learning-based classifiers: The most commonly used supervised classifiers for shot boundary detection are the support vector machine (SVM) and AdaBoost.

1) SVM [11], [21]: Chavez et al. [84] use the SVM as a weak classifier to separate cuts from noncuts. A kernel function is used to map the features into a high-dimensional space in order to overcome the influence of changes

n illumination and fast movement of objects. Zhao et al. [61] exploit two SVM classifiers, in a sliding window, to detect

cuts and gradual transitions, respectively. Ling et al. [58] first extract several features from each frame, and then use the SVM to classify the frames using these features into three categories: cut, gradual transition, and others. Yuan

et al. [16] and Liu et al. [72] compare the threshold-based method with an SVM-based classifier. First, the candidate

boundaries are selected using the threshold-based method, and then the SVM classifier is used to verify the boundaries. The SVM-based algorithms are widely used for shot boundary detection [265] because of their following merits.

a) They can fully utilize the training information and maintain good generalization.

b) They can deal efficiently with a large number of features by the use of kernel functions.

c) Many good SVM codes are readily available.

2) Adaboost: Herout et al. [63] make cut detection a pattern recognition task to which the Adaboost algorithm is applied. Zhao and Cai [85] apply the Adaboost algorithm to shot boundary detection in the compressed domain. The color and motion features are roughly classified first using a fuzzy classifier, and then each frame is classified as a cut, gradual, or no change frame using the Adaboost classifier. The main merit of the Adaboost boundary classifiers is that a large number of features can be handled: These classifiers select a part of features for boundary classification.

3) Others: Other supervised learning algorithms have been employed for shot boundary detection. For instance, Cooper et al. [191] use the binary k nearest-neighbor (kNN) classifier, where the similarities between frames within the particular temporal interval are used as its input. Boreczky and Wilcox [121] apply hidden Markov (HMM) models with separate states to model shot cuts, fades, dissolves, pans, and zooms.

The merits of the aforementioned supervised-learning approaches are that there is no need to set the thresholds used in the threshold-based approaches, and different types of features can be combined to improve the detection accuracy. The limitation is their heavy reliance on a well-chosen training set containing both positive and negative examples.

b) Unsupervised learning based algorithms: The unsupervised learning based shot boundary detection algorithms are classified into framesimilarity-based and frame-based. The framesimilarity-based algorithms cluster the measurements of similarity between pairs of frames into two clusters: the

clus-ter

with low values of the similarities correspond to shot boundaries and the cluster with high values of the similarities correspond to non-boundaries. Clustering algorithms such as Kmeans and fuzzy Kmeans [64] have been used. The frame-based algorithms treat each shot as a cluster of frames that have similar visual content. Chang et al. [83] use clustering ensemble to group different frames into their corresponding shots. Lu et al. [12] use Kmeans clustering, and Damnjanovic et al. [57] use spectral clustering to cluster frames to detect the different shots. The merit of clustering-based approaches is that training dataset is not needed. Their limitations are that temporal sequence progression information is not preserved, and they are inefficient in recognizing the different types of gradual transition.

Shot boundary detection approaches can be classified into un-

compressed domain-

based and compressed domain-based. To avoid time consuming video decompression, the features available in the compressed domains such as discrete cosine transform coefficients, DC image and MB types, and motion vectors can be directly employed for shot boundary detection [40], [60], [85]. However, the compressed domain based approach is highly dependent on the compression standards, and it is less accurate than the uncompressed domain-based approach.

Recently, the detection of gradual transitions has received more attention. Ngo [41] detects dissolves based on multiresolution analysis. Yoo et al. [131] detect gradual transitions according to the variance distribution curve of edge information in frame sequences.

B. Key Frame Extraction

There are great redundancies among the frames in the shot; therefore, certain frames that best reflect the shot contents

are selected as key frames [15], [39], [170], [193] to succinctly represent the shot. The extracted key frames should contain as much salient content of the shot as possible and avoid as much redundancy as possible. The features used for key frame extraction include colors (particularly the color histogram), edges, shapes, optical flow, MPEG7 motion descriptors such as temporal motion intensity and spatial distribution of motion activity [206], MPEG discrete cosine coefficient and motion vectors [202], camera activity, and features derived from image variations caused by camera motion [161], [208]. Referring to [39], current approaches to extract key frames are

classified into six categories: sequential comparison-based, global comparison-based, reference frame-based, clustering-based, curve simplification-based, and object/event-based. 1) Sequential Comparison Between Frames: In these algorithms, frames subsequent to a previously extracted key frame are sequentially compared with the

key frame until a frame which is very different from the key frame is obtained. This frame is selected as the next key frame. For instance, Zhang et al. [209] used the color histogram difference between the current frame and the previous key frame to extract key frames. Zhang et al. [210] use the accumulated energy function computed from image-block displacements across two successive frames to measure the distance between frames to extract key frames. The merits of the sequential comparison-based algorithms include their simplicity, intuitiveness, low computational complexity, and adaptation of the number of key frames to the length of the shot. The limitations of these algorithms include the following. 1) The key frames represent local properties of the shot rather than the global properties. b) The irregular distribution and uncontrolled number of key frames make these algorithms unsuitable for applications that need an even distribution or a fixed number of key frames. c) Redundancy can occur when there are contents appearing repeatedly in the same shot.

2) Global Comparison Between Frames: The algorithms based on global differences between frames in a shot distribute key frames by minimizing a predefined objective function that depends on the application. In general, the objective function has one of the following four forms [39].

1) Event temporal variance: These algorithms select key frames in a shot such that the shot segments, each of which is represented by a key frame, have equal temporal variance. The objective function can be chosen as the sum of differences between event temporal variances of all these segments. The temporal variance in a segment can be approximated by the cumulative change of contents across consecutive frames in the segment [208] or by the difference between the first and last frames in the segment. For instance, Divakaran et al. [211] obtain key frames by dividing the shot into segments with the equal cumulative motion activity using the MPEG-7 motion activity descriptor, and then, the frame located at the halfway point of each segment is selected as a key frame.

2) Maximum coverage: These algorithms extract key frames by maximizing their representation coverage, which is the number of frames that the key frames can represent [39]. If the number of key frames is not fixed, then these algorithms minimize the number of key frames subject to a predefined fidelity criterion; alternatively, if the number of key frames is fixed, the algorithms maximize the number of frames that the key frames can represent [212], [213]. For instance, Chan et al. [214] specify the coverage of a key frame as the number of the frames that are visually

similar to the key frame. A greedy algorithm is used iteratively to find key frames.

3) Minimum correlation: These algorithms extract key frames to minimize the sum of correlations between key frames (especially successive key frames), making key frames as uncorrelated with each other as possible. For instance, Porter et al. [215] represent frames in a shot and their correlations using a directed weighted graph. The shortest path in the graph is found and the vertices in the shortest path which corresponds to minimum correlation between frames designate the key frames.

4) Minimum reconstruction error: These algorithms extract key frames to minimize the sum of the differences between each frame and its corresponding predicted frame reconstructed from the set of key frames using interpolation. These algorithms are useful for certain applications, such as an animation. Lee and Kim [216] use an iterative procedure to select a predetermined number of key frames, in order to reduce the shot reconstruction error as much as possible.

Li et al. [217] propose a key frame selection algorithm based on the extent to which key frames record the motion during the shot. In the algorithm, an inertia-based frame interpolation algorithm is used to interpolate frames.

The merit of the aforesaid global comparison-based algorithms include the following. 1) The key frames reflect the global characteristics of the shot. 2) The number of key frames is controllable. 3) The set of key frames is more concise and less redundant than that produced by these sequential comparison-based algorithms. The limitation of the global comparison-based algorithms is that they are more computationally expensive than the sequential comparison-based algorithms.

3) Reference Frame: These algorithms generate a reference frame and then extract key frames by comparing the frames in the shot with the reference frame. For instance, Ferman and Tekalp [204] construct an alpha-trimmed average histogram describing the color distribution of the frames in a shot. Then, the distance between the histogram of each frame in the shot and the alpha-trimmed average histogram is calculated. Key frames are located using the distribution of the distance curve. Sun et al. [205] construct a maximum occurrence frame for a shot. Then, a weighted distance is calculated between each frame in the shot and the

constructed frame. Key frames are extracted at the peaks of the distance curve. The merit of the reference frame-based algorithms is that they are easy to understand and implement. The limitation of these algorithms is that they depend on the reference frame: If the reference frame does not adequately represent the shot, some salient contents in the shot may be missing from the key frames.

4) Clustering: These algorithms cluster frames and then choose frames closest to the cluster centers as the key frames.

Girgensohn and Boreczky [199] select key frames using the

complete link method of hierarchical agglomerative clustering in

the color feature space. Yu et al. [200] extract key frames using

the fuzzy K-

means clustering in the color feature subspace.

Gibson et al. [201] use Gaussian mixture models (GMM) in the

eigenspace of the image, in which the number of GMM com-

ponents is the required number of clusters. The merit of the

clustering based algorithms are that they can use generic clustering algorithms, and the global characteristics of a video can be reflected in the extracted key frames. The limitation of these algorithms are as follows: First, they are dependent on the clustering results, but successful acquisition of semantic meaningful clusters is very difficult, especially for large data, and second, the sequential nature of the video cannot be naturally utilized: Usually, clumsy tricks are used to ensure that adjacent frames are likely to be assigned to the same cluster.

5) Curve Simplification: These algorithms represent each frame in a shot as a point in the feature space. The points are linked in the sequential order to form a trajectory curve and then searched to find a set of points which best represent the shape of the curve. Calic and Izquierdo [218] generate the frame difference metrics by analyzing statistics of the macroblock features extracted from the MPEG compressed stream. The key frame extraction method is implemented using difference metrics curve simplification by the discrete contour evolution algorithm. The merit of the curve simplification-based algorithms is that the sequential information is kept during the key frame extraction. Their limitation is that optimization of the best representation of the curve has a high computational complexity.

6) Objects/Events: These algorithms [192] jointly consider key frame extraction and object/event detection in order to ensure that the extracted key frames contain information about objects or events. Calic and Thomas [19

6] use the positions of regions obtained using frame segmentation to extract key frames where objects merge. Kim and Hwang [197] use shape features to extract key frames that can represent changes of human gestures. Liu and Fan [194] select initial key frames based on the color histogram and use these selected key frames to estimate a GMM for object segmentation. These segmentation results and the trained GMM are further used to refine the initial key frames. Song and Fan [195] propose a joint key frame extraction and object segmentation method by constructing a unified feature space for both processes, where key frame extraction is formulated as a feature selection process for object segmentation in the context of GMM based video modeling. Liu et al. [203] propose a triangle model of perceived motion energy for motion patterns in videos. The frames at the turning points of the motion acceleration and motion deceleration are selected as key frames. Han and Kwon [220] extract key frames by the maximum curvature of camera motion at each temporal scale. The key frames provide temporal interest points for classification of video events. The merit of the object/event based algorithms is that the extracted key frames are semantically important, reflecting objects or the motion patterns of objects. The limitation of these algorithms is that object/event

detection strongly relies on heuristic rules specified according to the application. As a result, these algorithms are efficient only

when the experimental settings are carefully chosen.

Because of the subjectivity of the key frame definition, there is

no uniform evaluation method for key frame extraction.

In general, the error rate and the video compression ratio are used as measures to evaluate the result of key frame extraction. Key frames giving lower error rates and high compression rates are preferred. In general, a lower error rate is associated with a low compression rate. The error rate depends on the parameters in the key frame extraction algorithms. Examples of these parameters are the threshold in sequential comparison based, global comparison based, reference frame based, and clustering based algorithms, as well as the parameters of fit the curve in the curve simplification-based algorithms. Users choose the parameters according to the error rate that can be tolerated.

C. Scene Segmentation

Scene segmentation is also known as story unit segmentation.

In general, a scene is a group of contiguous shots that are co-

herent with a certain subject or theme. Scenes have higher level semantic than shots. Scenes are identified or segmented out by grouping successive shots with similar content into a meaningful semantic unit. The grouping

may be based on information from texts, images, or the audio track in the video.

According to shot representation, scene segmentation approaches can be classified into three categories: key frame-based, audio and visual information integration-based, and background-based.

1) Key Frame-Based Approach: This approach [145] represents each video shot by a set of key frames from which features are extracted. Temporally close shots with similar features are grouped into a scene. For instance, Hanjalic et al. [140] compute similarities between shots using block matching of the key frames. Similar shots are linked, and scenes are segmented by connecting the overlapping links. Ngo et al. [144] extract and analyze the motion trajectories encoded in the temporal slices of image volumes. A motion-based key frame selection strategy is, thus, used to compactly represent shot contents. Scene changes are detected by measuring the similarity of the key frames in the neighboring shots. The limitation of the key frame-based approach is that key frames cannot effectively represent the dynamic contents of shots, as shots within a scene are generally correlated by dynamic contents within the scene rather than by key frame-based similarities between shots.

2) Audio and Vision Integration-Based Approach: This approach selects a shot boundary where the visual and audio contents change simultaneously as a scene boundary. For instance, Sundaram and Chang [147] detect audio scenes and video scenes separately. A time-constrained nearest neighbor algorithm is used to determine the correspondences between these two sets of scenes. The limitation of the audio and visual integration-based approach is that it is difficult to determine the relation between audio segments and visual shots.

3) Background-Based Approach: This approach segments scenes under the assumption that shots belonging to the same scene often have similar backgrounds. For instance, Chen et al. [139] use a mosaic technique to reconstruct the background of each video frame. Then, the color and texture distributions of all the background images in a shot are estimated to determine the shot similarity and the rules of film making are used to guide the shot grouping process. The limitation of the background-based approach is the assumption that shots in the same scene have similar backgrounds: sometimes the backgrounds in shots in a scene are different.

According to the processing method, current scene segmentation approaches can be divided into four categories: merging-based, splitting-

based, statistical model-based, and shot boundary classification-based.

a) Merging-based approach: This approach gradually merges similar shots to form a scene in a bottom-up style. Rasheed and Shah [133] propose a two-pass scene segmentation algorithm. In the first pass, oversegmentation of scenes is carried out using backward shot coherence. In the second pass, the oversegmented scenes are identified using motion analysis and then merged. Zhao et al. [134] propose a best first model-merging algorithm for scene segmentation. The algorithm takes each shot as a hidden state and loops upon the boundaries between consecutive shots by a left-right HMM.

b) Splitting-based approach: This approach splits the whole video into separate coherent scenes using a top-down style. For instance, Rasheed and Shah [136] construct a shot similarity graph for a video and partition the graph using normalized cuts. The subgraphs represent individual scenes in the video. Tavanapong and Zhou [138] introduce a scene definition for narrative films and present a technique to cluster relevant shots into a scene using this definition.

c) Statistical model-based approach: This approach constructs statistical models of shot-to-segment scenes. Zhai and Shah [132] use the stochastic Monte Carlo sampling to generate scenes. The scene boundaries are updated by diffusing, merging, and splitting the scene boundaries estimated in the previous step. Tan and Lu [137] use the GMM to cluster video shots into scenes according to the features of individual shots. Each scene is modeled with a Gaussian density. Gu et al. [149] define a unified energy minimization framework in which the global content constraint between individual shots and the local temporal constraint between adjacent shots are both represented. A boundary voting procedure decides the optimal scene boundaries.

d) Shot boundary classification-based approach: In this approach, features of shot boundaries are reextracted and then used to classify shot boundaries into scene boundaries and non-scene boundaries. Goela et al. [148] present a genre-independent method to detect scene boundaries in broadcast videos. In their method, scene segmentation is based on a classification with the two classes of—scene change and—non scene change. An SVM is used to classify the shot boundaries. Hand-labeled video scene bounda-

ries from a variety of broadcast genres are used to generate positive and negative training samples for the SVM. The common point in the merging-based, splitting-based, and statistical model-based approaches is that the similarities between different shots are used to combine similar shots into scenes. This is simple and intuitive. However, in these approaches, shots are usually represented by a set of selected key frames, which often fail to represent the dynamic contents of the shots. As a result, two shots are regarded as similar, if their key frames are in the same environment rather than if they are visually similar. The shot boundary classification-based approach takes advantage of the local information about shot boundaries. This ensures that algorithms with low computational complexities are easy to obtain. However, lack of global information about shots inevitably reduces the accuracy of scene segmentation.

It is noted that most current approaches for scene segmentation exploit the characteristics of specific video domains such as movies, TVs, and news broadcasts [150], [152], [153], for example, using the production rules by which movies or TV shows are composed. The accuracy of scene segmentation is improved, but it is necessary to construct a priori model for each application.

III. FEATURE EXTRACTION

To extract features according to video structural analysis results is the base of video indexing and retrieval. We focus on the visual features suitable for video indexing and retrieval. These mainly include features of key frames, objects, and motions. Auditory features and text features are not covered.

A. Static Features of Key Frames

The key frames of a video reflect the characteristic of the video to some extent. Traditional image retrieval techniques can be applied to key frames to achieve video retrieval. The static key frame features are useful for video indexing and retrieval and are mainly classified as color-based, texture-based, and shape-based.

1) Color Based Features: Color based features include color histograms, color moments, color correlograms, a mixture of Gaussian models, etc. The extraction of color based features depends on color spaces such as RGB, HSV, YCbCr and normalized RGB, YUV, and HVC. The choice of color space depends on the applications. Color features can be extracted from

the entire image or from image blocks into which the entire image is partitioned. Color based features are the most effective image features for video indexing and retrieval. In particular, color histogram and color moments are simple but efficient descriptors. Amir et al. [222] compute color histogram and color moments for video retrieval and concept detection. Yan and Hauptmann [229] first split the image into 5×5 blocks to capture local color information. Then in each block, color histogram and color moments are extracted for video retrieval. Adcock et al. [226] use color correlogram to implement a video search engine. The merits of color based features are that they are easy to extract, and their extraction has low computational complexity. The limitation of color based features is that they do not directly describe texture, shape, etc., and are, thus, ineffective for the applications in which texture or shape is important.

2) Texture-Based Features: Texture-based features are object surface owned intrinsic visual features that are independent of color or intensity and reflect homogeneous phenomena in images. They contain crucial information about the organization of object surfaces, as well as their correlations with the surrounding environment. Texture features in common use include Tamura features, simultaneous autoregressive models, orientation features, wavelet transform based texture features, co-occurrence matrices, etc. Amir et al. [222] use co-occurrence texture and Tamura features including coarseness, contrast and directionality for the TREC Vid-2003 video retrieval task. Hauptmann et al. [223] use Gabor wavelet filter to capture texture information for a video search engine. They design 12 oriented energy filters. The mean and variance of the filtered

outputs are concatenated into a texture feature vector. Hauptmann et al. [228] divide the image into 5×5 blocks and compute texture features using Gabor-wavelet filters in each block. The merit of texture-based features is that they can be effectively applied to applications in which texture information is salient in videos. However, these features are unavailable in non-texture video images.

3) Shape-Based Features: Shape-based features that describe object shapes in the image can be extracted from object contours or regions. A common approach is to detect edges in images and then describe the distribution of the edges using a histogram. Hauptmann et al. [223] use the edge histogram descriptor (EHD) to capture the spatial distribution of edges for the video search task in TREC Vid-2005. The EHD is computed by counting the number of pixels that contribute to the edge according to their quantized directions. To

capture local shape features, Foley et al. [224] and Cooke et al. [225] first divide the image into 4×4 blocks and then extract a edge histogram for each block. Shape-based features are effective for applications in which shape information is salient in videos. However, they are much more difficult to extract than color- or texture-based features.

B. Object Features

Object features include the dominant color, texture, size, etc., of the image regions corresponding to the objects. These features can be used to retrieve videos likely to contain similar objects [17]. Faces are useful objects in many video retrieval systems. For example, Sivic et al. [18] construct a person retrieval system that is able to retrieve a ranked list of shots containing a particular person, given a query face in a shot. Le et al. [19] propose a method to retrieve faces in broadcast news videos by integrating temporal information into facial intensity information. Texts in a video are extracted as one type of object to help understand video contents. Li and Doermann [20] implement text-based video indexing and retrieval by expanding the semantics of a query and using the Glimpse matching method to perform approximate matching instead of exact matching. The limitation of object-based features is that identification of objects in videos is difficult and time-consuming. Current algorithms focus on identifying specific types of objects, such as faces, rather than various objects in various scenes.

C. Motion Features

Motion is the essential characteristic distinguishing dynamic videos from still images. Motion information represents the visual content with temporal variation. Motion features are closer to semantic concepts than static keyframe features and object features. Video motion includes background motion caused by camera motion and foreground motion caused by moving objects. Thus, motion-based features for video retrieval can be divided into two categories: camera-based and object-based. For camera-based features, different camera motions, such as zooming in or out, panning left or right, and tilting up or down, are estimated and used for video indexing. Video retrieval using only camera-based features has the limitation that they cannot describe motions of key objects.

Object-based motion features have attracted much more interest in recent work. Object-based motion features can be further classified into statistics-based, trajectory-based, and objects' spatial relationships-based.

1) Statistics-Based: Statistical features of the motions of points in frames in a video are extracted to model the distribution of global or local motions in the video. For instance, Fablet et al. [233] use causal Gibbs models to represent the spatiotemporal distribution of appropriate local motion-related measurements computed after compensating for the estimated dominant image motions in the original sequence. Then, a general statistical framework is developed for video indexing and retrieval. Ma and Zhang [234] transform the motion vector field to a number of directional slices according to the energy of the motion. These slices yield a set of moments that form a multidimensional vector called motion texture. The motion texture is used for motion-based shot retrieval. The merit of statistics-based features is that their extraction has low computational complexity. The limitation of these features is they cannot represent object actions accurately and cannot characterize the relations between objects.

2) Trajectory-Based: Trajectory-based features [22] are extracted by modeling the motion trajectories of objects in videos.

Chan et al. [236] propose an online video retrieval system supporting automatic object-based indexing and spatiotemporal queries. The system includes algorithms for automated video object segmentation and tracking. Bashir et al. [237] present a motion trajectory-based compact indexing and efficient retrieval mechanism for video sequences. Trajectories are represented by temporal orderings of subtrajectories. The subtrajectories are then represented by their principal component analysis coefficients.

Chen and Chang [238] use wavelet decomposition to segment each trajectory and produce an index based on velocity features.

Jun et al. [25] base their motion model on polynomial curve fitting. The motion model is used as an indexing key to access individual objects. Su et al. [26] construct motion flows from motion vectors embedded in MPEG bitstream to generate

continuous motion information in the form of a trajectory. Given a trajectory, the system retrieves a set of trajectories that are similar to it.

Hsieh et al. [27] divide trajectories into several small

segments, and each segment is described by a semantic symbol.

A distance measure combining an edit distance and a visual

distance is exploited to match trajectories for video retrieval. The merit of trajectory-based features is that they can describe object actions. The limitation of these features is that their extraction

depends on correct object segmentation and tracking and

automatic recording of trajectories, all of which are still very challenging tasks.

3) Objects' Relationship-

Based: These features describe

spatial relationships between objects. Bimbo et al. [235] de-

scribe relationships between objects using a symbolic repre-

sentation scheme which is applied to video retrieval. Yajima et

al. [24] query the movements of multiple moving objects and

specify the spatiotemporal relationships between objects by ex-

pressing each object's trace on a timeline. The merit of objects'

relationship-

based features is that they can intuitively represent relationships between multiple objects in the temporal domain. The limitation of these features is that it is difficult to label each object and its position.

IV. VIDEO DATA MINING, CLASSIFICATION, AND ANNOTATION

Video data mining, classification, and annotation rely heav-

ily on video structure analysis and the extracted video features.

There are no boundaries between video data mining, video clas-

sification, and video annotation. In particular, the concept of

video classification and annotation are very similar. In this sec-

tion, we review the basic concepts and approaches for video data

mining, classification, and annotation. The annotation is the basis

for the detection of video's semantic concepts and the construction of semantic indices for videos.

A. Video Data Mining

The task of video data mining is, using the extracted features, to find structural patterns of video contents, behavior patterns of moving objects, content characteristics of a scene, event pat-terns [230], [232] and their

associations, and other video se-mantic knowledge [45], in order to achieve video intelligent applications, such as video retrieval [118]. The choice of a strategy for video data mining depends on the application. Current strategies include the following.

1) Object Mining: Object mining is the grouping of different

instances of the same object that appears in different parts of a

video. It is very hard because the appearance of an object can

change a great deal from one instance to another. Sivic and

Zisserman [86] use a spatial neighborhood technique to cluster the features in the spatial domain of the frames. These clusters are used to mine frequently appearing objects in key frames.

Anjulan and Canagarajah [81] extract stable tracks from shots. These stable tracks are combined into meaningful object clusters, which are used to mine similar objects.

Quack et al. [28] present a method for mining frequent occurrences of objects and scenes from videos. Object candidates are detected by finding recurring spatial arrangements of affine covariant regions.

2) Special Pattern Detection: Special pattern detection applies to actions or events for which there are a priori models, such as human actions, sporting events [127], traffic events, or crime patterns. Laptev et al. [124] propose an appearance-based method that recognizes eight human actions in movies, e.g., answer phone, get out of a car, handshake, hug person, kiss. They extract local space-time features in space-time pyramids, build a spatial-temporal bag-of-features, and employ multichannel nonlinear SVMs for recognition. Ke et al. [125] propose a template-based method that recognizes human actions, such as picking up a dropped object or waving in a crowd. They oversegment the video to obtain spatial-temporal patches, and combine shape and optical flow cues to match testing patches and templates. Liu et al. [126] detect events in a football match, including penalty kicks, free kicks near the penalty box, and corner kicks in football games. Li and Porikli [128] detect six traffic patterns using a Gaussian mixture HMM framework, and Xie et al. [129] extract traffic jam events by analyzing the road background features. Nath [130] detects crime patterns using a clustering algorithm.

3) Pattern Discovery: Pattern discovery is the automatic discovery of unknown patterns in videos using unsupervised or

semisupervised learning. The discovery of unknown patterns is useful to explore new data in a video set or to initialize models for further applications. Unknown pat-

terns are discovered by analyzing the video content using unsupervised learning. The discovery of unknown patterns is useful to explore new data in a video set or to initialize models for further applications. Unknown pat-

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terns are discovered by analyzing the video content using unsupervised learning. The discovery of unknown patterns is useful to explore new data in a video set or to initialize models for further applications. Unknown pat-

ns are typically found by clustering various feature vectors in the videos. The discovered patterns have the following applications: 1) detecting unusual events [230] that are often defined by their dissimilarity to discovered patterns; 2) associating clusters or patterns with words for video retrieval, etc; 3) building supervised classifiers based on the mined clusters for video classification or annotation, etc. Bur [105] describes an algorithm for mining motion trajectories to detect trigger events, determine typical or anomalous patterns of activities, classify activities into named categories, cluster activities, determine interactions between entities, etc. Hamid et al. [2] use n-grams and suffix trees to mine motion patterns by analyzing event subsequences over multiple temporal scales. The mined motion patterns are used to detect unusual events. Turaga et al. [1] use a generative model to capture and represent diverse classes of activities, and build a fine and view-invariant of the activity into the distance metric for clustering. The clusters correspond to semantically meaningful activities. Cutler and Davis [14] compute an object's self-similarity as it evolves in time, and apply time-frequency analysis to detect and characterize the periodic motion. The periodicity is analyzed using the 2-D lattice structures inherent in similarity matrices.

4) Video Association Mining: Video association mining is mainly used to discover inherent relations between different events or the most frequent association patterns for different objects, such as the simultaneous occurrence of two objects, frequency of shot switches, and association between video types [118]. Video association mining also includes the deduction of inter-associations between semantic concepts in the same shot from existing annotations or the inference of a semantic concept for the current shot from detection results of neighboring shots, etc. Pan and Faloutsos [102] propose an algorithm to find correlations between different events in news programs, such as those between—earthquake and—volcano or—tourism and—wine. Zhu et al. [100] propose explicit definitions and evaluation measures for video associations by integrating distinct features of the video data. Their algorithm introduces multilevel sequential association mining to explore associations

between audio and visual cues, classifies the associations by assigning each of them a class label, and uses their appearances in the video to construct video indices. Yan et al. [13] describe various multi-concept relational learning algorithms based on a unified probabilistic graphical model representation and use a graphical model to mine the relationship between video concepts. Liu et al. [231] use association-mining techniques to discover inter-concept associations in the detected concepts, and mine inter-shot temporal dependence, in order to improve the accuracy of semantic concept detection.

5) Tendency Mining: Tendency mining is the detection and analysis of trends of certain events by tracking current events [118]. Xie et al. [103] propose a news video mining method, which involves two visualization graphs: the time-tendency graph and the time-spaced distribution graph. The time-tendency graph records the tendencies of events, while the time-space distribution graph records the spatial-temporal relations between various events. Oh and Banti [104] mine the tendency of a traffic jam by analyzing the spatial-temporal relations between objects in videos.

6) Preference Mining: For news videos, movies, etc., the user's preferences can be mined [118]. For instance, Kulese et al. [101] propose a personalized multimedia news portal to provide a personalized news service by mining the user's preferences.

B. Video Classification

The task of video classification [106], [245] is to find rules or knowledge from videos using extracted features or mined results and then assign the videos into predefined categories. Video classification is an important way of increasing the efficiency of video retrieval. The semantic gap between extracted formative information, such as shape, color, and texture, and an observer's interpretation of this information, makes content-based video classification very difficult.

Video content includes semantic content and editing effects. Referring to [23], semantic content classification can be performed on three levels: video genres, video events, and objects in the video, where genres have rougher and wider detection range; and events

and objects have thinner and limited detection range. In the following, we discuss edit effect classification, genre classification, event classification, and object classification, respectively.

1) Edit Effect Classification: Editing effects depend on the ways for editing videos, such as camera motion and the composition of scenes and shots. Editing effects themselves are not a part of video content, but they influence the understanding of video content; therefore, they may be used in video semantic classification. For instance, Ekin et al. [165] classify shots of soccer videos into long, in-field medium, close-up, and out-of-field views using cinematic features and further detect events such as play, break, and replay. Xu et al. [246] use the domain-specific feature of grass-area-ratio to classify frames of soccer videos into global, zoom-in, and close-up views and obtain play/break statuses of games from the sequences of labeled frames. Tan et al. [247] estimate camera motion using data from the MPEG stream, and further classify basketball shots into wide-angle and close-up views and detect events such as fast breaks, shots at the basket, etc.

2) Video Genre Classification: Video genre classification is the classification of videos into different genres such as —movie, —news, —sports, and —cartoon. Approaches to classify video genres can be classified into statistic-based, rule- or knowledge-based, and machine learning-based [23].

a)Statistic-basedapproach: This approach classifies videos by statistically modeling various video genres. Fisher et al. [89] classify videos as news, carriage, tennis, animated cartoon, and commercials. First, video syntactic properties such as color statistics, cuts, camera motion, and object motion are analyzed. Second, these properties are used to derive abstract film style attributes such as camera panning and zooming, speech, and music. Finally, these detected style attributes

are mapped into film genres. Based on characteristics of films, Rasheed et al. [123] only use four visual features, namely average shot length, color variance, motion content, and lighting key, to classify films into comedies, actions, dramas, or horror

films. The classification is achieved using mean shift clustering.

Some methods only utilized dynamic features to classify video genres. Roach et al. [122] propose a cartoon video classification method that uses motion features of foreground objects to distinguish between cartoons and non-cartoons. Roach et al. [108] classify videos based on the dynamic content of short video sequences, where foreground object motion and background camera motion are extracted from videos. The classified videos include sports, cartoons, and news.

b)Rule- or knowledge-based approach: This approach applies heuristic rules from domain knowledge to low-level features to classify videos. Chen and Wong [109] develop a knowledge-based video classification method, in which the relevant knowledge is coded in the form of generative rules with confidence to form a rule-base. The Clip language is used to compile a video content classification system using the rule-base. Zhou et al. [110] propose a supervised rule-based video classification system, in which higher semantics are derived from a joint use of low-level features along with classification rules that are derived through a supervised learning process. Snoek et al. [93] propose a video classification and indexing method, combining video creation knowledge to extract semantic concepts from videos by exploring different paths through three consecutive analysis steps: the multimodal video content analysis step, the video style analysis step, and the context analysis step. Zhou et al. [107] propose a rule-based video classification

system that applies video content analysis, feature extraction and clustering techniques to the semantic clustering of videos. Experiments on basketball videos are reported.

c)Machine learning-based approach: This approach uses labeled samples with low-level features to train a classifier or a set of classifiers for videos. Mittal and Cheong [112] use the Bayesian network to classify videos. The association between a continuous and nonparametric descriptor space and the class is

learned and the minimum Bayes error classifier is deduced. Qiet al.[97] propose a video classification framework using SVMs-based active learning. The results of clustering all the videos in the dataset are used as the input to the framework. The accuracy of the classifiers is improved gradually during the active-learning process. Fan et al.[98] use multiple levels of concepts of video content to achieve hierarchical semantic classification of videos to enable highly efficient access to video contents. Truong et al. [90] classify videos into the genres of cartoons, commercials, music, news, and sports. The features used include the average shot length, the percentage of each type of transition, etc. The C4.5 decision tree is used to build the classifier for genre labeling. Yuan et al.[240] present an automatic video genre classification method based on a hierarchical ontology of video genres. A series of SVM classifiers united in a binary-tree form assign each video to its genre. Wu et al.[154] propose an online video semantic classification framework, in which local and global sets of optimized classification models are online trained by sufficiently exploiting both local and global statistic characteristics of videos. Yuan et al. [155] learn concepts from a large-scale imbalanced dataset using support cluster machines. From the aforesaid video genre classification approaches, the following conclusions can be drawn [23]. 1) These approaches either use static features only, dynamic features only, or combine them both. 2) All the approaches preferably employ global statistical low-level features. This is because such features are robust to video diversity, making them appropriate for video genre classification. Many algorithms attempt to add semantic features on the basis of these low-level features. 3) Prior domain knowledge is widely used in video genre classification. To use knowledge or rules can improve the classification efficiency for special domains, but the corresponding algorithms cannot be generalized to videos from other domains.

3) Event Classification: An event can be defined as any human-visible occurrence that has significance to represent video contents. Each video can consist of a number of events, and each event can consist of a number of sub-events. To determine the classes of events in a video is an important component of content-based video classification [3], and it is connected with event detection in video data mining. There is a great deal of published work on event classification. Yu et al. [115] detect and track balls in broadcast soccer videos and extract ball trajectories, which are used to detect events such as handball and ball possession by a team. Chan et al. [111] detect and classify highlights in baseball game videos using HMM models that are learned from special shots identified as highlights. Duan et al. [116] propose a visual feature representation model for sports videos. This model is combined with supervised learning to perform top-down semantic shot classification. These semantic shot classes are further used as a mid-level representation for high-level semantic analysis. Xu et al. [94] present an HMM-based framework for video semantic analysis. Semantics in different granularities are mapped to a hierarchical model in which a complex analysis problem is decomposed into subproblems. The framework is applied to basketball event detection. Osadchy and Kerem [119] offer a natural extension of the—antifacel method to event detection, in both the gray-level and feature domains. Xi et al. [151] employ HMM and dynamic programming to detect the sports video concepts of—play, —no play, etc. Pan et al. [114] extract visual features and then use an HMM to detect slow-motion replays in sports videos. From the aforesaid event classification algorithms, the following conclusions can be drawn [23]. 1) In contrast with genre classification, event classification needs more complex feature extraction. 2) Complicated motion measures are often attached to event classifiers. Some event classification methods employ only dynamic features, involving the accurate tracking of m

ov-ing objects or rough region-based motion measures, and then classify the object motions in order to recognize motion events. 4) Object Classification: Video object classification which is connected with object detection in video data mining is conceptually the lowest grade of video classification. The most common detected and classified object is the face [120]. Object detection often requires the extraction of structural features of objects and classification of these features. Prior knowledge

such as an object appearance model is often incorporated into the process of object feature extraction and classification. Hong et al. [92] propose an object-based algorithm to classify video shots. The objects in shots are represented using features of color, texture, and trajectory. A neural network is used to cluster correlatives shots, and each cluster is mapped to one of 12 categories. A shot is classified by finding the best matching cluster. Dimitrova et al. [91] propose a method to classify four types of TV programs. Faces and texts are detected and tracked, and the number of faces and texts is used to label each frame of a video segment. An HMM is trained for each type using the frame labels as the observation symbols. The limitation of object classification for video indexing is that it is not generic; video object classification only works in specific environments.

C. Video Annotation

Video annotation [4], [117], [241] is the allocation of video shots or video segments to different predefined semantic concepts, such as person, car, sky, people walking. Video annotation is similar to video classification, except for two differences [239]: 1) Video classification has a different category/concept ontology compared with video annotation, although some of the concepts could be applied to both; and 2) video classification applies to

complete videos, while video annotation applies to video shots or video segments. Video annotation and video classification share similar methodologies: First, low-level features are extracted, and then certain classifiers are trained and employed to map the features to the concept/category labels. Corresponding to the fact that a video may be annotated with multiple concepts, the approaches for video annotation can be classified as isolated concept-based annotation, context-based annotation, and integrated-based annotation [244].

1) Isolated Concept-Based Annotation: This annotation method trains a statistical detector for each of the concepts in a visual lexicon, and the isolated binary classifiers are used individually and independently to detect multiple semantic concepts—correlations between the concepts are not considered. Feng et al. [8] use the multiple-Bernoulli distribution to model image and video annotation. The multiple-Bernoulli model explicitly focuses on the presence or absence of words in the annotation, based on the assumption that each word in an annotation is independent of the other words. Naphade and Smith [69] investigate the efficiencies of a large variety of classifiers, including GMM, HMM, kNN, and AdaBoost, for each concept. Song et al. [9] introduce active learning together with semisupervised learning to perform semantic video annotation. In this method, a number of two-class classifiers are used to carry out the classification with multiple classes. Duan et al. [116] employ supervised learning algorithms based on the construction of effective midlevel representations to perform video semantic shot classification for sports videos. Shen et al. [73] propose a cross-training strategy to stack concept detectors into a single discriminative classifier and to handle the classification errors that occur when the classes overlap in the feature space. The limitation of isolated concept-based annotation is that the associations between the different concepts are not modeled. 2) Context-Based Annotation: To use contexts for different concepts [71] can improve concept detection performance. The task of context-based annotation is to refine the detection results of the individual binary classifiers or infer higher level concepts from detected lower level concepts using a context-based concept fusion strategy. For instance, Wu et al. [248] use an ontology-based learning method to detect video concepts. An ontology

hierarchy is used to improve the detection accuracy of the individual binary classifiers. Smith and Naphade [249] construct model vectors based on the detection scores of individual classifiers to mine the unknown or indirect correlations between specific concepts and then train an SVM to refine the individual detection results. Jian et al. [250] propose an active-learning method to annotate videos. In the method, users annotate a few concepts for a number of videos, and the manual annotations are then used to infer and improve detections of other concepts. Bertini et al. [251] propose an algorithm that uses pictorially enriched ontologies that are created by an unsupervised clustering method to perform automatic soccer video annotation. Occurrences of events or entities are automatically associated with higher level concepts, by checking their proximity to visual concepts that are hierarchically linked to higher level semantics. Fan et al. [32], [253] propose a hierarchical boosting scheme, which incorporates concept ontology and multitask learning, to train a hierarchical video classifier that exploits the strong correlations between video concepts. The limitation of context-based annotation is that the improvement of contextual correlation to individual detection is not always stable because the detection errors of the individual classifiers can propagate to the fusion step, and partitioning of the training samples into two parts for individual detections and conceptual fusion, respectively, causes that there are not sufficient samples for the conceptual fusion because of the usual complexity of the correlations between the concepts.

3) **Integration-Based Annotation:** This annotation method simultaneously models both the individual concepts and their correlations: The learning and optimization are done simultaneously. The entire set of samples is used simultaneously to model the individual

concepts and their correlations. Qi et al. [244] propose a correlative multilabel algorithm, which constructs a new feature vector that captures both the characteristics of concepts and the correlations between concepts. The limitation of the integration-based annotation is its high computational complexity.

The learning of a robust and effective detector for each concept requires a sufficiently large number of accurately labeled training samples, and the number required increases exponentially with the feature dimension. Recently, some approaches have been proposed to incorporate unlabeled data into the supervised learning process in order to reduce the labeling burden. Such approaches can be classified into semisupervised-based and active-learning-based.

a) **Semisupervised learning:** This approach uses unlabeled samples to augment the information in the available labeled examples. Yan and Naphade [74], [146] present semisupervised cross feature learning for cotraining-based video concept detection and investigate different labeling strategies in

cotraining involving unlabeled data and a small number of labeled videos. Yuan et al. [143] propose a feature selection-based manifold-ranking algorithm to learn concepts using a small number of samples. The algorithm consists of three major components: feature pool construction, prefiltering, and manifold ranking. Wan et al. [141] propose a video annotation algorithm, based on semisupervised learning by the kernel density estimation. Wan et al. [135], [279] propose an optimized multigraph-based semisupervised learning algorithm to deal with the insufficiency of training data in video annotation. Ewerth and Freisleben [167] propose a semisupervised learning method to adaptively learn the appearances of certain objects or events for a

particular video. A data boost and SVM are incorporated for feature selection and ensemble classification.

b) **Active learning:** Active learning is also an effective way to handle the lack of labeled samples. Song et al. [6] propose an active-learning algorithm for video annotation based on multiple complementary predictors and incremental model adaptation. Furthermore, Song et al. [7] propose a video annotation framework based on an active learning and semisupervised ensemble

method, which is specially designed for personal video databases.

V. QUERY AND RETRIEVAL

Once video indices are obtained, content-based video retrieval [5] can be performed. On receiving a query, a similarity measure method is used, based on the indices, to search for the candidate videos in accordance with the query. The retrieval results are optimized by relevance feedback, etc. In the following, we review query types, similarity matching, and relevance feedback.

A. Query Types

Nonsemantic-based video query types include query by example, query by sketch, and query by objects. Semantic-based video query types include query by keywords and query by natural language.

1) Query by Example: This query extracts low-level features from given example videos or images and similar videos are found by measuring feature similarity. The static features of key frames are suitable for query by example, as the key frames extracted from the example videos or exemplar images can be matched with the stored key frames.

2) Query by Sketch: This query allows users to draw sketches to represent the videos they are looking for. Features extracted from the sketches are matched to the features of the stored videos. Hu et al. [36] propose a method of query by sketch, where trajectories drawn by users are matched to trajectories extracted from videos.

3) Query by Objects: This query allows users to provide an image of object. Then, the system finds and returns all occurrences of the object in the video database [267]. In contrast with query by example and query by sketch, the search results of query by objects are the locations of the query object in the videos. 4) Query by Keywords: This query represents the user's query by a set of keywords. It is the simplest and most direct query type, and it captures the semantics of videos to some extent. Keywords can refer to video metadata, visual concepts, transcripts, etc. In this paper, we mainly consider visual concepts.

5) Query by Natural Language: This is the most natural and convenient way of making a query. Aytar et al. [255] use semantic word similarity to retrieve the most relevant videos and rank them, given a search query specified in the natural language (English). The most difficult part of a natural language interface is the

parsing of natural language and the acquisition of accurate semantics.

6) Combination-

Based Query: This query combines different

types of queries such as text-

based queries and video example-

based queries. The combination-based query is adaptable to

multimodal search. Kennedy et al. [259] develop a framework to

automatically discover useful query classes by clustering

queries in a training set according to the performance of various

unimodal search methods. Yan et al. [258] propose an adaptive

method to fuse different search tools to implement query-class-

dependent video retrieval, where the query-

class association

weights of the different search tools are automatically

determined. Yuan et al. [219] classify the query space in to person and non-person queries in their multimedia retrieval

system. Yan and Hauptmann [198] consider the classification of queries

and the determination of combination weights in a probabilistic

framework by treating query classes as latent variables.

The following query interfaces are among the most famous so far.

1) The Informedia interface [31], [70]: This interface supports filtering based on visual semantic concepts. The visual concept filters are applied after a keyword-based search is carried out.

2) The MediaMill query interface [30], [99]: This interface combines query-by-visual concept, query by example, and query by textual keyword.

B. Similarity Measure

Video similarity measures play an important role in content-based video retrieval. Methods to measure video similarities can be classified into feature matching, text matching, ontology-based matching, and combination-based matching. The choice of method depends on the query type.

1) Feature Matching: The most direct measure of similarity between two videos is the average distance between the features of the corresponding frames [34]. Query by example usually uses low-level feature matching to find relevant videos. However, video similarity can be considered in different levels of resolution or granularity [35].

According to different user demands, static features of key

frames [59], object features [81], and motion features [3

6]all can be used to measure video similarity. For example, Sivic et al.

[18] extract face features from an example shot containing the queried face and match the extracted features with the stored face features. Then, shots containing the queried face are retrieved. Lie and Hsiao [37] extract trajectory features of major objects in a given set of videos and match the extracted trajectory features with stored trajectory features to retrieve videos.

The merit of feature matching is that the video similarity can be conveniently measured in the feature space. Its limitation is that semantic similarity cannot be represented because of the gap between sets of feature vectors and the semantic categories familiar to people.

2) Text Matching: Matching the name of each concept with query terms is the simplest way of finding the videos that satisfy the query. Snoek et al. [242] normalize both the descriptions of concepts and the query text and then compute the similarity between the query text and the text descriptions of concepts by using a vector space model. Finally, the concepts with the highest similarity are selected. The merits of the text-matching approach are its intuitiveness and simplicity of implementation. The limitation of this approach is that all related concepts must be explicitly included in the query text in order to obtain satisfactory search results.

3) Ontology-Based Matching: This approach achieves similarity matching using the ontology between semantic concepts or semantic relations between keywords. Query descriptions are enriched from knowledge sources, such as ontology of concepts or keywords. Snoek et al. [242] perform the syntactic disambiguation of the words in the text query and then translate the nouns and noun chunks extracted from the text to ontological concepts by looking up each noun in Wordnet. As the concepts are also linked to Wordnet, the ontology is used to determine which concepts are mostly related to the original query text. Based on the fact that the semantic word similarity is a good approximation for visual co-occurrence. Aytar et al. [255] utilize semantic word similarity measures to measure the similarity between text annotated videos and users' queries. Videos are retrieved based on their relevance to a user-defined text query. The merit of the ontology-based matching approach is that extra concepts from knowledge sources are used to improve

retrieval results [221], [227]. The limitation of this approach is that irrelevant concepts are also likely to be brought in, perhaps leading to unexpected deterioration of search results.

4) Combination-

Based Matching: This approach—leverages semantic concepts by learning the combination strategies from a training collection, e.g., learning query-independent combination models [222] and query-class-dependent combination models [258] [229]. It is useful for combination-based queries that are adaptable to multimodal searches. The merit of the combination-based matching approach is that concept weights can be automatically determined and hidden semantic concepts can be handled to some extent. The limitation of this approach is that it is difficult to learn query combination models.

C. Relevance Feedback

In relevance feedback, the videos obtained in previous search queries are ranked either by the user or automatically. This ranking is used to refine further searches. The refinement methods include query point optimization, feature weight adjustment, and information embedding. Relevance feedback bridges the gap between semantic notions of search relevance and the low-level representation of video content. Relevance feedback also reflects user's preferences by taking into account user feedback on the previously searched results. Like relevance feedback for image retrieval, relevance feedback for video retrieval can be divided into three categories: explicit, implicit, and pseudo feedback.

1) Explicit Relevance Feedback: This feedback asks the user to actively select relevant videos from the previously retrieved videos. Thiel et al. [49] propose an interface for image and video retrieval. Users are required to choose positive samples and retrieval results are improved by modifying the query point toward the positive examples. Chen et al. [51] adjust the weight embedded in the similarity measure to reflect the user's feedback. The user can label sample videos as—highly relevant, |—relevant, |—no opinion, |—nonrelevant, |or—highly nonrelevant, | Sudha et al. [42] employ a simultaneous perturbation st

ochastic approximation-based algorithm to compute the optimal feature weights according to user's feedback. Aksoy and Cavus [55] describe a relevance feedback response technique that can adjust the weights of different features and different spatial locations in key frames according to the user's feedback. Browne and Smeaton [52] describe an ostensive relevance feedback that takes into account the changes in the user's requirements that occur while users search for information. A decay function is used to weigh the contribution of a previously viewed and relevant object to reflect the evolution of the user's interest. Savet al. [54], [56] present an interactive object-based video retrieval system that uses relevance feedback to refine an underlying model of the search object. The user can directly select the features important for the user and the image sections that the user wants to search for. The merit of explicit feedback is that it can obtain better results than implicit feedback or the pseudo feedback discussed later as it uses the user feedback directly. Its limitation is that it needs more user interaction, which requires more user patience and cooperation.

2) **Implicit Relevance Feedback:** This feedback refines retrieval results by utilizing click-through data obtained by the search engine as the user clicks on the videos in the presented ranking [43]. Ghosh et al. [53] present a method to personalize video retrieval results based on click-through data analysis. The parameters of a Bayesian network that establishes uncertainties between concepts and video features are learned using the implicit user feedback. Hopfgartner et al. [62] propose a simple model to adapt retrieval results based on simulated implicit relevance feedback. The merit of implicit feedback is that it does not require the conscious cooperation of the user, making it more acceptable, available, and practicable than explicit feedback. The limitation of implicit feedback is that the information gathered from the user is less accurate than in explicit feedback.

3) **Pseudorelevance Feedback:** This feedback selects positive and negative samples from the previous retrieval results without the participation of the user. The positive samples are the ones near to the query sample in the feature space, and the

negative samples are far from the query sample. This way, the user's feedback is simulated. These samples are returned to the system for the second search. Muneesawang and Guan [50] present a self-training neural network-based relevance feedback that can obtain good retrieval performance with no user input. Forward and backward signal propagation is used to simulate the user's feedback. Yan et al. [33] propose an automatic retrieval method that learns an adaptive similarity space by automatically feeding back the bottom-ranked examples for negative feedback. Hauptmann et al. [252] develop a robust pseudo relevance feedback method called probabilistic local feedback based on a discriminative probabilistic retrieval framework. The proposed method is effective to improve retrieval accuracy without assuming that most of the top-ranked documents are relevant. The merit of pseudo relevance feedback is the substantial reduction in user interaction. It is limited in applications because of the semantic gap between low-level and high-level features: the similarities of low-level features obtained from different videos do not always coincide with the similarities between the videos defined by the user. Active learning has been applied to relevance feedback for video retrieval. For example, Luan et al. [269] iteratively select videos that are the most relevant to the query until the number of videos labeled as relevant by users in an iteration step becomes very small. Then, the videos closest to the classifier boundary are returned to users for identification and the system is updated using the identified videos. Nguyen et al. [270] also use active learning in the interaction process to choose videos closest to the classifier boundary. In contrast with the aforementioned algorithm that selects videos in the feature space, they choose videos in the dissimilarity space represented by a number of prototypes. Bruno et al. [271] design a multimodal dissimilarity space for fast and efficient video retrieval. Different prototypes are

arned for each modality. Videos are selected in the multimodal dissimilarities spaces based on the multimodal characteristics. In contrast with the traditional relevance feedback algorithms which select the most relevant videos which are ranked for further search, active-learning-based relevance feedback algorithms [268] usually return the videos closest to the classifier boundary for identification. Then, these most informative videos are used to improve the precision of the retrieval system. It has been verified that active-learning-based relevance feedback algorithms have a better performance than traditional relevance feedback algorithms [268].

VI. VIDEOSUMMARIZATION AND BROWSING

Video summarization [39], [156], [157], [181] removes the redundant data in videos and makes an abstract representation or summary of the contents, which is exhibited to users in a readable fashion to facilitate browsing. Video summarization complements video retrieval [183], by making browsing of retrieved videos faster, especially when the total size of the retrieved videos is large: The user can browse through the abstract representations to locate the desired videos. A detailed review on video browsing interfaces and applications can be found in [261]. There are two basic strategies for video summarization.

- 1) Static video abstracts: each of which consists of a collection of keyframes extracted from the source video.
- 2) Dynamic video skims: each of which consists of a collection of video segments (and corresponding audio segments) that are extracted from the original video and then concatenated to form a video clip which is much shorter than the original video.

These two strategies can be combined to form hierarchical video summarizations. In the following, the different methods for video summarization are briefly reviewed. As video summarization is a research topic which is as large as video retrieval, we focus on reviewing papers published in the last four years, as a supplement to previous surveys [39], [181] on video summarization.

A. Key Frame-Based Static Abstracts

In recent years, many approaches [182], [189] have been proposed to organize extracted keyframes into static video abstracts. These approaches include video table of contents [142],

storyboard, and pictorial video summary. For instance, Xie and Wu [169] propose an algorithm to automatically generate the video summary for broadcast news videos. An affinity propagation-based clustering algorithm is used to group the extracted keyframes into clusters, aiming to keep the pertinent keyframes that distinguish one scene from the others and remove redundant keyframes. Li et al. [164] propose a MinMax rate distortion optimization algorithm to find keyframes for an optimal video summary. Optimal algorithms are developed to solve both the rate minimization and the distortion minimization formulations with different summarization rates. Calic et al. [175] propose a video keyframes summarization and browsing algorithm that produces a comic-like representation of a video. The algorithm creates visual summaries in a user-centered way. Guironnet et al. [161] propose a method for video summarization using camera motion analysis, based on rules to avoid temporal redundancy between the selected frames. Ane et al. [186] compose mosaics of scene backgrounds in sitcom programs. The mosaic images provide a compact static visual summary of the physical settings of scenes. Choudary and Liu [190] summarize the visual content in instructional videos, using extracted texts and figures. They match and mosaic the extracted keyframes to reduce content redundancy and to build compact visual summaries. Christe et al. [276] have constructed a baseline rush summarization system at TREC Vid 2008 [272]. This baseline method simply presents the entire video at 50x normal speed. The merit of keyframe-based static abstracts includes the following. 1) The video content is displayed in a rapid and compact way, with no timing or synchronization issues, for browsing and navigation purposes. 2) Nonlinear browsing of video content is possible. 3) The total video content can

becovered. The limitations of keyframe-based static abstracts include the following. 1) Audio content in the original video is missing.

2) The dynamic visual content of videos cannot be described.

3) The abstracts are unnatural and hard to understand when the video is complex.

B. Dynamic Video Skimming

Dynamic video skimming [166], [168], [172], [173] condenses the original video into a much shorter version that consists of important segments selected from the original video. This shorter version can be used to browse or to guide the editing of the original video.

The merits of dynamic video skimming include the following.

1) It preserves the time-evolving nature of the original video.

2) Audio can be included in skims. 3) It is often more entertaining and interesting to watch a skim rather than a slide show of key frames. The limitations of dynamic video skimming include the following. 1) The sequential display of video skims is time-consuming. 2) The content integrity is sacrificed, while video highlights are emphasized.

There are three main approaches to video skimming: redundancy removal, object or event detection, and multimodal integration.

1) Redundancy Removal: This approach removes unnecessary or redundant video segments from the original video and

retains the most informative video segments that are concatenated to form a skim. For example, Xiao et al. [158] extract

repeating patterns from a video. A video shot importance evaluation model is used to select the most informative video shot to

construct the video summary. Ngo et al. [160] represent a video

as a complete undirected graph and use the normalized cut

algorithm to optimally partition the graph into video clusters. At

most one shot is retained from each cluster of visually similar

shots in order to eliminate redundant shots. Gao et al. [174]

propose a video summarization algorithm suitable for personal

video recorders. In the algorithm, according to the defined

impact factors of scenes and key frames, parts of shots are

selected to generate an initial video summary. Then, repetitive

frame segment detection is applied to remove redundant information from the initial video summary. Wang and Ngo [176]

have proposed an algorithm for rush summarization task in TREC Vid-2007 [177]-[179]. In the algorithm, undesirable shots are filtered out and the intershot redundancy is minimized by

detecting and then removing repetitive shots. The most representative video segments are selected for summarization using

techniques such as object detection, camera motion estimation, key-point matching, and tracking. Liu et al. [274] have devised

an algorithm for the rush summarization task in TREC Vid-2008 [272]. They first segment a video into shots and the

nusea clustering algorithm to find and remove similar shots. Then, saliency detection is applied to detect the most informative shots

to be included in the summary. Chasan et al. [275] measure similarities between shots based on the similarities between key frames and employ them to remove repeated shots.

2) Object or Event Detection: Semantic primitives in videos, such as relevant objects, actions, and events, can be used in highlight-preserving video skims. In the object or event

detection-based approach, video segments are selected according to the results of video segment classification and object or event detection. Detected objects and events are ranked to create

the video skim. For example, in skimming sports videos, goals, fouls, touchdowns, etc. are detected as important events.

Ekim et al. [165] propose a framework to skim soccer videos through dominant color region detection, robust shot boundary

detection, shot classification, goal detection, referee detection, and penalty box detection. As an example of object-based skimming, Peker

et al. [188] propose a video skimming algorithm using face detection on broadcast video programs. In the algorithm, faces

are the primary targets, as they constitute the focus of most consumer video programs. Naci et al. [277] extract features using face detection, camera motion, and MPEG-7 color layout descriptors of each frame. A clustering algorithm is employed to find and then remove repeated shots. Bailer and Thallinger [273] compare two content selection methods for skimming rush videos. One approach is rule-based, and the other is HMM-based. A face detection module is employed to help select important segments to be included in the summary.

3) **Multimodal Integration:** For videos whose content is largely contained in the audio, such as news programs and documentaries, the spoken text can assist video summarization. Once caption text or speech transcripts in a video are available, a text summary can be integrated with the visual summary into the video skim, or the video sections corresponding to the selected text can be concatenated to generate the video skim. For instance, Taskiran et al. [184] divide a video into segments by pause detection, and derive a score for each segment according to the frequencies of the words in the audio track for the segment. A summary is produced by selecting these segments with the highest scores while maximizing the coverage of the summary over the full video. Gong [159] summarizes the audio and visual content of a source video separately and then integrates the two summaries using a bipartite graph. The audio content summarization is achieved by selecting representative spoken sentences from the audio track, while the visual content summarization is achieved by preserving visually distinct contents from the image track.

C. Hierarchical Summarization

Hierarchical video summaries can be obtained from key frames or from static video abstracts combined with video skimming. For instance, Taskiran et al. [185] cluster key frames extracted from shots using color, edge, and texture features and

present them in a hierarchical fashion using a similarity pyramid. Gen et al. [187] propose a hierarchical video summarization algorithm based on video structure and highlights. In the algorithm, video structure units (frame, shot, and scene) are ranked using visual and audio attention models. According to the measured ranks, the skim ratio and the key frame ratio of the different video structure units are calculated and used to construct summaries at different levels in a hierarchical video summary. Ciocca and Schettini [171] remove meaningless key frames using supervised classification on the basis of pictorial features derived directly from the frames, together with other features derived from the processing of the frames by a visual attention model. Then, the key frames are grouped into clusters

to allow multilevel summary using both low-level and high-level features.

VII. FUTURE DEVELOPMENTS

Although a large amount of work has been done in visual content-based video indexing and retrieval, many issues are still open and deserve further research, especially in the following areas.

1) **Motion Feature Analysis.** The effective use of motion information is essential for content-based video retrieval. To distinguish between background motion and foreground motion, detect moving objects and events, combine static features and motion features, and construct motion-based indices are all important research areas.

2) **Hierarchical Analysis of Video Contents.** One video may contain different meanings at different semantic levels. Hierarchical organization of video concepts is required for semantic-based video indexing and retrieval. Hierarchical analysis requires the decomposition of high-level semantic concepts into a series of low-level basic semantic concepts and their constraints. Low-level basic semantic concepts can be directly associated with low-level features, and high-level semantic concepts can be deduced from low-level basic semantic concepts by statistical analysis. In addition, building hierarchical semantic rel

a-tions
between scenes, shots, and key frames, on the basis of video
structural analysis; establishing links between classifications
with the three different levels: genres, event and object; and
hierarchical organizing and visualizing retrieval results are all interesting research issues.

3) Hierarchical Video Indices. Corresponding to hierarchical video analysis, hierarchical video indices can be utilized in video indexing. The lowest layer in the hierarchy is the index store model corresponding to the high-dimensional feature index structure. The highest layer is the semantic index model describing the semantic concepts and their correlations in the video store to be retrieved. The middle layer is the index context model that links the semantic concept model and the store model. Dynamic, online, and adaptive updating of the hierarchical index model, handling of temporal sequence features of videos during index construction and updating, dynamic measure of video similarity based on statistic feature selection, and fast video searching using hierarchical indices are all interesting research questions.

4) Fusion of Multimodels. The semantic content of a video is usually an integrated expression of multiple models. Fusion of information from multiple models can be useful in content-based video retrieval [38], [95]. Description of temporal relations between different kinds of information from multiple models, dynamic weighting of features of different models, fusion of information from multiple models that express the same theme, and fusion of multiple model information in multiple levels are all difficult issues in the fusion analysis of integrated models.

5) Semantic-Based Video Indexing and Retrieval. Current approaches for semantic-based video indexing and retrieval usually utilize a set of text to describe the visual contents of videos. Although many automatic semantic concept detectors have been developed, there are many unanswered questions: How to select the features that are the most representative of semantic concepts? How should large-scale concept ontology for videos

[76] be constructed? How to choose useful generic concept detectors with high retrieval utility? How many useful concepts are needed [243]? How can high-level concepts be automatically incorporated into video retrieval? How can ontology [79], [80] be constructed for translating the query into terms that a concept detector set can handle? How can inconsistent annotations resulting from different people's interpretations of the same visual data be reconciled? How can elaborate ontology be established between the detector lexica? How can multimodality fusion be used to detect concepts more accurately? How can different machine learning approaches be fused to obtain more accurate concepts?

6) Extensible Video Indexing. Most current video indexing approaches depend heavily on prior domain knowledge. This limits their extensibility to new domains. The elimination of the dependence on domain knowledge is a future research problem. Feature extraction with less domain knowledge and dynamic construction of classification rules using rule-mining techniques may eliminate this dependence.

7) Multimodel Human-Computer Interface. A multimodel human-computer interface can convey the query intentions more accurately and improve the accuracy of the retrieval results. Furthermore, the video output with multimodel representation is more visual and vivid. The layout of multimodel information in the human-computer interface, the effectiveness of the interface to quickly capture the results in which users are interested, the suitability of the interface for users' evaluation and feedback, and interface's efficiency in adapting to the users' query habits and expressions of their personality are all topics for further investigation.

8) Combination of Perception with Video Retrieval. It is interesting to simulate human perception to exploit new video retrieval approaches. The research in visual perception shows that the human vision system quickly identifies the salient image regions [46]. This ability extends from salient objects (i.e., faces) in video scenes to significant behaviors in video sequences. New video retrieval schemes could be based on the detection and extraction of image regions or video behaviors that attract users' attention [46], [162].

9) Affective Computing-Based Video Retrieval. Video affective semantics describe human psychological feelings such as romance, pleasure, violence, sadness, and anger. Affective computing-based video retrieval is the retrieval of videos that produce these feelings in the viewer. To combine affective semantics from the spoken

language in the audio track with visual affective semantics [75], to utilize cognitive models, cultural backgrounds, aesthetic criteria, cold and warm tones, psychology, or photography [88], and to understand affective semantics in videos are very interesting research issues.

10) Distributed Network Video Retrieval. Network video re-trieval should adopt distributed frameworks [48] rather than conventional centralized frameworks. Distributed network retrieval is composed of two stages: video gathering and video content analysis. In video gathering, the bandwidth of

transportation and storage is kept low by using only real-time

online methods to analyze the videos. In video content analysis,

more elaborate methods are used to search for specific objects

and to categorize the videos. The video content analysis uses key

data extracted during video gathering. Video indexing and

retrieval in the cloud computing environment, where the individual

video is to be searched and the dataset of videos are both

changing dynamically, will form a new and flourishing research

direction in video retrieval in the very near future.

11) Social Network-

Based Video Retrieval. Besides optimizing

the performance of each local video indexing and retrieval

system, local systems can be integrated into a network character-

ized by distributed and collaborative intelligence to achieve

more accurate retrieval. It is very interesting to implement such

integration in the context of a social network in which users

share video contents which they recommend to each other through

collaborative filtering or in the context of a video content infer-

ence network in which video content inference systems learn

from each other and complement each other [29]. Such integration

by a social network can even take the social or cultural context into consideration during video retrieval.

VIII. CONCLUSION

We have presented a review on recent developments in visual content-based video indexing and retrieval. The state of the art of

existing approaches in each major issue has been described with

the focus on the following tasks: video structure analysis including shot boundary detection, keyframe extraction and

scene segmentation, extraction of features of static keyframes,

objects and motions, video data mining, video classification and

annotation, video search including interface, similarity measure

and relevance feedback, and video summarization and browsing.

At the end of this survey, we have discussed future directions

such as affective computing-based video retrieval and distributed

network video retrieval.

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