## RESEARCH ARTICLE

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# A Multi-Objective Ant Colony System Algorithm for Virtual Machine Placement

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## ABSTRACT

Virtual machine placement is a process of mapping virtual machines to physical machines. The optimal placement is important for improving power efficiency and resource utilization in a cloud computing environment. In this paper, we propose a multi-objective ant colony system algorithm for the virtual machine placement problem. The goal is to efficiently obtain a set of non-dominated solutions (the Pareto set) that simultaneously minimize total resource wastage and power consumption. The proposed algorithm is tested with some instances from the literature. Its solution performance is compared to that of an existing algorithm. The results show that the proposed algorithm is more efficient and effective than the methods we compared it to.

### I. INTRODUCTION

In the case of ACO algorithms the theoretical analyses of their runtime behavior has been started only recently. We increase the theoretical understanding of ACO algorithms by investigating their runtime behavior on the wellknown traveling salesperson (TSP) problem. For ACO the TSP problem is the first problem where this kind of algorithms has been applied. Therefore, it seems to be natural to study the behavior of ACO algorithms for the TSP problem from a theoretical point of view in a rigorous manner. ACO algorithms are inspired by the behavior of ants to search for a shortest path between their nest and a common source of food. It has been observed that ants find such a path very quickly by using indirect communication via pheromones. This observed behavior is put into an algorithmic framework by considering artificial ants that construct solutions for a given problem by carrying out random walks on a so-called construction graph. The random walk (and the resulting solution) depends on pheromone values that are values on the edges of the construction graph.

#### II. ANT COLONY SYSTEM

Ant is a small insect that live in colonies in/on the ground. Ants explore their area surrounding the nest for food in random manner. While searching the food, ant leaves chemical materials called pheromone. Ant can smell these pheromones. While choosing the path, they tend to choose the path which contains strong pheromones concentration and this path chosen by ants on the bases of probability. When an ant finds the food source, it evaluates the food quality and quantity and carries some food with it and return to its nest. During coming back to the nest, the quantity of pheromones it leaves on the ground is depends on the quality and quantity of food. Pheromones trials guide other ant to find the food source. The communication of the ants via pheromones trail finds the shortest path between the nest and food source.

Ant colony optimization algorithm is now used to solve the numerous optimization problems like TSP (Traveling Salesman Problem), FSSP (Flow Shop Scheduling Problem) etc. some extension of ACO algorithm proposed in literature like Ant System, ACS and MMAS etc.

The system works as: in initialization phase, all parameters are initialized and pheromones trial is set to  $\tau_0$ . In next Iterative part each ant receives the request from all the VMs and then assigning VMs to physical server. Assigning the VM.s to physical server is based on pseudorandom proportional rule which is used by ant to choose the particular VM as the next one to fit into the current physical server. This rule is made on the bases of the information of current pheromone concentration level while movement of ant and this guide the ant to choose the most appropriate VM. There are two updates are performed. First is local update. Local update is performed once an ant has built movement. Second is global update. Global update is performed with current Pareto set when ants constructed their solutions.

There are 3 point which differ the algorithms are:

## 1. Pheromone updates:

There are two strategies; first strategy is to select the iteration-best, or a best-so-far solution to update the pheromone matrices, second strategy is to collect and store the non-dominated solutions in an external set. Only the solutions in the nondominated set are allowed to update the pheromones.

#### 2. Definition of pheromones and heuristic information:

There are two approaches to define heuristic/pheromones information first is using one matrix and second is multiple matrixes.

#### 3. Pheromone and heuristic aggregation:

When multiple matrices are used then some aggregation rule should be used to combine multiple pheromones matrices

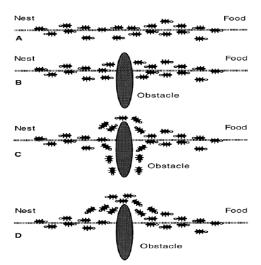


Fig.1: how real ant finds the shortest path

#### 2.2.1 MMAS (Min-Max Ant System):

MMAS is also based on the ant colony system. It based on the search paradigm that is applicable for the solution of optimization problem. It is an improved version of ant system. In ant system the disadvantage is that stagnation of search makes tour improvement impossible. When stagnation occurs, the trials on few edges grow so fast that ants always choose the same path again and again. So MMAS allows best ants to update the trails. In MMAS minimum and maximum trial strength are introduced explicitly and it is depends on the average path length. It also provides local search heuristic. There are two ways to allow an ant to perform local search, first is that to allow all ants to perform local search and second is to iterationbest.

So in MMAS ant system with local search provides an adaptive framework for the solution of optimization problems.

In virtual machine placement, many of the research focus on the single objective criterion. But in real-world single objective does not provide full optimization, so in recent real-world application multi-objective criterion is used for optimization of computing resources wastage and power consumption. Ant colony system algorithm used for this purpose.

#### 2.2.3 Ant Colony Algorithm for virtual machine placement:

/\* Initialization \*/

Set the value of parameter  $\alpha$ ,  $q_0$ ,  $\rho_l$ ,  $\rho_g$ ,  $\tau_0$ , 1. NA (number of ants) and M (number of iteration).

- Initialize Pareto set P as empty. 2.
- Initialize all pheromone values to  $\tau_0$ . 3.
- /\*Iterative loop\*/
- 4. Repeat
- 5. For j=1 to NA do
  - /\*construct a solution\*/
- 6. Sort the server list PL in random order
- 7. Repeat
- 8. Introduce new server from server list PL
- 9 Repeat

10. For each remaining VM that can be packed in to the current server do

Calculate desirability of movement acc. 11. to Eq.  $n_{i}$ ,  $j = n_{i}$ ,  $j, 1 + n_{i}$ , j, 2

Calculate probability of movement acc. to 12. Eq.  $\sim$ 

$$P^{k}_{i,j} = \begin{cases} \frac{\alpha \times \tau_{i,j} + (1 - \alpha) \times \eta_{i,j}}{u \in \Omega_{k}(j)(\alpha \times \tau_{u}, j + (1 - \alpha) \times \eta_{u,j}), i \in \Omega_{k}(j)} \end{cases}$$

	0, otherwise
13.	End For
	/*choice of the VM to assign*/
14.	Draw q
15.	If $q \le q_0$ then
16.	Exploitation
17.	Else
18.	Exp loration
10	

- 19. End If
  - /\*Local pheromones updating\*/
- 20. Apply local updating rule :  $\tau_{i,i}(t) =$  $(1-\rho_l)\tau_{i,\,i}(t-1)+\rho_l\cdot\,\tau_0$

Until no remaining VM fits in the server 21. anymore

- 22. Until all VM are placed
- 23. End For
- /\*evaluation\*/

Calculate the value of two objective for 24. each solution in current ant population

If a solution in current ant population is 25. not dominated by any other solutions in the current population and non-dominated solutions in the Pareto set P, this solution is added to the set P.

/\*global pheromones updating\*/

26. For each non-dominated solutions in the Pareto set P do

27. Apply global updating rule:

$$\tau_{i,j}(t) = (1 - \rho_g)\tau_{i,j}(t - 1) + \rho_g \cdot \lambda$$

- 28. End For
- 29. Until the maximum number of iteration is reached
- 30. Return the Pareto set P

P'(S) + W(S)

## III. CONCLUSION

The ant colony optimisation algorithm was extensively compared with the multi-objective genetic algorithm. The combined implementation of both the algorithms fetches a more optimal result. The proposed algorithm when tested with literature instances proved to be more efficient in VM placement thereby reducing the resource wastage and reducing the power consumption of the servers.

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