Enhanced Performance of Matrix Converter using Adaptive Computing Techniques

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ABSTRACT
This paper deals mainly with the improvement of linear load current profile considering different grid conditions. A popular power conversion circuit known to be a Matrix Converter was considered to study the effects on the quality of electrical power supply. This advanced converter configured with power semiconductor devices effectively optimizes the harmonic components of linear type loads with the aid of various controllers like PI, Fuzzy, Adaptive Fuzzy and ANFIS models. The simulation studies and subsequent comparisons are derived for the proposed system on MATLAB/SIMULINK package under balanced and distorted grid conditions.

Keywords: Power Quality, Matrix Converter, Venturini Modulation, Adaptive Fuzzy Controller, ANFIS, Linear Load, Total Harmonic Distortion, Balanced grid, Distorted grid.

I. INTRODUCTION
Due to subsequent developments in the field of power semiconductor technology adaptability of the electrical power system to the dynamic load requirements is enhanced. Frequent variations on the supply and load side affect the parameters like service continuity, frequency, transient voltages and currents. Power conversion methods provide an optimal solution to ensure a proper and efficient operation of the electrical system. In the late 1970’s Gyugyi proposed a direct ac-ac frequency converter. Thereafter Static power frequency converters were considered of which indirect ac-ac converter with PWM-VSI became predominant. Due to the uncontrolled action of diode bridge rectifier in the converter, the currents on the input side contain harmonics which creates distortion in the input line voltages [1].

Later a high frequency based matrix converter operated with ideal transformer was presented by Venturini [2]. Subsequently Venturini modulated matrix converter configured using classical PI controller was introduced to minimize the effects of the distorted input line voltages [7]. Further to enhance the matrix converter efficiency a good compensated Fuzzy system based controller was proposed [8]. Then a PI based Fuzzy controller was implemented to mitigate the harmonic effects produced by different non-linear loads [9].

In this paper, the operational ability of the Matrix converter is observed with linear load for undistorted grid and distorted grid cases. Various controller models like PI, Fuzzy, Adaptive Fuzzy and ANFIS were applied to the proposed model. The effective operation of Matrix converter is assessed by observing the linear load current waveform with minimum harmonic content.

II. OPERATION AND MODULATION OF MATRIX CONVERTER

2.1 Operating Principle
Basically the circuit of a matrix converter comprises of one level converter arranged with an array of m × n bilateral power semiconductor switches to connect, directly, an m-phase voltage supply to n-phase linear load.

![Fig 2.1. Circuit of Matrix Converter](image)

From the above circuit diagram the matrix converter consists of the supply voltages, supply currents and the output load voltages w.r.t the neutral point of the load. Each switch $s_{pq}(t)$, $p = \{A, B, C\}$ and $q = \{a, b, c\}$ can connect or disconnect phase $p$ of the input side to phase $q$ of the load side and, with possible combination of the conduction periods of these switches, output voltages $v_{pq}$ can be calculated.
Each switch is described by a switching model, defined as:

\[ S_{pq}(t) = 0 \text{ if } S_{pq} \text{ is in open condition} \]
\[ S_{pq}(t) = 1 \text{ if } S_{pq} \text{ is in closed condition} \]

\[ S_{Ap} + S_{Bq} + S_{Cq} = 1 \text{ where } p = A, B, C \text{ and } q = a, b, c \]

To implement the modulation schemes the following equations (3) and (4) are significant. These equations describe the possible switching combination of open and closed switches to produce the required output load voltages.

\[ \begin{bmatrix}
    v_{a1}(t) \\
    v_{b1}(t) \\
    v_{c1}(t)
\end{bmatrix} =
\begin{bmatrix}
    S_{Aa}(t) & S_{Bb}(t) & S_{Cc}(t) \\
    S_{Ab}(t) & S_{Bb}(t) & S_{Cc}(t) \\
    S_{Ac}(t) & S_{Bb}(t) & S_{Cc}(t)
\end{bmatrix}
\begin{bmatrix}
    v_{a}(t) \\
    v_{b}(t) \\
    v_{c}(t)
\end{bmatrix} \quad (3)
\]

\[ \begin{bmatrix}
    i_{a1}(t) \\
    i_{b1}(t) \\
    i_{c1}(t)
\end{bmatrix} =
\begin{bmatrix}
    S_{Aa}(t) & S_{Bb}(t) & S_{Cc}(t) \\
    S_{Ab}(t) & S_{Bb}(t) & S_{Cc}(t) \\
    S_{Ac}(t) & S_{Bb}(t) & S_{Cc}(t)
\end{bmatrix}
\begin{bmatrix}
    i_{a}(t) \\
    i_{b}(t) \\
    i_{c}(t)
\end{bmatrix} \quad (4)
\]

The input source currents are represented by a filter model with an array of switched input currents. This model is derived on the assumption that \( V_{op} = V_{p} \) which stands important for implementing modulation schemes.

2.2 Venturini Modulation Method

Among the available modulation techniques, Venturini modulation method is implemented for the matrix converter. This modulation scheme provides the simple synthesis of low frequency components of output load voltages and input source currents with instantaneous magnitudes of input source voltages and output load currents respectively. The modulation algorithm represented is suitable for real time implementation but in practice it is not used due to the 50% voltage transfer ratio limitation [1].

III. CONFIGURABLE CONTROLLERS

3.1 PI Controller

A Closed loop arrangement of matrix converter using PI controller is presented in Figure 3.1. The momentary magnitude of the error can be determined from the differences observed between the instantaneous current-space-vector \( I \) which is sensed by the measured 3-udgets of the matrix converter and the reference current-space-vector \( I_{ref} \).

3.2 Fuzzy Logic Controller

A fuzzy logic controller based feedback system for a matrix converter is shown in Fig. 3.2. In this model also the error term can be calculated by considering the measured \( I \) and the reference-current-space-vector \( I_{ref} \).

3.3 Adaptive Fuzzy Controller

Based on the working abilities and control features of matrix converter, an Adaptive Fuzzy control technique is developed and represented in Figure 3.3.
A traditional PI controller is used in combination with a fuzzy logic control system. From the obtained error signal and its time derivative, the fuzzy system adapts continuously the suitable parameters of the PI controller to extract the better operational features [9]. For the fuzzy controller system the error and its derivative are considered as the input quantities. The corrected instantaneous error $e(t)$ can be determined from the resultant of measured current value and its reference value.

3.4 ANFIS controller

ANFIS controller is basically a hybrid computing model comprising a suitable kind of artificial neural network which is based on T-S fuzzy inference method. This model introduced in the early decade of 1990s is able to provide good solutions for most of the non-linear systems. In this model the inference engine represent to a suitable set of fuzzy if-then rule which have adaptive learning capability in optimizing the nonlinear system models [11].

IV. SIMULATION AND RESULTS

Adaptive fuzzy controller is a hybrid controller which incorporates the features of both PI and fuzzy logic controllers [9] & [10]. The simulink model of adaptive fuzzy controller is shown below.
V. CONCLUSION

In order to observe the effective operation and modulation schemes of the matrix converter, various control methods like PI, Fuzzy, Adaptive Fuzzy and ANFIS are duly implemented using MATLAB/SIMULINK tool. The simulation results display the linear load current profile when these control methods are used during distorted and undistorted grid cases along with its THD values shown in Table 1. From the obtained results conclusions can be drawn towards ANFIS controller for its better performance as it significantly improves the nature of linear load currents when compared to all other methods.

REFERENCES


