

Comparison on Different Domino Logic Design for High-Performance and Leakage-Tolerant Wide OR Gate

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ABSTRACT

- Dynamic logic circuits are used for high performance and high speed applications. Wide OR gates are used in Dynamic RAMs, Static RAMs, high speed processors and other high speed circuits. In spite of their high performance, dynamic logic circuit has high noise and extensive leakage which has caused problems for the circuits. To overcome these problems Domino logic circuits are used which reduce sub-threshold leakage current in standby mode and improve noise immunity for wide OR gates. In this paper we analyze and compare different domino logic design topologies for lowering the sub-threshold leakage current in standby mode, increasing the speed and increasing the noise immunity. We compare power, delay, and unit noise gain (UNG) of different topologies. The simulation results revealed that High Speed Clock Delay Domino (HSCD) circuit gives the better results in terms of reduction in delay and power consumption as compare to other circuits.

Keywords - Wide domino circuit, sub-threshold leakage current, delay, noise immunity.

I. INTRODUCTION

In comparison to static CMOS circuits, dynamic CMOS circuits have a large number of advantages such as lower number of transistors, low-power, higher speed, short-circuit power free and glitch-free operation. Because of these properties, high performance systems are realized using dynamic CMOS circuits. The main limitations of dynamic logic are cascading and charge sharing. To overcome these problem domino circuits are use. In addition to dynamic logic an inverter and a weak pMOS pull-Up keeper transistor (with a small (W/L) ratio) is added to the dynamic CMOS output stage in domino logic. Inverter is use to avoid cascading problem and to avoid charge sharing problem weak keeper is used, which essentially forces high output level unless there is a strong pull-down path between the output and the ground.

Wide fan-in domino circuits [1] are used to design high performance register files, ALU front ends, and priority encoders in content addressable memories. Wide domino logic refers to domino logic gates with N parallel pull down branches when N is greater then 4; that are used to design circuits in microprocessor critical path. By scaling down the technology the sensitivity of the dynamic node to the noise sources has emerged as a serious design challenge. For improving noise immunity and reducing leakage the keeper transistor is added. However, power dissipation increases and

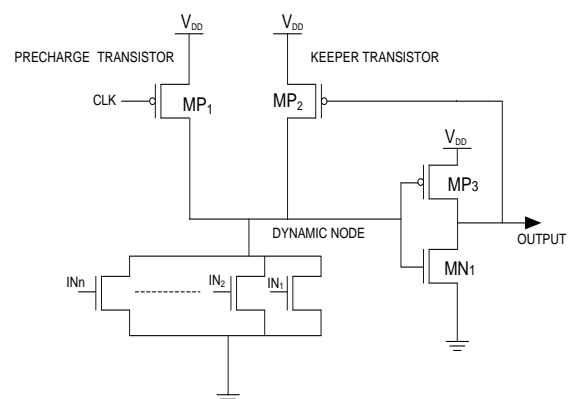


Fig.1 Standard Footerless Domino Logic Circuit

performance degrades by adding this pMOS keeper transistor. Upsizing the keeper transistor improves robustness at a cost of higher power dissipation and delay. The severity increases many fold in wide Domino circuits because of higher number of parallel pull-down branches [2]. Therefore small size keeper is desired for high-speed applications while to increase the robustness, larger keeper is required. Thus, trade off exist between delay and power to improve noise and leakage immunity [3]. Such trade-off is not acceptable because it may increase the delay or make the circuit too power hungry. There are several techniques introduce in the paper to address this issue.

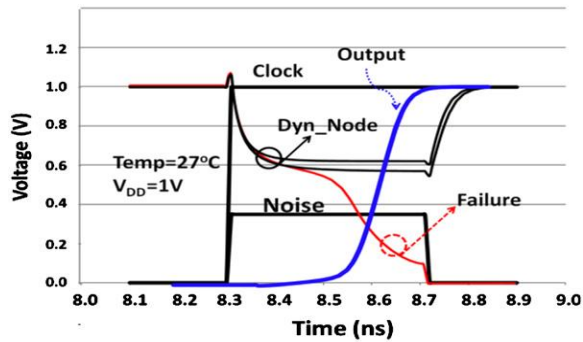


Fig. 2 Failure mechanism for 16-in OR gate (FLDL)

The rest of the paper is arranged as follows. Section II, studies five types of circuits that have been proposed in related literatures, standard footless domino logic, standard footed domino logic, conditional keeper domino logic, high speed domino logic, split domino logic and high speed clock delay domino logic. Simulation results of different methods and compare in section II. Conclusion in section III.

II. PREVIOUS TECHNIQUE

A. Standard Footless Domino Logic Circuit (SFLDL)

The footless scheme [4] is characterized by the fact that discharge of dynamic node is faster. This property is exploited by the high-performance circuits. The circuit of the SFLD logic is shown in Fig1. Operation of Footless-Domino is as follows: During the pre-charge phase, i.e. when then clock (CLK) is LOW, the dynamic node is charged to V_{DD} and the keeper transistor MP_2 turns ON to maintain the voltage of the dynamic node. During the evaluation mode, i.e. when the CLK goes HIGH, the dynamic node is either discharged to ground or remains HIGH depending on the inputs. The size of the keeper transistor should be large enough to compensate for charge sharing problem and at the same time it should be small enough to reduce the contention between the keeper and the nMOS pull down transistor in the case the pull down network evaluates the dynamic node to logic level zero. Otherwise, the pull down network and keeper transistor compete to drive the dynamic node to two opposite directions, this effect is called contention and this results in the degradation of speed.

B. Standard Footed Domino Logic Circuit (SFDL)

The footer nMOS transistor MN_2 is connected to the source of evaluation nMOS transistor to obtain the FDL [5] design which basically reduces the leakage current. The speed the SFDL is lower than the footless one because of the stacking effect, but the noise immunity is higher. Fig.3 shows the most conventional footed domino logic circuit. When clock is low, the dynamic node is pre-charged to V_{DD} [7]. In this phase the footed transistor MN_2 is turned off, which reduces the leakage current. When clock goes high, footer transistor MN_2 is turned on. So,

depending on incoming data to pull-down network the state of output node is obtained.

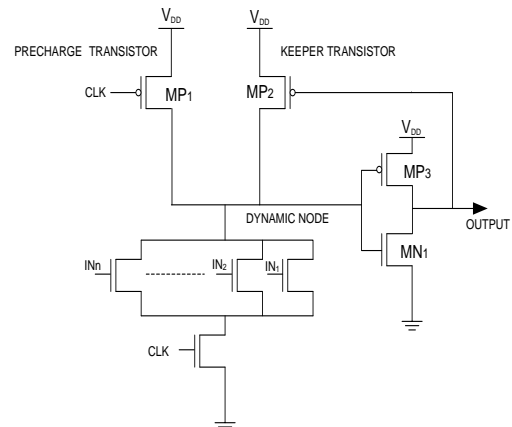


Fig.3 standard footed domino logic circuit

C. High Speed Domino Logic (HS)

The circuit of the HS Domino logic is shown in Fig.4 [6]. In HS domino the keeper transistor is driven by a combination of the output node and a delayed clock. The circuit works as follows: At the start of the evaluation phase, when clock is high, MP_3 turns on and then the keeper transistor MP_2 turns OFF. In this way, the contention between evaluation network and keeper transistor is reduced by turning off the keeper transistor at the beginning of evaluation mode. After the delay equals the delay of two inverters, transistor MP_3 turns off. At this moment, if the dynamic node has been discharged to

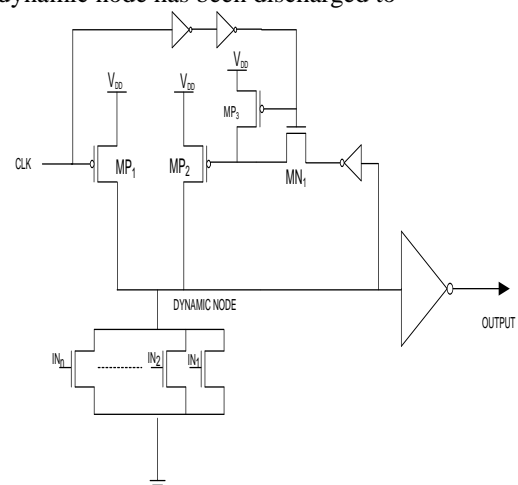


Fig.4 High Speed Domino Logic

ground, i.e. if any input goes high, the nMOS transistor MN_1 remains OFF. Thus the voltage at the gate of the keeper goes to $V_{DD}-V_{th}$ and not V_{DD} causing higher leakage current though the keeper transistor[7]. On the other hand, if the dynamic node remains high during the evaluation phase (all inputs at "0", standby mode), MN_1 turns on and pulls the gate of the keeper transistor. Thus keeper transistor will turn on to keep the dynamic node high, fighting the effects of leakage.

D. Conditional Keeper Domino Logic (CKD)

Conditional Keeper employs two keepers, small keeper and large keeper [8]. In this technique, the keeper device (PK) in conventional domino is divided into two smaller ones, PK1 and PK2. The keeper sizes are chosen such that $PK = PK1 + PK2$ [9]. Such sizing insures the same level of leakage tolerance as the conventional gate but yet improving the speed.

The circuit works as follows: in pre-charge phase when clock is low, the pull-up transistor is on, so the dynamic node starts being charge up to V_{DD} . At the beginning of evaluation phase when clock is high pre-charge transistors and large keeper PK1 are off. When all the inputs are at low logic level, i.e. in standby mode, the dynamic node after the delays of two inverters remains high, in this condition the output node of NAND gate goes low, this causes the large keeper PK1 to be turned on. The large keeper is deployed after a delay for two inverters, to prevent erroneous discharge of the dynamic node when all inputs remain LOW. The small keeper PK2; however remain ON to compensate for charge leakage until PK1 is activated.

E. Split Domino Logic (SDL)

As mentioned before, there are many parallel branches in a large fan-in dynamic OR gate. When the dynamic node voltage remains at V_{DD} , the nMOS pull-down branches cause a large amount of leakage current. The propagation delay is increased due the large parasitic capacitive effect as this parasitic capacitance must be discharged to zero during evaluation. Split-domino is a very smart technique that by splitting the pull-down network into smaller groups improves the operation of the gate by using small size of keeper in both

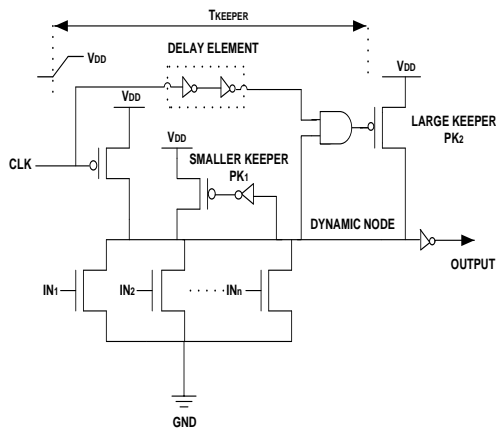
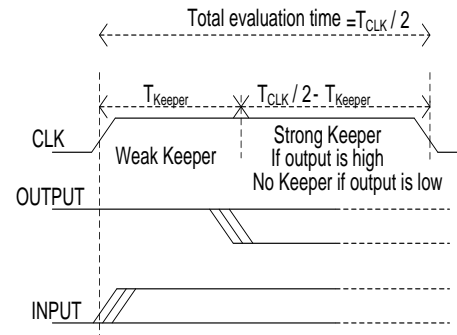


Fig.5 Conditional Keeper Domino Logic



Dynamic timing and strength variation of the CKD during the evaluation time

situations [10]. Therefore, in theory we need two keeper transistors with a width almost half as much as the conventional circuit. Fig.6 shows the 16-bit domino OR gate split in two. The circuit overhead is not as much as it might look, as there are two static inverters in the conventional domino circuit in place of two and three input NAND gates and besides they can be implemented using minimum size transistors. The circuit overhead is almost the same as the conditional keeper technique.

F. High Speed Clock Delay Domino Logic (HSCD)

Another proposed circuit topology of High Speed Clock Delay Domino circuit[11] is shown in Fig.7. In this circuit footer transistor MN_1 is added to the tail of the evaluation network, which employs stacking effect. Thus the noise immunity improves. At the beginning of the evaluation phase steady state voltage of N-FOOT node is uses to reduce leakage of the evaluation network. The circuit works as follow:

Precharge Mode: during the precharge mode when clock is low precharge transistor is turned on which charge the dynamic node to V_{DD} . in addition pMOS keeper transistor is turned on helping the precharge. MN_1 is also ON at the beginning of the evaluation phase which connects the N-FOOT node to ground. Furthermore, node GMN2 is low which is connected to the gate of MN_2 and thus MN_2 is OFF. After the delay equals to the delay of the two inverter (delay element), transistor MN_1 turns off. After the delay of an inverter, MN_1 turns off. In this case, the N-FOOT node voltage rises to an intermediate voltage level. To avoid any possibility of short circuit current in the precharge phase evaluation transistors are sized such that the DC voltage on GMN2 node does not exceed the threshold voltage of MN_2 .

Evaluation mode: in evaluation mode clock is high. There is two possibility first when all the inputs are low (standby mode) and second when any input is high(active mode).

Standby Mode: In standby mode, i.e. when all the inputs are at logic low level, nMOS footer transistor MN_1 is OFF at the

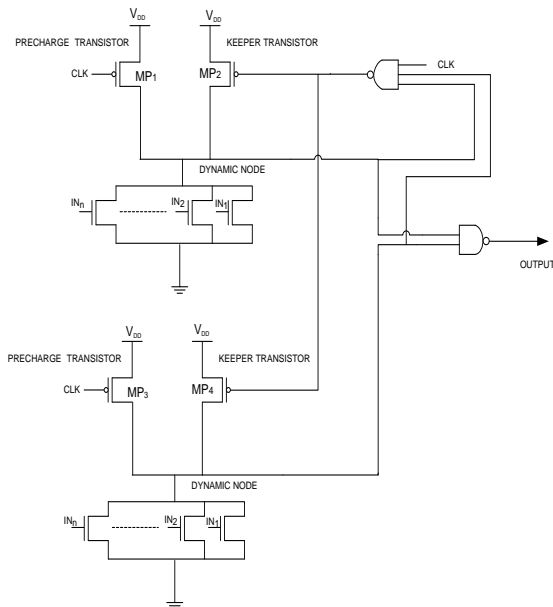


Fig.6 Split Domino Logic Circuit

beginning of the evaluation phase. Therefore, N-FOOT node voltage charges up to a DC voltage. This DC voltage reduces leakage of the evaluation network substantially resulting in significant leakage power reduction.

Active Mode: When any one of the input switches from low to high, the N-FOOT node voltage increases at the beginning of the evaluation phase which turns on transistor MP3.

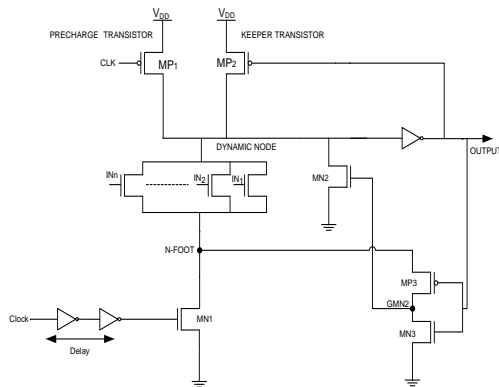


Fig.7 High Speed Clock Delay Domino Logic

Consequently, node GMN2 is charged to a voltage that is supplied by N-FOOT node voltage. Therefore, GMN2 voltage goes higher than the threshold voltage of MN₂ depending on the sizing of the transistors. Then at the onset of evaluation phase while the footer transistor MN₁ is OFF, nMOS transistor MN₂ turns on which connects the dynamic node to ground. However the size of the MN₂ decides the amount of discharging current through MN₂. After a delay equals to the delay of two inverters, N-FOOT node is connected to ground and the rest of evaluation phase is accomplished through the footer transistor, MN₁. When the dynamic node goes low, the output node becomes high, turning on MN₃ that leads to OFF MN₂. However, the rest of evaluation phase

(discharging of the dynamic node) completes through the evaluation network and the footer transistor that is fully on. Here we have more degree of freedom for increasing speed or enhancing noise immunity.

III. PERFORMANCE COMPARISON OF PRESENTED METHODES

Simulations are performed in 65 nm technology at 2 GHz frequency and V_{DD} of 1 V. The fall/rise times of the waveforms were set to 1pS. Considering the application of wide OR gates delay, power dissipation and UNG(Unit Noise Gain) has been calculated for 8 input and 16 input OR gate to compare different topologies.

For calculation of UNG [11], a pulse noise is applied to all inputs with amplitude which is a fraction of supply voltage and a pulse width equal to 30% of duty cycle. Then, the amplitude of the input noise pulse is increased until the amplitude of the resulting output noise voltage is equal to that of the input noise signal. This noise amplitude is defined as

$$UNG = \frac{V_{in,noise}}{V_{output}}$$

Transient Analysis

- Transient analysis shows a graph between inputs, outputs with respect to time axis. Fig.8 shows the waveform of inputs, outputs, clock and dynamic node voltage of 8 inputs OR gate based on proposed circuit and based on DCLCR logic style respectively.

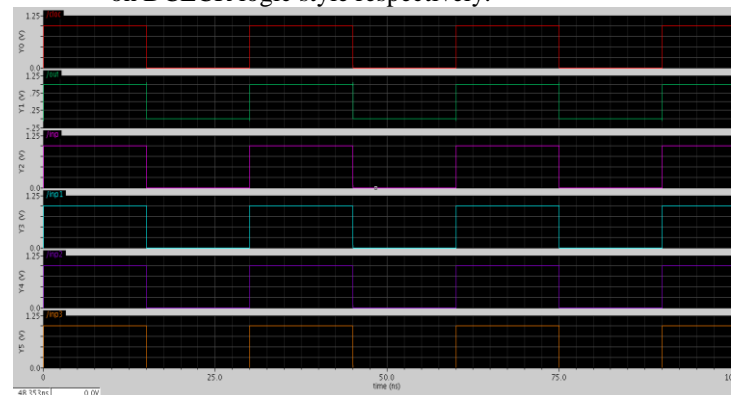


Fig. 8 Simulation results of 8 inputs DCLCD based OR gate

Area: This is the Layout Diagram for area Calculation of

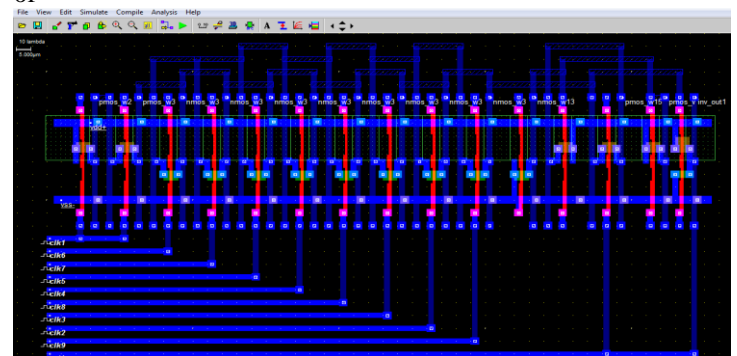


Fig.8 Layout Diagram

TABLE I
 Result for 8 Input OR gate

	Delay	UN G	Power dissipation	EVALUATION DELAY (ps)
SFLD	1	1	1	1
SFD	1.07	1.01	.85	8.14
CKD	1.01	.94	1.02	14.40
HS	.96	1.02	1.01	8.22
SD	.94	.93	1.11	11.39
HSCD	.93	3.1	1.02	13.80

TABLE II
 Result for 16 Input OR gate

	Delay	UNG	Power dissipation	EVALUATION DELAY (ps)
SFLD	1	1	1	1
SFD	1.09	1.03	0.87	17.54
CKD	1.05	0.9	1.05	11.96
HS	0.951	0.97	1.03	14.54
SD	0.921	0.95	1.25	17.98
HSCD	0.907	3.3	1.1	19.08

I. CONCLUSION

In this paper, several domino logic circuit topologies were proposed for high-speed and leakage-tolerant design. High speed clock delayed (HSCD) domino method has the best performance among others. HSCD has a speed improvement of 9% as compared to SFLD and noise immunity also increases. HSCD method can be used for very high speed circuit.

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