

From Smart Farming towards Agriculture 5.0: A Review on Crop Data Management

Samarendra Samal, Subham Kumar Barik

Gandhi Institute of Excellent Technocrats, Bhubaneswar

Modern Institute of Technology and Management, Bhubaneswar, Odisha, India

ABSTRACT: The information that crops offer is turned into profitable decisions only when efficiently managed. Current advances in data management are making Smart Farming grow exponentially as data have become the key element in modern agriculture to help producers with critical decision-making. Valuable advantages appear with objective information acquired through sensors with the aim of maximizing productivity and sustainability. This kind of data-based managed farms rely on data that can increase efficiency by avoiding the misuse of resources and the pollution of the environment. Data-driven agriculture, with the help of robotic solutions incorporating artificial intelligent techniques, sets the grounds for the sustainable agriculture of the future. This paper reviews the current status of advanced farm management systems by revisiting each crucial step, from data acquisition in crop fields to variable rate applications, so that growers can make optimized decisions to save money while protecting the environment and transforming how food will be produced to sustainably match the forthcoming population growth.

Keywords: agriculture 4.0; big data; farm management information system (FMIS); robotics; IoT; variable-rate technology (VRT); AI

I. INTRODUCTION

The agriculture sector is undergoing a transformation driven by new technologies, which seems very promising as it will enable this primary sector to move to the next level of farm productivity and profitability [1]. Precision Agriculture, which consist of applying inputs (what is needed) when and where is needed, has become the third wave of the modern agriculture revolution (the first was mechanization and the second the green revolution with its genetic modification [2]), and nowadays, it is being enhanced with an increase of farm knowledge systems due to the availability of larger amounts of data. The United States Department of Agriculture (USDA) already reported in October 2016 that Precision Agriculture technologies increased net returns and operating profits [3]. Also, when considering the environment, new technologies are increasingly being applied in the farms to maintain the sustainability of farm production. However, the adoption of these technologies involves uncertainty and trade-offs. According to a market analysis, the factors that would facilitate the adoption of sustainable farming technologies include better education and training of farmers, sharing of information, easy availability of financial resources, and increasing consumer demand for organic food [4]. When applying these new technologies, the challenge for retrieving data from crops is to come out with something coherent and valuable, because data themselves are not useful,

just numbers or images. Farms that decide to be technology-driven in some way, show valuable advantages, such as saving money and work, having an increased production or a reduction of costs with minimal effort, and producing quality food with more environmentally friendly practices [5]. However, taking these advantages to the farm will depend, not only on the willingness of producers for adopting new technologies in their fields, but also on each specific farm potential in terms of scale economies, as profit margin increases with farm size. The USDA reported that, on average, corn farm operating profit of Precision Agriculture adopters was 163 dollars per hectare higher than for non-adopters, taking into account that the highest adoption rates for three technologies (computer mapping, guidance, and variable-rate equipment) were on farms over 1500 hectares [3]. Such margins can even go up to 272 dollars depending on the crop. A greater use of Smart Farming services is vital to not only improving a farm's financial performance, but also to meet the food needs of an expanding population [6].

The final purpose of this paper is to demonstrate how making decisions with the modern data-based agriculture available today can lead to sustainable and profitable actuation to nourish people while reducing harm to the environment. In order

to evaluate how modern agriculture can help in a sustainable decision-making process, this article revisits the main steps of an information-based agriculture and focuses on data management systems by reviewing recent applications related to each crucial step, from data acquisition in crop fields to the execution of tasks with variable rate equipment.

Data-Driven Agriculture: Agriculture 4.0

This new philosophy centered on agricultural data has been expressed with several names:

Agriculture 4.0, Digital Farming, or Smart Farming, and was born when telematics and data management were combined to the already known concept of Precision Agriculture, improving the accuracy of operations [7]. As a result, Agriculture 4.0 is based on Precision Agriculture principles with producers using systems that generate data in their farms, which will be processed in such a way to make proper strategic and operational decisions. Traditionally, farmers have gone to the field to check the status of their crops and make decisions based on their accumulated experience. This approach is no longer sustainable as, among other reasons, some fields are too large to be efficiently managed according to the threefold criteria that will lead the coming years: Efficiency, sustainability and availability (for people). Advanced management systems within the context of Smart Farming are providing practical solutions. Also, despite some farmers have a long-time experience gathered after many years of work in the field, technology may provide a systematic tool to detect unforeseen problems hard to notice by visual inspection on occasional checks. Regarding the willingness of adopting modern tools in agriculture, young farmers show a more positive attitude than elder ones, as the former can support their not-so-large experience in the field with new smart tools providing key information. However, the average age of farmers in the last decades has been alarmingly increasing: Around 58 years old in the USA and Europe, 60 in sub-Saharan Africa, or 63 in Japan [8,9]. Fortunately, this trend is expected to change. Several European policies, for example, are being set to support a generational renewal, facilitating access to initial investment, loans, business advice, and training [9]. A generational renewal in a rural development context goes beyond a reduction in the average age of farmers; it is also about empowering a new generation of highly qualified young farmers to bring the full benefits of technology in order to support sustainable farming practices [10]. This implies that young farmers will need to transform the existing land to more modern and competitive farms with the purpose of maintaining viable food production while improving the competitiveness of

the agrifood chain, because with advanced technologies and new thinking, young people can transform the agricultural sector [8].

Internet of Things: Collecting Information

Internet of things (IoT) in an agricultural context refers to the use of sensors and other devices to turn every element and action involved in farming into data. It has been reported that an estimation of a 10% to 15% of US farmers are using IoT solutions on the farm across 1200 million hectares and 250,000 farms [11]. IoT drives Agriculture 4.0 [12]; in fact, IoT technologies is one of the reasons why agriculture can generate such a big amount of valuable information, and the agriculture sector is expected to be highly influenced by the advances in these technologies [13]. It is estimated that, with new techniques, the IoT has the potential to increase agricultural productivity by 70% by 2050 [14], which is positive, because according to Myklevy et al., the world needs to increase global food production by 60% by 2050 due to a population growth over nine thousand million [15]. The main advantages of the use of IoT are achieving higher crop yields and less cost. For example, studies from OnFarm found that for an average farm using IoT, yield rises by 1.75% and energy costs drop 17 to 32 dollars per hectare, while water use for irrigation falls by 8% [12].

Big Data: Analysis of Massive Data

In the current technology-based era, the concept of big data is present in many economic sectors, but is it already available to agriculture? The ever-growing amount of data available for field management makes necessary the implementation of some type of automatic process to extract operational information from bulk data. However, the volume of data currently retrieved from most commercial fields is, arguably, not yet at the level considered to be classified as big data. According to Manyica et al. [16], big data has three dimensions: Volume, velocity, and variety. Kunisch [17] added a fourth V for veracity. Finally, a fifth V was added by Chiet al. for the extra dimension valorization [18]. Overall, the five V (dimensions) of big data stand for:

- Volume refers to datasets whose size is beyond the ability of typical database software tools to capture, store, manage, and analyze information. This definition includes an estimate of how big a dataset needs to be in order to be considered big, and it can vary by study sector, depending on software tools that are commonly available and common sizes of datasets, typically starting in the terabyte range [16].
- Velocity refers to the capability to

acquire, understand and interpret events as they occur. In agriculture, this would refer to applications that occur in real time, like data being processed right in the field to apply variable rates of chemicals in equipment featuring variable rate application technologies.

- Variety refers to the different data formats (videos, text, voice), and the diverse degrees of complexity. This situation is not strange in agriculture when different data sources are used to work in complex scenarios such as images and soil or weather probes.

- Veracity refers to the quality, reliability, and overall confidence of the data.

- Valorization is the ability to propagate knowledge, appreciation and innovation [18].

In the context of crop management, Kunisch [17] concluded that big data is applicable only in some cases in agriculture, depending on each farm and its level of technology adoption. Nevertheless, the Proagrica [19] report confirmed that big data was being increasingly applied in the agriculture sector. Kamilaris et al. [18] cited 34 works where big data was used in agricultural applications, and Wolfert et al. [20] published a review on big data applications in Smart Farming. In line with this trend, the Consortium of International Agricultural Research Centers (CGIAR, Montpellier, France) created a Platform for Big Data in Agriculture with the purpose of using big data approaches to solve agricultural development problems faster, better, and at a greater scale than before [21].

Agriculture 5.0: Robotics and Artificial Intelligence (AI) to Help in Nourishing People

Big engineering challenges typically spur big solutions through disruptive technologies, and Agriculture 5.0 is probably the one for the first half of the 21st Century. The concept Agriculture 5.0 implies that farms are following Precision Agriculture principles and using equipment that involves unmanned operations and autonomous decision support systems. Thus, Agriculture 5.0 implies the use of robots and some forms of AI [22]. By tradition, farms have needed many workers, mostly seasonal, to harvest crops and keep farms productive. However, so society has moved away from being an agrarian society with large quantities of people living in farmstop eople living in cities now; as a result, farms are facing the challenge of a workforce shortage. One solution to help with this shortage of workers is agricultural robots integrating AI features. According to a Forbes study [23], farm robots augment the human labor workforce and can harvest crops at a high volume and faster pace than human laborers. Although there are still many cases in which robots are not as fast as humans, agriculture is currently developing robotics systems to work in the field

and help producers with tedious tasks [24–27], pushing agricultural systems to the new concept of Agriculture 5.0. According to Reddy et al. [28], the advent of robots in agriculture drastically increased the productivity in several countries and reduced the farm operating costs. As said before, robotic applications for agriculture are growing exponentially [27], which offers promising solutions for Smart Farming in handling labor shortage and a long-time declining profitability; however, like most innovations, there exist important limitations to cope with at the current early stages. These technologies are still too expensive for most farmers, especially those with small farms [29], because scale economics make small individual farms less profitable [30]. Nevertheless, the cost of technology decreases with time, and agricultural robots will be surely implemented in the future as the alternative to bring about higher production [4, 31]. The world agricultural production and crop yields slowed down in 2015. The concept of agricultural robotics was introduced to overcome these problems and satisfy the rising demand for high yields. Robotic innovations are giving a boost to the global agriculture and crop production market, as according to the Verified Market Intelligence report, agricultural robots will be capable of completing field tasks with greater efficiency as compared to the farmers [32].

Agricultural tech startups have raised over 800 million dollars in the last five years [31]. Startups using robotics and machine learning to solve problems in agriculture started gaining momentum in 2014, in line with a rising interest in AI [33]. In fact, venture capital funding in AI has increased by 450% in the last five years [34]. This kind of new agriculture pre-tendstodomorewithless, because nourishing people while increasing production sustainably and taking care of the environment will be crucial in the coming years, as the Food and Agriculture Organization of the United Nations (FAO) estimates that, in 2050, there will be a world population of 9.6 billion [35]. Advanced sensing technologies in agriculture can help to meet the challenge; they provide detailed information on soil, crop status, and environmental conditions to allow precise applications of phytosanitary products, resulting in a reduced use of herbicides and pesticides, improved water use efficiency and increased crop yield and quality [2].

Data-Driven Management for Advanced Farming: Principal Stages

The raw measurements of key parameters

from crops need to be efficiently processed so that numbers or images unambiguously turn into valuable information. Crop management based on field data already evolved when Precision Agriculture came to light thirty years ago, but it has certainly been transformed by the present digital information era. Traditionally, and in those places where technology has not arrived yet, field management consists of visually inspecting the development of crops to reach a diagnosis with which farmers make decisions and actuate giving different treatments to their crops. This approach relies on field experience and the information perceived through the eyes of farmers. Additionally, associated growers can follow the recommendations of cooperative technicians or engineers hired by the society they belong to. In farms where advanced technology has been implemented, field management varies according to the operating cycle shown in Figure 1. This management system based on objective field data and smart decision-making starts with the actual crop to manage, taking advantage of its inner variability, both spatial-wise and time-wise. The platform

refers to the physical means with which information is acquired, being the sensor or the specific elements through which objective data are obtained. Data includes the information directly retrieved from the parameters measured from the crop, soil, or ambient. Retrieving the data from the sensors can be done in multiple ways, from inserting a pen drive in a USB port to the files [36] to retrieving data from software applications synchronized to the Internet. The nexus between the data and the decision stage involves filtering routines and AI algorithms for getting only the right data and helping the grower make correct decisions. Finally, actuation refers to the physical execution of an action commanded by the decisions system, and is typically carried out by advanced equipment that can receive orders from a computerized control unit. As each action takes place over the crop, the cycle starts and closes at crop level; the response of the crop is then registered by specialized sensors and the loop continues systematically until harvesting time, which marks the end of the crop life cycle.

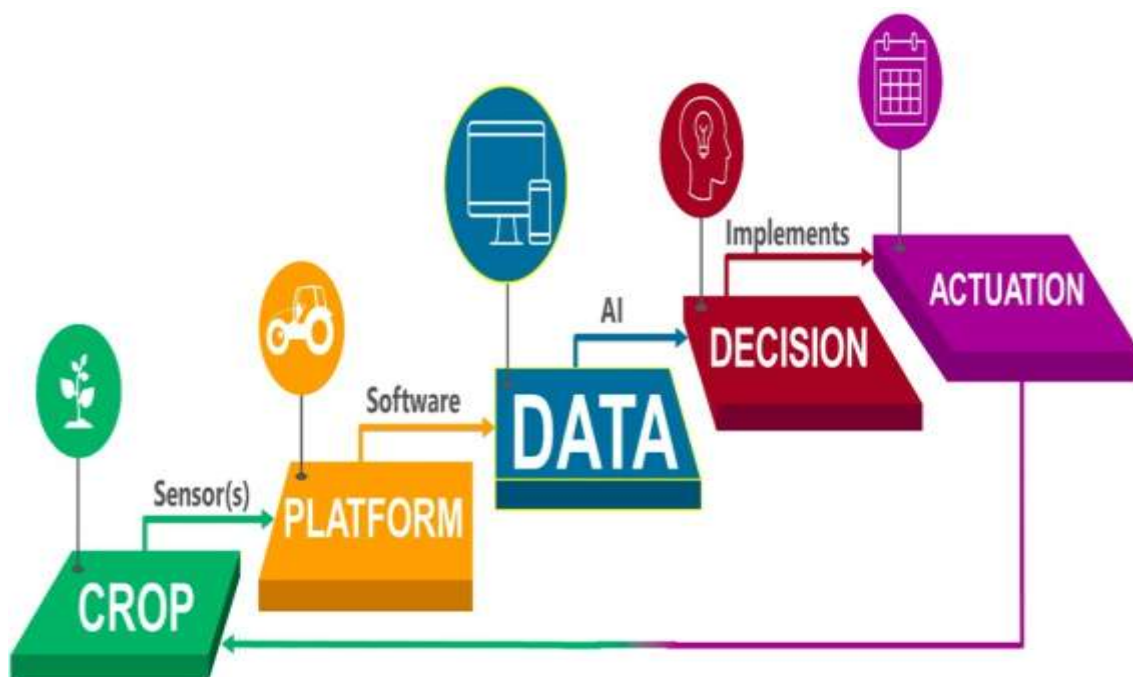







Figure 1. Information-based management cycle for advanced agriculture.

The following paragraphs and Figure 1 explain the cycle that embodies a general data-driven management system for advanced agriculture, including representative examples for each stage. Table 1 classifies the scientific works referenced in this study into the different categories of Figure 1.

Table 1. Classification of the research articles referenced in the present study.

Category	Subcategory	References
 CROP	Precision and Smart Farming	[2,4,7,29,35,37-40]
	Social and economic impact	[3,5,6,8-11,31]
	Management zones	[38,41-43]
 PLATFORM	Remote sensing (satellite and aircraft)	[44-46]
	Proximal sensing (ground vehicles)	[24-28,36,45-63]
	Big data	[1,16-21,30,32]
 DATA	Internet of Things (IoT)	[12-14,64]
	Mapping	[42,65-69]
	Information Systems (GIS, FMIS)	[64,70-80]
 DECISION	Artificial Intelligence (AI)	[22,23,33,34,81]
	Decision Support Systems (DSS)	[77,82-90]
 ACTUATION	Variable Rate Applications (VRA)	[91-93]

Stage I: The Crop as the Beginning and End of the Agricultural Management Cycle—
 Analyzing Variability
 Regardless how the crop will be managed, some degree of spatial variability is assumed for all fields by nature. According to Searcy [37], natural variability is influenced by weather within a growing season and from year to year; then, data from several years may be needed to determine trends in the parameters of interest, and hence, data becomes a regular input to the farm management system. Therefore, the necessity of monitoring crops comes from the existence of variability, but there is a need for the producer to manage that variability in a feasible way, and the widely accepted way to do it is by setting within-field management zones. Management zones are subfields that have homogeneous features, so field practices can be customized to each of such areas, resulting in a practical and cost-effective approach to Precision Agriculture [41]. The adoption of management zones would reduce the cost of fertilizing, improve crop yields, reduce the use of pesticides, provide better farm records that are essential for sale, and provide better information for management decisions [4]. According to Zhang et al. [38], the number of management zones is a function of the natural variability within the field, the size of the field and certain management factors. If the variability is high, the minimum size of a zone is limited by the possibility of each farmer to differentially manage regions within a field in economic and logistic terms. In addition to deciding the area of working zones, the selection of the specific parameters to be tracked within those zones must be carefully made early in the process. Rovira-Más and Saiz-Rubio [65] classified crop

biometric traits in a tri-level division of crop features depending on the focus of interest being at soil level, plant level, or produce level. This division allowed the superimposition of various layers in a standardized map with the aim of determining a data-based wine quality index defined as the Quality Potential Index (QPI) for each subfield area in a vineyard. Nevertheless, there may be specific cases where the spatial variability of a field is so low that a single mapping event can be sufficient, as reported by Klassen et al. [42] when characterizing soil variability in rice fields.

Stage II: Platforms Supporting Sensors

Sensors are the universal devices to monitor crops and to obtain objective information from them. They are usually integrated in a platform, which is the general term used in Figure 1 to name the structures where sensors are placed and carried. These platforms may be attached to off-road vehicles or fixed to the ground within fields such as local weather stations. One of the most urgent challenges to cope with in the next few years will be getting a wide range of non-invasive sensors able to measure on-the-go. This approach would be closer to Agriculture 5.0, as these sensors could be attached to autonomous platforms and robots. Nowadays, not all the parameters of interest can be measured non-invasively and at a distance from the target; however, so many technologies such as multispectral or hyperspectral imaging are making significant improvements.

Remote Sensing Platforms: Satellites

Remote sensing has played a key role in the progress of Smart Farming when field data became

generally accessible from artificial satellites. Important satellites providing agricultural information are the American Landsat satellites (eight satellites take spectral data from the Earth each 16 to 18 days), the European Sentinel 2 satellite system (it provides multispectral data at 10 m pixel resolution for NDVI—Normalized Difference Vegetation Index—imagery, soil, and water cover every ten days), the Rapid Eye constellation (five satellites provide multispectral RGB imagery, as well as red-edge and NIR bands at 5 m resolution), the GeoEye-1 system (captures multispectral RGB data and NIR data at 1.84 m resolution), and the WorldView-3 (collects multispectral data from the RGB bands including the red-edge, two NIR bands, and 8 SWIR bands with a resolution of 1.24 m at nadir). IKONOS and QuickBird have been already decommissioned. There exist several reviews on satellite sensing applications, having recent studies focused on the potential applications of thermal technologies using remote sensing [44] and nutritional status in commodity crops [45].

Aircraft Systems

The distance between crops and satellites is considerable, typically around 700 km, and deeper insights are reachable when sensors remain closer to the targets. For aircraft systems, the distance to land can be around 100 m. For example, there is a legal limit of 120 m above the ground in Spain for unmanned flying vehicles. Unmanned aerial vehicles (UAV) and remotely-piloted aircrafts (RPA) can basically be of two kinds: Fixed-wing aircrafts and multirotor aircrafts. Rotary-wing UAVs are more stable fliers as they are capable of a vertical take-off and landing; however, they are slower and cannot cover as much area during their battery life. Fixed-wing platforms, on the other hand, can cover more area per flight and carry larger payloads, but tend to be more expensive and break more easily after multiple landings [45]. When compared to remote sensing, the advantages of UAVs for Precision Agriculture are their flexibility in frequency (revisit time of satellites) and better spatial resolutions. When compared to ground vehicles, UAVs can get data from inaccessible places where conventional equipment cannot stand; however, they require professional planning of the flight route beforehand, and certain machine vision applications may require flying at midday to avoid vegetation shadows on the ground causing errors with imagery data. Furthermore, post processing the data and image mosaicking is often quite challenging. An important disadvantage of UAVs is the limited payload

they can carry, which often limits the suite of sensors on board, as well as the incapacity of flying with strong wind.

Proximal Sensing: Ground Autonomous Systems—the Great Push for Agriculture 5.0
When monitoring platforms operate from the ground, the distance from the sensor to the target crop diminishes to less than 2 m. Due to the proximity of the sensor to the plant, when data is acquired from ground-

based platforms, it is called proximal sensing. Ground vehicles are polyvalent in relation to the payload of sensors. As these vehicles move near the crop, the data acquired increases in accuracy, and resolutions of one or more samples per meter are feasible, being only limited by the specifications of the particular sensors implemented. When active sensors are used, weather conditions such as strong sunlight or poor illumination are not a serious problem anymore, and, in case of on-the-fly processing, real-time applications are possible, as spraying weeds with the previous detection of the pest [47]. There has been a significant impulse in the last five years for the particular case where data is retrieved from an autonomous platform (unmanned ground vehicle or UGV) [48–52]. Aravind et al. [48] reviewed ground robots for tilling, soil analysis, seeding, transplanting, crop scouting, pest control, weed removal and harvesting, where crop scouting has been defined as the process of continuously monitoring the field to acquire information on the plant status, disease incidence, and infestations affecting crop growth. Shamshiri et al. [27] described recent achievements of UGVs for weed control, field scouting, and harvesting, highlighting that, if successfully integrated and implemented, field scouting robots can play a key role in reducing production cost, increasing productivity and quality, and enabling customized plant and crop treatments. The European Commission (EC) has recently backed the relevance of robotic technology for Smart Farming by funding four projects involving the construction of UGVs for advanced vineyard management: VineRobot, Vinbot, GRAPE, and VineScout. In 2016, the European project VineRobot [53] delivered a monitoring robot prototype at a Technology Readiness Level (TRL) status between 6 and 7 (TRL1 represents an early stage concept and TRL9 is a solution ready for production), paving the path for its conceptual termination in the VineScout project [54]. The 2019 version of VineScout is shown in Figure 2. This robot is autonomously driven when monitoring vineyards with the assistance of local perception sensors (stereo camera, lidar and ultrasound sensors) for navigation and safeguarding. It gathers data from the canopy of the vines with the goal of creating plant water status maps and nutritional

status maps. In order to accomplish its mission in a reasonable time frame, established by end-users at a rate of 6h per day, this robot monitors vine canopies non-invasively, which implies several challenges. Regarding hardware, fast and robust sensors were set to work non-invasively and in motion, while having a cost-efficient price for the agriculture sector. Regarding software, the challenge was the agile integration of all the crop-sensing devices and the multi-season ground-truth validation of the models developed in the field.

In addition to scouting robots, the introduction of robotic tools to the farm is also being led by industry on specific agricultural tasks. Naïo Technologies, for instance, has developed robot Oz for mechanical weeding [55], and the autonomous sprayer GUSS received the Davidson Prize in 2019 [56]. RowBot Systems LLC (Minneapolis, MN, USA) patented a robotic platform whose structure was configured to perform several field tasks, as selectively applying

fertilizer, mapping growth zones, or seeding cover crop [57]. Over the 20th century, farm productivity has been increasing by augmenting the size of machines, which has led to heavy and oversized equipment. In order to invert this trend, researchers and growers have started to think about alternatives to tractors to avoid soil compaction.

Shamshiri et al. [27] suggested using various machines instead of one heavy machine. In the same line, Hameed [58] proposed a technology that enabled a single farmer to control a team of automated vehicles, and Ball et al. [59] used cooperative robots as a measure to control weeds. In fact, there have been several projects implementing more than one machine operating in collaborative work, as the Flourish European project that combines UAVs and UGVs to retrieve information for decision support [46], or the RHEA project where a fleet of autonomous robot units performed treatments in crops [82].



Figure 2. Version II (2019) of VineScout autonomous robot: Front (a) and rear (b).

Stage III: Data

One of the fundamental differences between traditional and modern farming is, apart from the mechanization level, the data collected directly from the crops. In traditional farms where growers judge by visual assessment, decisions are relative and subjective. Modern farming offers assessment by quantitative data producing objective decisions. Sensors allow data acquisition in the field, but the special case of non-invasive technologies in combination with on-the-fly sensing from moving platforms has opened the window of massive data collection, a forerunner of big data in agriculture. However, the excess of data is also a serious challenge to cope with, as vital

information may result masked by noise. The NDVI measurements collected for plotting the maps of Figure 3 [94] were collected with two sensors working simultaneously (SRS sensors, METER Group, Inc., Pullman, WA, USA) and placed in the robot of Figure 2. One of the sensors pointed to the sky and corrected NDVI estimates with the incident light from the sun, and the other sensor pointed sideways to the canopy to collect data from the leaves at an approximate distance of 0.5 m. The zenithal photo inserted on the bottom-right corner of Figure 3a shows the VineScout autonomous robot taking data between two rows in a vineyard. The onboard algorithm averaged individual local measurements of NDVI in square

cells of 16 m² classified into nine NDVI levels between 0 and 1 (Figure3a). The grid map of Figure3a, despite informative, is not operational, so after the simplification of data is necessary before a grower may find it useful. Figure3b is the result of

applying a clustering filter to Figure3a. It shows two management zones based on vine vigor (high-medium) for the grower to make decisions, together with water status maps, about fertilization and differential harvesting.

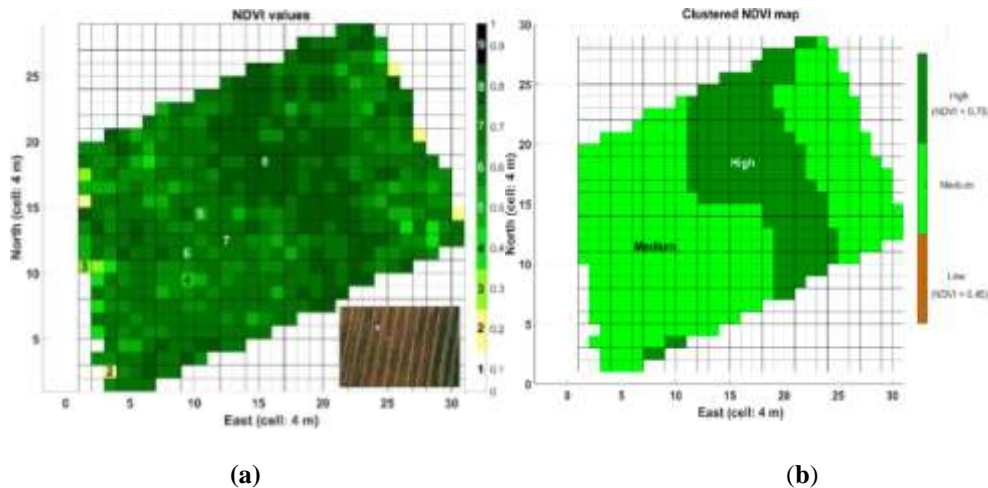


Figure 3. Grid maps of NDVI (Normalized Difference Vegetation Index) without zoning (a), and after applying a clustering algorithm (b).

Maps Containing Relevant Field Features

Displaying data in a coherent format is key for farmers to understand what is happening in the field. The most common way to display agricultural data has been in the format of maps, as mapping is useful to define spatial trends and homogeneous zones. However, displaying agronomical information in beautiful maps should not be the goal of map generation. Maps need to be useful for making decisions, they need to be a help to answer a question, providing an interpretation of spatial information [39]. The goal of building maps is obtaining a few management zones with the parameters of interests so that a treatment can be efficiently applied. To get plausible management zones, kriging is one of the most used interpolation techniques to delimit areas of manageable sizes [43]. Taking into account the considerable amount of data that Smart Farming generates, there are many software applications to cope with interpolation, in general, or kriging in particular [66]. Also, when building a map, a coordinate system needs to be supplied along with the map. One ideal alternative for agricultural maps is brought by the Local Tangent Plane (LTP) coordinate system, which features Euclidean geometry, allows user-set origins, and employs the intuitive coordinate frame east-north. Regarding the coding and display of data in the maps, grids allow the systematic quantization of the LTP coordinate system to manage crop production information more efficiently, facilitating the exchange of information among successive seasons and the comparison of multiple parameters on the same field [67]. A practical

example of grid-based maps using LTP coordinates is shown in Figure 3.

Taking into account the key role of positioning systems, a map-based approach is the method in which a Global Positioning System (GPS)—or any other Global Navigation Satellite System (GNSS)—receiver and a data logger (e.g., an onboard computer) are used to record the position of a particular measurement (georeferenced data), so several maps can be generated and processed along with other layers of spatially variable information [68]. In general, GNSS receivers are the universal position devices used to build maps; however, in some cases, for example in greenhouses or dense fields of tall trees, GNSS is not the best option to use due to the difficulty of getting signals with reliable accuracy; so, in some cases, alternative solutions such as machine vision must be implemented [69].

Data Management Software to Ease the Process of Decision Making

A popular way to manage field data displayed on maps and culminate with a practical solution is through the use of Geographic Information Systems (GIS). This set of computer-based tools (or data platforms) allow to store, analyze, manipulate and map any type of georeferenced information. A specific GIS system called the Field-level geographic Information System (FIS) was developed for Precision Agriculture applications [70], but it was set for old computer operative systems such as Windows 3.1x, 95, 98, or NT [71]. The updated version of FIS is the farm management

information system (FMIS), which according to Burlacu et al. [72] is a management information system designed to assist farmers with various tasks, ranging from operational planning, implementation and documentation to the assessment of performed field work. The purpose of FMIS is to reduce production costs, comply with agricultural standards, and maintain high product quality and safety, guiding growers to make the best decisions possible [95]. Farm management software solutions support the automation of data acquisition and processing, monitoring, planning, decision making, documenting, and managing the farm operations [64], and include basic functions for record keeping like crop production rates (harvests and yields), profits and losses, farm tasks scheduling, weather prediction, soil nutrients tracking, and field mapping, up to more complex functionalities for automating field management accounting for farms and agribusinesses (accounting, inventory management, or labor contracts). In many cases, growers do not need to be fluid on data management because the software can build maps or decision-making models with basic information introduced by growers. Furthermore, a critical feature of these applications is that they even help in the early warning of weather-related hazards that enables farmers, policy makers, and aid agencies to mitigate their exposure to risk [83]. However, it must be taken into consideration that the efficiency of a recommendation for a particular agent will depend on the factors included in the algorithms of the software (technical, economic, safety-wise. . .). In this sense, a DSSAT (Decision Support System for Agrotechnology Transfer) provides outputs with experimental data for evaluation of crop models, allowing users to compare simulated outcomes with observed results, which is critical for real-world decisions or recommendations are based on modeled results [84]. Table 2 gathers representative sets of commercially available FMIS programs specifically configured to deal with the usual data generated in the farm. It includes the

name of each application program, the company commercializing it with its headquarters location, and the main features of the program. The table is focused on programs managing crop data as the primary tool, and its purpose is not the compilation of all available FMIS software, which would be futile given the rate new applications are constantly released, but bringing a proof of the global effort realized in the last decade to deploy Smart Farming in actual farms, accelerating the move from academics to agribusiness. The examples show that some smartphone and tablet applications already include complex features so that growers can insert data directly in the field; other companies, on the contrary, prefer having a basic application for mobile devices to increase complexity in the cloud-based desktop version. In the majority of cases, it is not necessary to have wireless connection while the grower is entering data in the field, because as soon as the mobile device finds a wireless connection to the internet, it synchronizes the data previously introduced by the grower in the mobile device with the data safely stored in the cloud. Many of the programs listed below offer the option of upgrading the software depending on specific grower needs, increasing the price accordingly. The most advanced tools include features for financial and machinery management, help in the decision-making process, release warnings, or even propose management advice. In many cases, these software applications are not only addressed to the grower or producer, but also to other stakeholders in agriculture such as input suppliers, service suppliers, and food distributors, which makes a difference for Smart Farming, where multiple agriculture agents are connected. Regarding exploitation rights, various agricultural management systems have been patented, as the software from The Climate Corp. to generate agriculture prescriptions [85], which entered into partnership with AGCO Corporation in 2017 [4]. Decisive Farming Corp. [73,74], AgVerdict Inc. [75] or Trimble [86] have also patented their commercial solutions.

Table 2. Crop data management software applications and their main features [31,77–79,91].

Software	Company	Headquarters	Relevant Features
ADAPT	AgGatekeeper	WashingtonDC, USA	Input/output translator to manage data among controllers, field equipment, and farm management information system (FMIS) in an adequate format. Open-source system offered at no cost for developers to adopt into their proprietary systems.
AGERmetrix	AGERpoint	Florida, USA	Crop data and analytics platform with mapping interface. Able to scan and collect high-resolution crop data through LIDAR and other collaborative techniques. Permits taking data on mobile devices.
AgHub	GiSC	Texas, USA	Independent solution by a cooperative. Collect and securely stores data. Data can be shared with trusted advisors. Integration from IBM's Weather Operations, Main Street Data, Validator, and Market Vision.
AgriVi	AgriVi	United Kingdom	Weather, field mapping, plan inventory. Crop machinery and personnel management (notifications and reports). Web-based and mobile versions. Upgrades and Add-ons.
Agroptima	Agroptima	Spain	Mobile App as an electronic notebook to record field activities, products applied, workers implied, working time or machinery usage. Data can be downloaded on Excel, and safely stored in the cloud. [In Spanish]
AgroSense	Corizon	Netherlands and Spain	Open source. Work done, fields data, and timetables can be shared with contractors or employees. Automate importing and interpreting performed tasks via ISOBUS. Export in several formats.
AgVerdict	AgVerdict (Wilbur-Ellis)	California, USA	Desktop and mobile app. Enables data delivery to regulatory agencies or packers, shippers, and processors. Data security, decision making, VR ¹ possibility, soil analysis and crop recommendations.
Akkerweb	(Several providers)	The Netherlands	Independent consulting platform for organizing field and crop rotation plans. Information in one central geo-platform. Several applications. [In Dutch]
APEX™ JDLink	John Deere	Illinois, USA	Online tools enabling access to farm, machines, and agronomic data. Allows collaborative decisions from the same set of information to optimize logistics, plans and direct in-field work.
CASE IH AFS software	CASE IH	Wisconsin, USA	Single, integrated software package. View, edit, manage, analyze and utilize precision farming data to generate yield or VR ¹ prescription maps. Maps and reports can be shared in different formats.
Connected Farm	Trimble Agriculture	California, USA	Input, access, share records (images, reports) in real time. Integrates the whole system: crop scouting, grid sampling, fleet management, contracts. Farm Core connects all aspects of farm operation.
Cropio	New Science Technologies	New York, USA	Productivity management system. Remote monitoring of land. Real time updates on current field and crop conditions; harvest forecasting. Web-based service and mobile app. Training provided.
Cropwin Vintel	itk	France	Customizable tool for integrated crop management. Observation, analysis, and optimization. Vintel: Decision support tool for vineyards. Tracks water status, cover crop and nutrient management.
The Phyttech Platform	PHYTECH	Israel	Plant-based app for irrigation. Monitors and provides data on crop growth. All data can be used to determine overall water needs.
ESE™ Agri solution	Source Trace	Massachusetts USA	Thought to manage group of farms and farmers. Unified and up-to-date farmer database. Record field visits with photos, notes, activities, location. Farm-to-Fork traceability of produce. Unique ID for each farmer.

Table 2.Cont.

Software	Company	Headquarters	Relevant Features
Fambrate	Fambrate	Colorado, USA	Farm schedule at-a-glance or in detail. The schedule can be shared to set up daily or recurring tasks. Weather forecast available. To-Do list, reminders, events, and appointments.
FarmCommand	FarmersEdge	Manitoba, Canada	Farm management platform. Provides both hardware (i.e., weather station) and software for in-field decision support. Available as a web-based tool and a mobile app.
Famleap	Famleap	France	Comparison of field performance locally and nationally. Reports time spent by operation type, yield analysis, production costs, irrigation follow-up, detailed weather, data sharing, employee management (In French).
FarmLogic/ FamPAD	TapLogic	Kentucky, USA	Web-based ag record-keeping. Global Positioning System (GPS) field mapping to draw boundaries, mark points, measurements, etc.; personalized reports for distribution, pesticide database, maintenance records, and work orders creation.
Farm Management Pro	Smart farm software	Ireland	Mobile app for farm records, costs and expenditure accounting, tractor management, crop management, fertilizer and spray compliance, staff timesheets, document management. No desktop version available.
Famplan (Gatekeeper)	Proagrica	United Kingdom	For crops (Gatekeeper), livestock, and business. Exchange data, workplans setup, weather data, data storage, instantaneous reports, pesticide information. Several upgrades. Compatibility with other brands.
FieldView™	The Climate Corporation	California, USA	Data connectivity and visualization, crop performance analysis, field health imagery. Offers VR ¹ prescriptions and fertility management based on models.
Granular	DowDuPont	California, USA	Different software according to necessities. Combination from several sources to build decision-making models. Advisory and training services. Support for more than 230 crop subspecies. Cloud-based.
KSAS	Kubota	Japan	Cloud-based agricultural management support service integrated by Kubota machinery. For smartphones and PC. Farm management by collecting and utilizing data from supported machinery.
Mapgrower	Agropreciso	Chile	Company-oriented platform that allows automated planning, work management, traceability, online statistics, account management, or visualization on maps. Available for smartphones.
Myeasyfarm	MyEasyFarm	France	Allows to define fields and their operations, plan season work and share it with a team, see real-time progress, and analyze results.
MyFarm Manager	Decisive Farming	Alberta, Canada	Mobile devices. Packages available for VRA ¹ , agronomy, and soil testing. Advice from experts. Marketing plans. Inventory and scheduled task in Cropvity application.
Phoenix	Agdata	Queensland Australia	It is modular so farmers can build their solution. Available in the cloud or desktop. Training provided. Farmers can create maps (.shp, .gpx, .kml, .bmp, and .jpg formats), add data, and update them.
PLMConnect	NewHolland	Italy	Enables connection with field machinery. Map and analysis of crop/soil data, yield performance, VR ¹ prescription, inventory and accounting records on supplies, seeds, chemicals, and fertilizer.
SSTsoftware	Proagrica	United Kingdom	Collect and manage data in the field. Statistical analysis reports, decision-making tools. PaaS ² (agX [®] Platform) for the ag industry providing geospatial infrastructure.
SMS	AgLeader	Iowa, USA	Soil sampling, grids and regions. Seed with higher yield potential can be chosen based on historic performance, reports, record operations, VRA ¹ maps, and prescriptions. Mobile app available.

Table 2.Cont.

Software	Company	Headquarters	Relevant Features
SpiderWeb GIS	Agrisat Iberia	Satellite Spain Data corresponding to each pixel can be downloaded in the form of temporary tables and graphs.	Allows consultation, management and analysis. images and other spatial reference layers.

memberstotheattendeesofafielddemonstrationin Portugal(October2019),evidencedthehighvaluegive ntographicaluserinterfaces(GUI).Considering that the prototype is in research phase and not commercial yet, 84% of the attendees concluded that the robot GUI shown in Figure4was simple to understand and easy to use (unpublished research). Rupnik et al. [89] developed a cloud-based system to allow growers upload their own data, utilize severaldataanalysismethods,andfinallypresenttheir outputsasdecisionstoapply.Thistime,their usecasefocusedonsprayplanningforfightingagainstpestsinvineyardsandorchards. Roseetal.[90] conductedasurveyonDSSandarrivedtotheconclusion that15factorswereinfluentialinconvincing UKgrowersandadviserstouseDSS,includingusability ,cost-effectiveness,performance,relevanceto user,andcompatibilitywithcompliancedemands.Inad

dition,theyfoundthat49%ofUKfarmersused some kind of DSS, and the preferred ways of delivery were software (28%), paper-based (22%) tools, and mobile apps (10%). These results show that the use of software to manage decisions is growing, but its percentage is still low and comparable to those who preferred paper-based tools. Choosing softwareandmobileapplicationstomakeagriculturaldecisionsmaybeconsideredbeneficialbecause digitaltoolsincrease managementefficiencywhencomparedtopaper-basedtools;however,thereis stillalongwaytomaketechnology-basedtoolsattractiveenough— easytounderstand,intuitiveand nice—for growers to adopt. On the producer side, it is important to have access to proper training until these technologies can be comfortablymanaged.



Figure 4. Graphical user interface (GUI) for the VineScout robot.

Stage V: Actuation through Variable Rate Technology

The last step for closing the loop in the complete crop management cycle of Figure 1 is the physical actuation on the crop. Actuation is understood as executing some action on the crop or related to it, and this can be done by making decisions right after obtaining information (real-time applications) or in another moment deferred in time (off-line). For farmers to execute decisions, they need advanced equipment that can receive orders from a computerized control unit. Variable rate machines can execute a number of farming tasks driven by a smart system [60]. Variable rate

technology (VRT) applied on site-specific crop management (SSCM) has the potential to increase profit and decrease environmental impact [61] as only what is needed is actually applied. Colaço and Molin [92] conducted a long-term study for six years with the goal of evaluating the effects of variable rate fertilization on fertilizer consumption, soil fertility, and yield in citrus. The outcomes of comparing variable and uniform rates showed that the former achieved higher yields while using less fertilizer: using nitrogen, fruit yield (kg of oranges) respect to the amount of fertilizer resulted in a 32% yield increase in field 1, and 38% in field 2. When using potassium, the yield increase even

reached 40% in field 1. In the case of phosphorus, the growth rate was approximately 20% for both fields. A recent review led by Nawar et al. [93] confirmed that, when management zone delineation techniques were used for variable-rate nutrient application, farm efficiency increased in all cases when compared to traditional uniform-rate applications, and environmental impacts were reduced. Machinery manufacturers are leading the development of commercial solutions implementing VRT. Thomasson et al. [62] described commercial VRT systems offered by major agricultural machinery manufacturers, like CLAAS, that used the ISARIA crop sensor for the variable-rate application of nitrogen-based fertilizer, or the CEBIS MOBILE ISOBUS, which, apart from having other Precision Agriculture functions, it is a compatible terminal to integrate the ISARIA sensor. Another promising type of variable actuation is automatic differential harvesting or variable rate harvesting (VRH), which attempts harvesting according to previously defined management zones. In specialty crops, Sethuramasamyraja[40]workedindifferentialharvestingforvineyardsbyusingnear-infraredsensors todeterminegrapequalityinthefieldbasedontheanthocyanincontentofberries.ThethreestepsforthisVRH system involved sensing the anthocyanin content of grapes, using these data to produce qualitymapbasedonathresholdanthocyaninlevel,and feedingthequalitymaptotheharvesterforits commanding.

CLAASwasawardedforimplementingVRHincombinationandforageharvesters[91]bymergingprecision sensing technology with autonomous machine control. The goal was to maximize productivityandautomaticallyoptimizeharvesterperformance,accordingtothechangingconditionsofthesoil,plants,grain,andhumidityintheharvestedfield.AUSDAstatisticalanalysisconductedin2010[3] showed that variable rate technologies had positive, but small, rate adoptions of 1% due to theirdifficultyofuse.Apartfromefficiencyandutility,costisalsoacriticalparametertoconsiderforthe adoption of this technology. In this sense, the ubiquitous availability of low-cost electronics will favortheintroductionofsuchdigitalapplications.Infact,advancesinautonomousdrivingtechnologyfor cars, including object detection capabilities through multi-camera systems, have already reduced the cost of developing automated agricultural machines[22].

II. DISCUSSION

After the Industrial Revolution, mainly since the advent of mechanization, and along the Green Revolution,humansandmachineshavebeenefficientl

ycollaboratingforgrowingcropstofeedpeople.

However, to face the population growth in the coming years, an extra effort is needed to succeed, not only in feeding people by increasing productivity, but also in doing it in the most efficient and respectfulpossibleway,that is,producing sustainably. To facethischallenge,remarkableadvancesintechnologyhavebeenappearingoverthelastdecades,in particulartheaccessstoreliableagricultural dataandadvancedcomputertechniques togettheoptimalmeaningfromthem,eventuallyobtaining maximumbenefitswhilebeingrespectfulwiththeenvironment.Thisnewapproachdrivenbydigital technologyimpliesthatgrowersmustactassupervisors oftheir cropsratherthanlaborers, inanattemptof avoiding repetitive, physically-demanding, and tedious field tasks. In this modern agronomical framework,DATAisthekey,andtheinformation-basedmanagementcycledescribedaboveprovides the practical approach that unites concept and tasks. The following points summarize some of the specific ideas drawn from thisstudy:

- Precision Agriculture, which consists of applying what is needed when and where is needed, has further improved the efficiency of managing farms with the addition of data-based digital systemsthatincrease theknowledgeofproducersabout theirfields;thisisknownasAgriculture 4.0 orDigital Farming. When these data-driven farms incorporate robotics with AI algorithms to their systems, the overall concept is then referred to as Agriculture 5.0. Some studies report that agricultural robots integrating forms of AI can do certain tasks faster than humans [23].Despite thereareotherstudies thatcontradictthisstatement[63], roboticsisagrowingeconomyandthere exists a great potential for many applications withinagriculture.
- A greater adoption of Digital Farming by professional growers is vital to not only improving a farm's financial performance, but also to meet the food needs of an expanding population [6]. Smallfarmswillsteadilyincorporatebasict technology whereaslargefieldswilllikelyinvestwith sophisticated equipment, but data-less intuition-driven management will no longer represent the modus operandi of professional farms in the future. This should be considered a source of opportunities, especially for a new generation of young farmers used to digital technology, who are the ones with the capacity to balance an aging population in rural areas, mainly those in industrializedcountries.
- After the rapid growth of UAVs, a steady-state is being reached, mostly induced by the factthat dataanalysisandground-truthvalidationhasresultedfarmorecomplexanddelicate thanimage

acquisition and platform handling. This has promoted the expansion of proximal sensing and the exploration of combining both data sources— aerial and terrestrial—for a better understanding of the physiology of plants and trees.

- Maps, as the most common way to represent agricultural data, would need to be standardized. Intensely-interpolated colored maps are output by GIS, FMIS, and other software applications, but at the time of comparing data with the precision agriculture to grant statistical significance, it often becomes an impossible mission without standardization. Figure 3, for example, uses the flat representation provided by the local tangent plane (LTP) and formatted in a regular grid. Other programs use UTM projections, and there are even images only given in geodetic coordinates. At the need of overlapping maps, it takes a big effort to make all data compatible. Not only the way coordinates are represented needs a standard, but also the units, intervals, and even colors in which parameters are displayed. The combination of aerial and ground data, for instance, will greatly benefit from such standardization in the way data is visually displayed for the average grower to understand.

- Table 2 provides a representative compilation of software applications for farm management. The list is not exhaustive, and yet includes companies from four continents and 14 countries, which provides evidence of the fact that agricultural digitalization is in fact a global move.

- Regarding variable rate applications, adoption rates need to augment, and to do so, farmers must find by themselves the value in this technology for their crops. Only after maintaining accurate spatial records and analyzing field data can effective variable rate prescriptions be created [39] to address particular tasks.

III. CONCLUSIONS

This analysis confirms that consistent knowledge about farms leads to optimal decisions. Agricultural management systems can handle farm data in such a way that results are orchestrated to address customized solutions for each farm. This aid for farmers in the form of digital solutions combines forces with robotics and artificial intelligence to launch the imminent idea of Agriculture 5.0. After thirty years of great expectations—and disappointments—by the application of robotics to agriculture, the timing seems right for the first time. However, in order to take the most advantages from Agriculture 5.0, deep training needs to be delivered to users, ideally young farmers eager to learn and apply modern technologies to agriculture and

granting a generational renewal still to come. It seems to be the right time to move forward towards a modern and sustainable agriculture that is capable of showing the full power of data-driven management to face the challenges posed to food production in the 21st Century. The evolution to Agriculture 5.0 is in the agenda of most major farm equipment makers for the next decade, and therefore off-road equipment manufacturers will play a key role in this move if agricultural robots are considered as the next—smarter—generation of farm machines.

REFERENCES

1. Himesh, S. Digital revolution and Big Data: A new revolution in agriculture. *CAB Rev.* **2018**, 13, 1–7. [CrossRef]
2. Zhang, Y. The Role of Precision Agriculture. *Resource* **2019**, 19, 9.
3. Schimmelpfennig, D. Farm Profits and Adoption of Precision Agriculture. *USDA* **2016**, 217, 1–46.
4. GrandView Research. Precision Farming Market Analysis. Estimates and Trend Analysis; GrandView Research Inc.: San Francisco, CA, USA, 2019; pp. 1–58.
5. Díez, C. Hacia una agricultura inteligente (Towards and intelligent Agriculture). *Cuaderno de Campo* **2017**, 60, 4–11.
6. Accenture Digital. Digital Agriculture: Improving Profitability. Available online: https://www.accenture.com/_acnmedia/accenture/conversion-assets/dotcom/documents/global/pdf/digital_3/accelture-digital-agriculture-point-of-view.pdf (accessed on 29 December 2019).
7. CEMA. Digital Farming: What Does It Really Mean? Available online: <http://www.cema-agri.org/publication/digital-farming-what-does-it-really-mean> (accessed on 17 September 2019).
8. Nierenberg, D. Agriculture Needs to Attract More Young People. Available online: <http://www.gainhealth.org/knowledge-centre/worlds-farmers-age-new-blood-needed> (accessed on 18 September 2019).
9. European Commission. Generational Renewal in EU Agriculture: Statistical Background; DG Agriculture & Rural Development: Economic analysis of EU agriculture unit: Brussels, Belgium, 2012; pp. 1–10.
10. Paneva, V. Generational Renewal. Available online: https://enrd.ec.europa.eu/enrd-thematic-work/generational-renewal_en (accessed on 28 December 2019).

11. AlphaBrown. What is IoT in Agriculture? Farmers Aren't Quite Sure Despite \$4bn US Opportunity—Report. Available online: <https://agfundernews.com/iot-agriculture-farmers-arent-quite-sure-despite-4bn-us-opportunity.html> (accessed on 28 December 2019).
12. Gralla, P. Precision Agriculture Yields Higher Profits, Lower Risks. Available online: <https://www.hpe.com/us/en/insights/articles/precision-agriculture-yields-higher-profits-lower-risks-1806.html> (accessed on 29 December 2019).
13. Tzounis, A.; Katsoulas, N.; Bartzanas, T.; Kittas, C. Internet of Things in agriculture, recent advances and future challenges. *Biosyst. Eng.* **2017**, 164, 31–48. [CrossRef]
14. Sarni, W.; Mariani, J.; Kaji, J. From Dirt to Data: The Second Green Revolution and IoT. Deloitte insights. Available online: <https://www2.deloitte.com/insights/us/en/deloitte-review/issue-18/second-green-revolution-and-internet-of-things.html#endnote-sup-9> (accessed on 18 September 2019).
15. Myklevy, M.; Doherty, P.; Makower, J. *The New Grand Strategy*; St. Martin's Press: New York, NY, USA, 2016; p. 271.
16. Manyica, J.; Chui, M.; Brown, B.; Bughin, J.; Dobbs, R.; Roxburgh, C.; Hung Byers, A. *Big Data: The Next Frontier for Innovation, Competition, and Productivity* | McKinsey. Available online: <https://www.mckinsey.com/business-functions/mckinsey-digital/our-insights/big-data-the-next-frontier-for-innovation> (accessed on 21 November 2019).
17. Kunisch, M. Big Data in Agriculture—Perspectives for a Service Organization. *Landtechnik* **2016**, 71, 1–3. [CrossRef]
18. Kamilaris, A.; Kartakoullis, A.; Prenafeta-Boldú, F.X. A review on the practice of big data analysis in agriculture. *Comput. Electron. Agric.* **2017**, 143, 23–37. [CrossRef]
19. Proagrica. How Big Data Will Change Agriculture. Available online: <https://proagrica.com/news/how-big-data-will-change-agriculture/> (accessed on 21 November 2019).
20. Wolfert, S.; Ge, L.; Verdouw, C.; Bogaardt, M.-J. Big Data in Smart Farming—A review. *Agric. Syst.* **2017**, 153, 69–80. [CrossRef]
21. CIAT & IFPRI. Big Data Coordination Platform. Proposal to the CGIAR Fund Council. Available online: <https://cgspace.cgiar.org/handle/10947/4303> (accessed on 17 September 2019).
22. Zambon, I.; Cecchini, M.; Egidi, G.; Saporito, M.G.; Colantoni, A. Revolution 4.0: Industry vs. Agriculture in a Future Development for SMEs. *Processes* **2019**, 7, 36. [CrossRef]
23. Walch, K. How AI Is Transforming Agriculture. Available online: <https://www.forbes.com/sites/cognitiveworld/2019/07/05/how-ai-is-transforming-agriculture/> (accessed on 1 January 2020).
24. Bechar, A.; Vigneault, C. Agricultural robots for field operations: Concepts and components. *Biosyst. Eng.* **2016**, 149, 94–111. [CrossRef]
25. Bechar, A.; Vigneault, C. Agricultural robots for field operations. Part 2: Operations and systems. *Biosyst. Eng.* **2017**, 153, 110–128. [CrossRef]
26. Bergerman, M.; Billingsley, J.; Reid, J.; van Henten, E. Robotics in Agriculture and Forestry. In *Springer Handbook of Robotics*; Siciliano, B., Khatib, O., Eds.; Springer Handbooks; Springer International Publishing: Cham, Switzerland, 2016; pp. 1463–1492. ISBN 978-3-319-32552-1.
27. Shamshiri, R.R.; Weltzien, C.; Hameed, I.A.; Yule, I.J.; Grift, T.E.; Balasundram, S.K.; Pitonakova, L.; Ahmad, D.; Chowdhary, G. Research and development in agricultural robotics: A perspective of digital farming. *Int. J. Agric. Biol. Eng.* **2018**, 11, 1–14. [CrossRef]
28. Reddy, N.; Reddy, A.; Kumar, J. A critical review on agricultural robots. *Int. J. Mech. Eng. Technol. (IJMET)* **2016**, 7, 6.
29. Lamborelle, A.; Fernández Álvarez, L. Farming 4.0: The Future of Agriculture? Available online: <https://www.euractiv.com/section/agriculture-food/infographic/farming-4-0-the-future-of-agriculture/> (accessed on 21 November 2019).
30. Sonka, S. Big Data and the Ag Sector: More than Lots of Numbers. *Int. Food Agribus. Manag. Rev.* **2014**, 17, 1–20.
31. CBINSIGHTS. Ag Tech Deal Activity More Than Triples. Available online: <https://www.cbinsights.com/research/agriculture-farm-tech-startup-funding-trends/> (accessed on 18 February 2019).
32. Verified Market Intelligence. *Global Agriculture eRobots Market Size, Status and Forecast to 2025*; Verified Market Intelligence Inc.: Boonton, NJ, USA, 2018; pp. 1–79.
33. Varadharajan, D. AI, Robotics, And the Future of Precision Agriculture. Available online: <https://www.cbinsights.com/research/ai-robotics->

- agriculture-tech-startups-future/ (accessed on 21 November 2019).
34. Murugesan,R.;Sudarsanam,S.K.;Malathi,G.; Vijayakumar,V.;Neelamarayanan,V.;Venugopal,R.;Rekha,D.; Summit, S.; Rahul, B.; Atishi, M.; et al. Artificial Intelligence and Agriculture 5. 0. Int. J. Recent Technol. Eng. (IJRTE) **2019**, 8,8.
35. Zhang,Q.PrecisionAgricultureTechnologyfor CropFarming, 1sted.;CRCPressand Taylor&FrancisGroup: Boca Raton, FL, USA, 2015; ISBN978-1-4822-5107-4.
36. Rovira-Más, F. (Coordinator). VineScout European Project. Available online:www.vinescout.eu(accessed on 21 November2019).
37. Searcy, S.W. Precision Farming: A New Approach toCrop Management. Availableonline:http://agpublications.tamu.edu/pubs/eng/15177.pdf(accessed on 21 November 2019).
38. Zhang,N.;Wang,M.;Wang,N.Precisionagricul ture— Aworldwideoverview.Comput.Electron.Agri c. **2002**,36, 113–132. [CrossRef]
39. Brasse, T.Precision Agriculture, 1st ed.; Thomson Delmar Learning: Clifton Park, NY, USA, 2006; ISBN1-4018-8105-X.
40. Sethuramasamyraja,B.PrecisionAgResearch atCaliforniaStateUniversity,Fresno.Resource **2017**,24,18–19.
41. Miao,Y.;Mulla,D.J.;Robert,P.C.Anintegrated approachtosite-specificmanagementzonedelineation.Front. Agric. Sci. Eng. **2018**, 5, 432–441. [CrossRef]
42. Klassen,S.P.;Villa,J.;Adamchuk,V.;Serraj,R. Soilmappingforimprovedphenotypingofdrou ghtresistance in lowland rice fields. Field Crops Res. **2014**, 167, 112–118.[CrossRef]
43. Buttafuoco,G.;Lucà,F.TheContributionofGeo statisticstoPrecisionAgriculture.Ann.Agric.C ropSci.**2016**, 1, 1008–1009.
44. Khanal,S.;Fulton,J.;Shearer,S.Anoverviewof currentandpotentialapplicationsofthermalrem otesensing in precision agriculture. Comput. Electron. Agric. **2017**, 139, 22–32.[CrossRef]
45. Rudd,J.D.;Roberson,G.T.;Classen,J.J.Applic ationofsatellite,unmannedaircraftsystem,and ground-based sensor data for precision agriculture: A review. In Proceedings of the 2017 ASABE Annual International Meeting; American Society of Agricultural and Biological Engineers, Spokane, WA, USA, 16–19 July 2017.
46. Liebisch, F.; Pfeifer, J.; Khanna, R.; Lottes, P.; Stachniss, C.; Falck, T.; Sander, S.; Siegwart, R.; Walter, A.; Galceran, E. Flourish—A robotic approach for automation in crop management. In Proceedings of the 22 Workshop Computer-Bildanalyse und UnbemannteautonomfliegendeSysteme in der Landwirtschaft,Postdam, Germany, 27 April 2017; pp.1–11.
47. Lameski,P.;Zdravevski,E.;Kulakov,A.Revie wofAutomatedWeedControlApproaches:An Environmental Impact Perspective. In Proceedings of the ICT Innovations 2018 Engineering and Life Sciences; Kalajdziski, S.,Ackovska, N., Eds.; Springer International Publishing: Cham, Switzerland, 2018; pp. 132–147.
48. Aravind, K.R.; Raja, P.; Pérez-Ruiz, M. Task-based agricultural mobile robots in arable farming: Areview.Span. J. Agric. Res. **2017**, 15, 1–16. [CrossRef]
49. Roldán,J.J.;delCerro,J.;Garzón-Ramos,D.;Garcia-Aunon,P.;Garzón,M.;deLeón,J.;Barrientos,A .Robots inAgriculture: StateofArtandPracticalExperiences.InServic eRobots;Neves,A.J.R.,Ed.;IntechOpen:Rijek a, Croatia, 2017. [CrossRef]
50. Gonzalez-de-Santos, P.; Ribeiro, A.; Fernandez-Quintanilla, C.; Lopez-Granados, F.; Brandstoetter, M.; Tomic, S.; Pedrazzi, S.; Peruzzi, A.; Pajares, G.; Kaplanis, G.; et al. Fleets of robots for environmentally-safe pest control in agriculture. Precis. Agric. **2017**, 18, 574–614.[CrossRef]
51. Tobe,F.What’sSlowingtheUseofRobotsinthe AgIndustry?Availableonline:https://www.th erobotreport.com/whats-slowng-the-use-of- robots-in-the-ag-industry/ (accessed on 21 November2019).
52. Bogue, R. Robots poised to revolutionise agriculture. Ind. Robot **2016**, 43, 450–456.[CrossRef]
53. Diago, M.P.; Rovira-Más, F.; Saiz-Rubio, V.; Faenzi, E.; Evain, S.; Ben Ghazlen, N.; Labails, S.; Stoll, M.; Scheidweiler,M.;Millot,C.;etal.The“eyes”oft heVineRobot:Non-destructiveandautonomousvineyardmonit ori ng on-the-go. In Proceedings of the 62nd German Winegrowers’ Congress, Stuttgart, Germany, 27–30 November 2016.
54. Saiz-Rubio, V.; Diago,M.;Rovira-Más,F.;Cuenca,A.;Gutiérrez,S.;Tardáguila,J. Physicalrequirementsfor vineyardmonitoringrobots.InProceedingsofth eXIXWorldCongressofCIGR,Antalya,Turkey ,22–25April 2018; pp. 1–4.
55. NãioTechnologies.Features&BenefitsOZWe

- edingRobot. Available online: <https://www.naiotechnology.com/en/agricultural-equipment/weeding-robot-oz/> (accessed on 21 November 2019).
56. Thomson, G. The global unmanned spraysystem(GUSS). *Resource* **2019**, 26,9–10.
57. Cavender-Bares, K.; Lofgren, J.B. Robotic Platform and Method for Performing Multiple Functions in Agricultural Systems. U.S. Patent US9265187B2, 23 February 2016.
58. Hameed, I.A. A Coverage Planner for Multi-Robot Systems in Agriculture. In Proceedings of the IEEE International Conference on Real-time Computing and Robotics (RCAR), Kandima, Maldives, 1–5 August 2018; pp.698–704.
59. Ball, D.; Ross, P.; English, A.; Patten, T.; Upcroft, B.; Fitch, R. Robotics for Sustainable Broad-Acre Agriculture. Available online: https://www.researchgate.net/publication/283722961_Robotics_for_Sustainable_Broad-Acre_Agriculture (accessed on 21 November 2019).
60. Tobe, F. The Ultimate Guide to Agricultural Robotics. Available online: https://www.roboticsbusinessreview.com/agriculture/the_ultimate_guide_to_agricultural_robotics/ (accessed on 21 November 2019).
61. Kweon, G.; Lund, E.; Maxton, C. Soil organic matter and cation-exchange capacity sensing with on-the-go electrical conductivity and optical sensors. *Geoderma* **2013**, 199, 80–89. [CrossRef]
62. Thomasson, A.; Baillie, C.; Antile, D.; Lobsey, C.; McCarthy, C. Autonomous Technologies in Agricultural Equipment: A Review of the State of the Art. In Proceedings of the 2019 Agricultural Equipment Technology Conference, Louisville, KY, USA, 11–13 February 2019; American Society of Agricultural and Biological Engineers: St. Joseph, MI, USA, 2019. ASABE Publication Number 913C0119.
63. Sennaar, K. Agricultural Robots—Present and Future Applications (Videos Included). Available online: <https://emerj.com/ai-sector-overviews/agricultural-robots-present-future-applications/> (accessed on 1 January 2020).
64. Köksal, Ö.; Tekinerdogan, B. Architecture design approach for IoT-based farm management information systems. *Precis. Agric.* **2019**, 20, 926–958. [CrossRef]
65. Rovira-Más, F.; Saiz-Rubio, V. Crop Biometric Maps: The Key to Prediction. *Sensors* **2013**, 13, 12698–12743. [CrossRef]
66. Oliver, M.; Webster, R. A tutorial guide to Geostatistics: Computing and modelling variograms and kriging. *Catena* **2014**, 113, 56–69. [CrossRef]
67. Saiz-Rubio, V.; Rovira-Más, F. Proximal sensing mapping method to generate field maps in vineyards. *Agric. Eng. Int. CIGR J.* **2013**, 15, 47–59.
68. Adamchuk, V.I.; Hummel, J.W.; Morgan, M.T.; Upadhyaya, S.K. On-the-go soil sensors for precision agriculture. *Comput. Electron. Agric.* **2004**, 44, 71–91. [CrossRef]
69. Cossell, S.; Whitty, M.; Liu, S.; Tang, J. Spatial Map Generation from Low Cost Ground Vehicle Mounted Monocular Camera. *IFAC Papers On Line* **2016**, 49, 231–236. [CrossRef]
70. Zhang, N.; Taylor, R.K. Applications of a Field-Level Geographic Information System (FIS) in Precision Agriculture. *Appl. Eng. Agric.* **2001**, 17, 885–892. [CrossRef]
71. Runquist, S.; Zhang, N.; Taylor, R.K. Development of a field-level geographic information system. *Comput. Electron. Agric.* **2001**, 31, 201–209. [CrossRef]
72. Burlacu, G.; Costa, R.; Sarraipa, J.; Jardim-Golcalves, R.; Popescu, D. A Conceptual Model of Farm Management Information System for Decision Support. In Proceedings of the Technological Innovation for Collective Awareness Systems; Camarinha-Matos, L.M., Barrento, N.S., Mendonça, R., Eds.; Springer: Berlin/Heidelberg, Germany, 2014; pp.47–54.
73. Schmaltz, R.; Coolidge, M.; Donald, G. Agricultural Enterprise Management Method and System. Canada Patent CA2967518A1, 11 May 2017.
74. Coolidge, M.; Schmaltz, R.; Schmaltz, T. Crop Management Method and System. U.S. Patent WO/2018/187870, 4 October 2018.
75. Wilbur, M.; Ellsworth, J.; Oommen, T.; Mohapatra, A.; Thayer, D. Systems and Methods for Cloud-Based Agricultural Data Processing and Management. U.S. Patent US9667710B2, 30 May 2017.
76. Granular Farm Management Software, Precision Agriculture, Agricultural Software. Available online: <https://granular.ag/> (accessed on 21 March 2019).
77. Ruland, S. AgGateway's Agricultural Data Application Programming Toolkit (ADAPT). *Resource* **2019**, July/August 2019.
78. Capterra Inc. Capterra. Farm Management Software. Available online: www.capterra.com (accessed on 21

- March2019).
79. PAT RESEARCH. Top 9 Farm Management Software—Compare Reviews, Features, Pricing in 2019. Availableonline:<https://www.predictiveanalyticstoday.com/top-farm-management-software/>(accessedon 21 November2019).
80. Srivastava, P.K.; Singh, R.M. GIS based integrated modelling framework for agricultural canal system simulation and management in Indo-Gangetic plains of India. *Agric. Water Manag.* **2016**, 163, 37–47. [CrossRef]
81. Giusti, E.; Marsili-Libelli, S. A Fuzzy Decision Support System for irrigation and water conservation in agriculture. *Environ. Model. Softw.* **2015**, 63,73–86. [CrossRef]
82. Drenjanac, D.; Tomic, S.; Hinterhofer, T. User interactions and network monitoring eased decision-making in a robotic fleet for Precision Agriculture. In Proceedings of the Second International Conference on Robotics and Associated High-technologies and Equipment for Agriculture and Forestry (RHEA2014), Madrid, Spain, 21–23 May2014.
83. Asfaw, D.; Black, E.; Brown, M.; Nicklin, K.J.; Otu-Larbi, F.; Pinnington, E.; Challinor, A.; Maidment, R.; Quaife, T. TAMSAT-ALERT v1: A new framework for agricultural decision support. *Geosci. Model Dev.* **2018**, 11, 2353–2371. [CrossRef]
84. Hoogenboom, G.; Porter, C.H.; Shelia, V.; Boote, K.J.; Singh, U.; White, J.W.; Hunt, L.A.; Ogoshi, R.; Lizaso, J.; Koo, J.; et al. Decision Support System for Agrotechnology Transfer (DSSAT) Version 4.7.5; DSSAT Foundation: Gainesville, FL, USA. Available online:<https://dssat.net>(accessed on 1 January2020).
85. Rupp, C.E.; Kull, A.C.S.; Pitstick, S.R.; Dumstorff, P.L. Generating an Agriculture Prescription. U.S. Patent US9974226B2, 22 May2018.
86. Lindores, R.J. Generating a Crop Recommendation. U.S. Patent US20140012732A1, 9 January2014.
87. Navarro-Hellín, H.; Martínez-del-Rincon, J.; Domingo-Miguel, R.; Soto-Valles, F.; Torres-Sánchez, R. A decision support system for managing irrigation in agriculture. *Comput. Electron. Agric.* **2016**, 124,121–131.[CrossRef]
88. Kumar, A.; Sah, B.; Singh, A.R.; Deng, Y.; He, X.; Kumar, P.; Bansal, R.C. A review of multi criteria decision making (MCDM) towards sustainable renewable energy development. *Renew. Sustain. Energy Rev.* **2017**,69, 596–609.[CrossRef]
89. Rupnik, R.; Kukar, M.; Vračar, P.; Košir, D.; Pevec, D.; Bosnić, Z. AgroDSS: A decision support system for agriculture and farming. *Comput. Electron. Agric.* **2019**, 161, 260–271.[CrossRef]
90. Rose, D.C.; Sutherland, W.J.; Parker, C.; Lobley, M.; Winter, M.; Morris, C.; Twining, S.; Ffoulkes, C.; Amano, T.; Dicks, L.V. Decision support tools for agriculture: Towards effective design and delivery. *Agric. Syst.* **2016**,149, 165–174.[CrossRef]
91. ASABE AE50 Awards. *Resour. Eng. Technol. Sustain. World* **2019**, 19,4–16.
92. Colaço, A.F.; Molin, J.P. Variable rate fertilization in citrus: A long term study. *Precis. Agric.* **2017**, 18,169–191. [CrossRef]
93. Nawar, S.; Corstanje, R.; Halcro, G.; Mulla, D.; Mouazen, A.M. Delineation of Soil Management Zones for Variable-Rate Fertilization. *Adv. Agron.* **2017**, 143, 175–245.[CrossRef]
94. Saiz-Rubio, V.; Rovira-Más, F. VineScout_ROBOT data_22July2019_TN102. Zenodo **2019**. [CrossRef]
95. Fountas, S.; Carli, G.; Sørensen, C.G.; Tsiropoulos, Z.; Cavalari, C.; Vatsanidou, A.; Liakos, B.; Canavari, M.; Wiebenson, J.; Tisserye, B. Farm management information systems: Current situation and future perspectives. *Comput. Electron. Agric.* **2015**, 115, 40–50. [CrossRef]
96. Kritikos, M. Precision Agriculture in Europe: Legal, Social and Ethical Considerations—Think Tank. Available online:[http://www.europarl.europa.eu/thinktank/en/document.html?reference=EPRS_STU\(2017\)603207](http://www.europarl.europa.eu/thinktank/en/document.html?reference=EPRS_STU(2017)603207) (accessed on 21 November2019).