

## EXISTENCE OF NONOSCILLATORY SOLUTIONS OF SECOND ORDER LINEAR NEUTRAL DELAY DIFFERENCE EQUATIONS WITH FORCING TERM

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**Abstract.** This paper is concerned with the nonoscillation of second order linear neutral delay difference equations with forcing term. By using Banach's contraction mapping principle, authors obtain some sufficient conditions for the existence of nonoscillatory solutions. To support the results, we use MATLAB programming to illustrate the examples.

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### 1. INTRODUCTION

In this paper, we consider the second order neutral delay difference equation with forcing term of the form

$$\Delta(r(n)\Delta[x(n) + p(n)x(n-\tau)]) + q_1(n)x(n-\sigma_1) - q_2(n)x(n-\sigma_2) = e(n), \quad (1)$$

where  $n \geq n_0$ ,  $\tau > 0$ ,  $\sigma_1, \sigma_2 \geq 0$  are integers. We assume the following conditions:

$$(A1) \quad q_i > 0 \text{ and } \sum_{s=n_0}^{\infty} s q_i(n) < \infty, i = 1, 2$$

$$(A2) \quad \text{There exists a function } E(n) \in C^2([n_0, \infty), R) \text{ such that } \Delta^2(E(n)) = e(n) \text{ and } \lim_{n \rightarrow \infty} E(n) = M \in R.$$

The nonoscillatory behavior of linear and nonlinear neutral delay difference and differential equations with positive and negative coefficients have been investigated by several authors, see, for example [3], [4], [5], [6], [7], [8] and [9], the references cited therein. We refer monographs [1] and [2] for good amount of discussion concerning the existence of solution of delay difference equations. Our aim in this paper is to establish the nonoscillation criteria for the second order linear neutral delay difference equation (1) for various ranges of  $p(n)$

As is customary, a solution of equation (1) is said to be nonoscillatory if it is eventually positive or eventually negative. Otherwise, it will be called oscillatory. We define  $\rho = \max\{\tau, \sigma_1, \sigma_2\}$

**Theorem 1.1. (Banach's Contraction Principle [2]).** Let  $(X, d)$  be a complete metric space and let  $T$  be a contraction mapping on  $X$ . Then  $T$  has exactly one fixed point on  $X$ , that is, there exists exactly one  $x \in X$  such that  $Tx = x$

## 2. Main Results

**Theorem 2.2.** Suppose that conditions  $(A_1)$  and  $(A_2)$  hold and that there exists a constant  $p_1$  such that

$$0 < p(n) \leq p_1 < 1. \quad (2)$$

Then equation (1) has a nonoscillatory solution.

**Proof.** Suppose (2) holds. Choose constants  $N_1 \geq M_1 > 0$  and choose  $n_1 > n_0 + \rho$ , sufficiently large such that

$$\sum_{s=n_1}^{\infty} s [q_1(s) + q_2(s)] < \frac{3(1-p_1)}{4}, \quad (3)$$

$$\sum_{s=n_1}^{\infty} s q_1(s) \leq \frac{p_1 + N_1 - 1}{N_1}, \quad (4)$$

$$\sum_{s=n_1}^{\infty} s q_2(s) \leq \frac{1-p_1(1+2N_1) - 2M_1}{2N_1} \text{ and} \quad (5)$$

$$|E(n) - M| \leq \frac{1-p_1}{4}. \quad (6)$$

Let  $X$  be the set of all continuous and bounded functions on  $[n_0, \infty)$  with the sup norm. Define

$$A_1 = \{x \in X : M_1 \leq x(n) \leq N_1, n \geq n_0\}.$$

Define a mapping  $T_1 : A_1 \rightarrow X$  as follows:

$$(T_1 x)(n) = \begin{cases} \frac{3(1-p_1)}{4} - p(n)x(n-\tau) \\ + (n-1) \sum_{s=n}^{\infty} [q_1(s)x(s-\sigma_1) - q_2(s)x(s-\sigma_2)] \\ + \sum_{s=n_1}^{n-1} s [q_1(s)x(s-\sigma_1) - q_2(s)x(s-\sigma_2)] + E(n) - M, n \geq n_1 \\ (T_1 x)(n_1), n_0 \leq n \leq n_1. \end{cases}$$

Clearly,  $T_1 x$  is continuous. For every  $x \in A_1$  and  $n \geq n_1$  using (4) and (6), we obtain

$$(T_1 x)(n) \leq 1 - p_1 + N_1 \sum_{s=n_1}^{\infty} s q_1(s) \leq N_1.$$

Furthermore, in view of (5) and (6), we have

$$(T_1 x)(n) \geq \frac{1-p_1}{2} - p_1 N_1 - N_1 \sum_{s=n_1}^{\infty} s q_2(s) \geq M_1.$$

Thus we proved that  $T_1 A_1 \subset A_1$ . Since  $A_1$  is a bounded, closed and convex subset of  $X$ , we have to prove that  $T_1$  is a contraction mapping on  $A_1$  to apply the contraction principle.

Now, for  $x_1, x_2 \in A_1$  and  $n \geq n_1$ , in view of (3), we have

$$\begin{aligned} |(T_1 x_1)(n) - (T_1 x_2)(n)| &\leq \|x_1 - x_2\| \left\{ p_1 + \sum_{s=n_1}^{\infty} s [q_1(s) + q_2(s)] \right\} \\ &< \frac{3 + p_1}{4} \|x_1 - x_2\| \\ &= \lambda_1 \|x_1 - x_2\|. \end{aligned}$$

This implies that  $\|T_1 x_1 - T_1 x_2\| < \lambda_1 \|x_1 - x_2\|$ ,  $\lambda_1 < 1$ . This proves that  $T_1$  is a contraction mapping on  $A_1$ .  $T_1$  has the unique fixed point  $x$ , which is obviously a positive solution equation (1). This completes the proof.

**Theorem 2.2.** Suppose that conditions  $(A_1)$  and  $(A_2)$  hold and that there exists a constant  $p_2$  such that

$$-1 < -p_2 \leq p(n) < 0. \quad (7)$$

Then equation (1) has a nonoscillatory solution.

**Proof.** Suppose (7) holds. Choose constants  $N_2 \geq M_2 > 0$  and choose  $n_1 > n_0 + \rho$ , sufficiently large such that

$$\sum_{s=n_1}^{\infty} s [q_1(s) + q_2(s)] < \frac{3(1-p_2)}{4}, \quad (8)$$

$$\sum_{s=n_1}^{\infty} s q_1(s) \leq \frac{(1-p_2)(N_2-1)}{N_2}, \quad (9)$$

$$\sum_{s=n_1}^{\infty} s q_2(s) \leq \frac{(1-p_2)-2M_2}{N_2} \text{ and} \quad (10)$$

$$|E(n) - M| \leq \frac{1-p_2}{4}. \quad (11)$$

Let  $X$  be the set as in theorem 1. Define

$$A_2 = \{x \in X : M_2 \leq x(n) \leq N_2, n \geq n_0\}.$$

Define a mapping  $T_2 : A_2 \rightarrow X$  as follows:

$$(T_2x)(n) = \begin{cases} \frac{3(1-p_2)}{4} - p(n)x(n-\tau) \\ + (n-1) \sum_{s=n}^{\infty} [q_1(s)x(s-\sigma_1) - q_2(s)x(s-\sigma_2)] \\ + \sum_{s=n_1}^{n-1} s[q_1(s)x(s-\sigma_1) - q_2(s)x(s-\sigma_2)] + E(n) - M, n \geq n_1 \\ (T_2x)(n_1), n_0 \leq n \leq n_1. \end{cases}$$

Clearly,  $T_2x$  is continuous. For every  $x \in A_2$  and  $n \geq n_1$  using (9) and (11), we obtain

$$\begin{aligned} (T_2x)(n) &\leq 1 - p_2 + p_2N_2 + N_2 \sum_{s=n_1}^{\infty} sq_1(s) \\ &\leq N_2, n \geq n_1. \end{aligned}$$

Furthermore, in view of (10) and (11), we have

$$\begin{aligned} (T_2x)(n) &\geq \frac{1-p_2}{2} - N_2 \sum_{s=n_1}^{\infty} sq_2(s) \\ &\geq M_2, n \geq n_1. \end{aligned}$$

Thus we proved that  $T_2A_2 \subset A_2$ . Since  $A_2$  is a bounded, closed and convex subset of  $X$ , we have to prove that  $T_2$  is a contraction mapping on  $A_2$  to apply the contraction principle.

Now, for  $x_1, x_2 \in A_2$  and  $n \geq n_1$ , in view of (8), we have

$$\begin{aligned} |(T_2x_1)(n) - (T_2x_2)(n)| &\leq p_2 \|x_1 - x_2\| + \|x_1 - x_2\| \sum_{s=n_1}^{\infty} s [q_1(s) + q_2(s)] \\ &< \frac{p_2 + 3}{4} \|x_1 - x_2\| \\ &= \lambda_2 \|x_1 - x_2\|. \end{aligned}$$

This implies that  $\|T_2x_1 - T_2x_2\| < \lambda_2 \|x_1 - x_2\|$ ,  $\lambda_2 < 1$ . This proves that  $T_2$  is a contraction mapping on  $A_2$ . Consequently  $T_2$  has the unique fixed point  $x$ , which is obviously a positive solution of equation (1). This completes the proof.

**Theorem 2.3.** Suppose that conditions (A1) and (A2) hold and that there exist constants  $p_1$  and  $p_2$  such that

$$1 < p_2 \leq p(n) < p_1 < +\infty \tag{12}$$

Then equation (1) has a non oscillatory solution.

**Proof.** Suppose that (12) holds. Choose constants  $N_3 \geq M_3 > 0$  and choose  $n_1 > n_0 + \rho$  sufficiently large such that

$$\sum_{s=n_1}^{\infty} s[q_1(s) + q_2(s)] < \frac{3(p_2 - 1)}{4}, \quad (13)$$

$$\sum_{s=n_1}^{\infty} sq_1(s) \leq \frac{1 - p_2(1 - N_3)}{N_3}, \quad (14)$$

$$\sum_{s=n_1}^{\infty} sq_2(s) \leq \frac{p_2(p_2 - 1) - 2p_1(N_3 + p_2M_3)}{2p_1N_3} \quad \text{and} \quad (15)$$

$$|E(n) - M| \leq \frac{p_2 - 1}{4}. \quad (16)$$

Let  $X$  be the set as in Theorem 1. Define

$$A_3 = \{x \in X : M_3 \leq x(n) \leq N_3, n \geq n_0\}.$$

Define a mapping  $T_3 : A_3 \rightarrow X$  as follows:

$$(T_3x)(n) = \begin{cases} \frac{3(p_2 - 1)}{4p(n + \tau)} - \frac{x(n + \tau)}{p(n + \tau)} \\ + \frac{n - 1 + \tau}{p(n + \tau)} \sum_{s=n+\tau}^{\infty} [q_1(s)x(s - \sigma_1) - q_2(s)x(s - \sigma_2)] \\ + \frac{1}{p(n + \tau)} \sum_{s=n_1}^{n+\tau-1} s[q_1(s)x(s - \sigma_1) - q_2(s)x(s - \sigma_2)] + \frac{E(n + \tau) - M}{p(n + \tau)}, n \geq n_1 \\ (T_3x)(n_1), n_0 \leq n \leq n_1 \end{cases}$$

Clearly,  $T_3x$  is continuous. For every  $x \in A_3$  and  $n \geq n_1$  using (14) and (16), we get

$$\begin{aligned} (T_3x)(n) &\leq 1 - \frac{1}{p_2} + \frac{N_3}{p_2} \sum_{s=n_1}^{\infty} sq_1(s) \\ &\leq N_3, \quad n \geq n_1. \end{aligned}$$

Furthermore in view of (15) and (16), we have

$$\begin{aligned} (T_3x)(n) &\geq \frac{p_2 - 1}{2p_1} - \frac{N_3}{p_2} - \frac{N_3}{p_2} \sum_{s=n_1}^{\infty} sq_2(s) \\ &\geq M_3, \quad n \geq n_1 \end{aligned}$$

Thus we proved that  $T_3 A_3 \subset A_3$ . Since  $A_3$  is a bounded, closed and convex subset of  $X$  we have to prove that  $T_3$  is a contraction mapping on  $A_3$  to apply the contraction principle.

Now, for  $x_1, x_2 \in A_3$  and  $n \geq n_1$ , where in view of (13), we obtain

$$\begin{aligned} |(T_3 x_1)(n) - (T_3 x_2)(n)| &\leq \frac{1}{p_2} \|x_1 - x_2\| \left\{ 1 + \sum_{s=n_1}^{\infty} s[q_1(s) + q_2(s)] \right\} \\ &< \frac{3p_2 + 1}{4p_2} \|x_1 - x_2\| \\ &= \lambda_3 \|x_1 - x_2\|. \end{aligned}$$

This implies that  $\|T_3 x_1 - T_3 x_2\| < \lambda_3 \|x_1 - x_2\|$ , we have  $\lambda_3 < 1$ . This proves that  $T_3$  is contraction mapping on  $A_3$ . Consequently  $T_3$  has the unique fixed point  $x \in X$ , which is obviously a positive solution of equation (1). This completes the proof.

**Theorem 2.4.** Suppose that the conditions (A1) and (A2) hold and that there exist constants  $p_1$  and  $p_2$  such that

$$-\infty < -p_2 < p(n) \leq -p_1 < -1. \quad (17)$$

Then equation (1) has a nonoscillatory solution.

**Proof.** Suppose (17) holds, Choose constants  $N_4 \geq M_4 > 0$  and choose  $n_1 > n_0 + \rho$ , sufficiently large such that

$$\sum_{s=n_1}^{\infty} s[q_1(s) + q_2(s)] < \frac{3(p_1 - 1)}{4}, \quad (18)$$

$$\sum_{s=n_1}^{\infty} s q_1(s) \leq \frac{p_2 - p_1(1 + M_4)(p_2 - 1)}{p_2 N_4}, \quad (19)$$

$$\sum_{s=n_1}^{\infty} s q_2(s) \leq \frac{N_4(p_1 - 1) - p_1}{N_4} \quad \text{and} \quad (20)$$

$$|E(n) - M| \leq p_1 - 1 \quad (21)$$

Let  $X$  be the set as in theorem 1. Define

$$A_4 = \{x \in X : M_4 \leq x(n) \leq N_4, n \geq n_0\}.$$

Define a mapping  $T_4 : A_4 \rightarrow X$  as follows:

$$(T_4x)(n) = \begin{cases} -\frac{1}{p(n+\tau)} - \frac{x(n+\tau)}{p(n+\tau)} \\ + \frac{n-1+\tau}{p(n+\tau)} \sum_{s=n+\tau}^{\infty} [q_1(s)x(s-\sigma_1) - q_2(s)x(s-\sigma_2)] \\ + \frac{1}{p(n+\tau)} \sum_{s=n_1}^{n+\tau-1} s[q_1(s)x(s-\sigma_1) - q_2(s)x(s-\sigma_2)] + \frac{E(n+\tau) - M}{p(n+\tau)}, n \geq n_1 \\ (T_4x)(n_1), n_0 \leq n \leq n_1. \end{cases}$$

Clearly,  $T_4x$  is continuous. For every  $x \in A_4$  and  $n \geq n_1$  using (20) and (21), we obtain

$$\begin{aligned} (T_4x)(n) &\leq -\left(\frac{1+x(n+\tau)}{p(n+\tau)}\right) - \frac{1}{p(n+\tau)} \sum_{s=n_1}^{\infty} sq_2(s)x(s-\sigma_2) + \frac{E(n+\tau) - M}{p(n+\tau)} \\ &\leq \frac{1+N_4}{p_1} + \frac{N_4}{p_1} \sum_{s=n_1}^{\infty} sq_2(s) + \frac{p_1-1}{p_1} \\ &\leq N_4, \quad n \geq n_1. \end{aligned}$$

Furthermore in view of (19) and (20) we have

$$\begin{aligned} (T_4x)(n) &\geq -\left(\frac{1+x(n+\tau)}{p(n+\tau)}\right) + \frac{1}{p(n+\tau)} \sum_{s=n_1}^{\infty} sq_1(s)x(s-\sigma_1) + \frac{E(n+\tau) - M}{p(n+\tau)} \\ &\geq \frac{1+M_4}{p_2} - \frac{N_4}{p_1} \sum_{s=n_1}^{\infty} sq_1(s) - \frac{p_1-1}{p_1} \\ &\geq M_4, \quad n \geq n_1 \end{aligned}$$

Thus we proved that  $T_4A_4 \subset A_4$ . Since  $A_4$  is a bounded, closed and convex subset of  $X$ , we have to prove that  $T_4$  is a contraction mapping on  $A_4$  to apply the contraction principle.

Now, for  $x_1, x_2 \in A_4$  and  $n \geq n_1$ , in view of (18), we have

$$\begin{aligned} |(T_4x_1)(n) - (T_4x_2)(n)| &\leq \frac{1}{p_1} \|x_1 - x_2\| \left\{ 1 + \sum_{s=n_1}^{\infty} s[q_1(s) + q_2(s)] \right\} \\ &< \frac{3p_1+1}{4p_1} \|x_1 - x_2\| \\ &= \lambda_4 \|x_1 - x_2\|. \end{aligned}$$

This implies that  $\|T_4x_1 - T_4x_2\| < \lambda_4 \|x_1 - x_2\|$ , we get  $\lambda_4 < 1$ .

This proves that  $T_4$  is contraction mapping on  $A_4$ .  $T_4$  has the unique fixed point  $x \in X$ , which is obviously a positive solution of equation (1). This completes the proof.

**Example 2.5.** Consider the second order delay difference equation

$$\Delta^2(x(n) + e^{-n}x(n-1)) + 2e^{-n-2}x(n-1) - e^{-n}x(n-1) = e(n), \quad (22)$$

where  $p(n) = e^{-n}$ ,  $q_1(n) = 2e^{-n-2}$ ,  $q_2(n) = e^{-n}$ ,  $e(n) = e^{-n-2} - 2e^{-n-1} + e^{-n} + e^{-2n-3}$  such that

$0 < p(n) \leq e^{-n} < 1$ . Since  $E(n) \rightarrow 0$  as  $n \rightarrow \infty$ ,  $\sum_{s=n_1}^{\infty} sq_1(n) < \infty$  and  $\sum_{s=n_1}^{\infty} sq_2(n) < \infty$ . Then the sufficient conditions of Theorem 2.1 are satisfied. Therefore, the equation (22) has a positive solution.

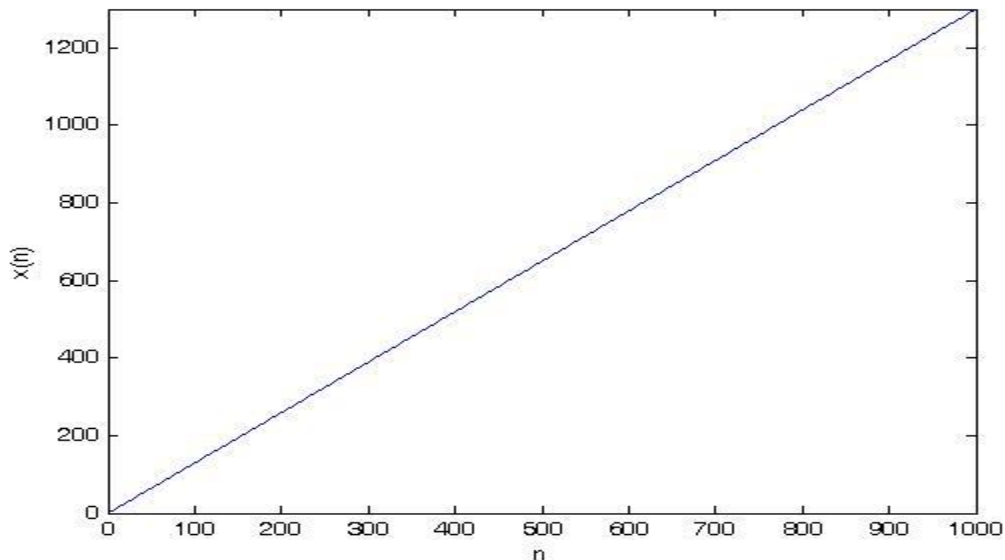


Figure 1

In Figure 1, the Nonoscillatory nature of equation (22) can be seen easily.

**Example 2.6.** Consider the second order delay difference equation.

$$\Delta^2(x(n) - (1 + e^{-n})x(n-1)) + e^{-n}x(n-1) - 2e^{-n-2}x(n-1) = e(n), \quad (23)$$

Where  $p(n) = -1 - e^{-n}$ ,  $q_1(n) = e^{-n}$ ,  $q_2(n) = 2e^{-n-2}$ ,  $e(n) = e^{-n-2} - 3e^{-n-1} + 3e^{-n} - e^{-n+1} + e^{-2n-3}$

such that  $-\infty < p(n) \leq -1$ . Since  $E(n) \rightarrow 0$  as  $n \rightarrow \infty$ ,  $\sum_{s=n_1}^{\infty} sq_1(n) < \infty$  and  $\sum_{s=n_1}^{\infty} sq_2(n) < \infty$ . Then the sufficient conditions of Theorem 2.4 are satisfied. Therefore, the equation (23) has a positive solution.



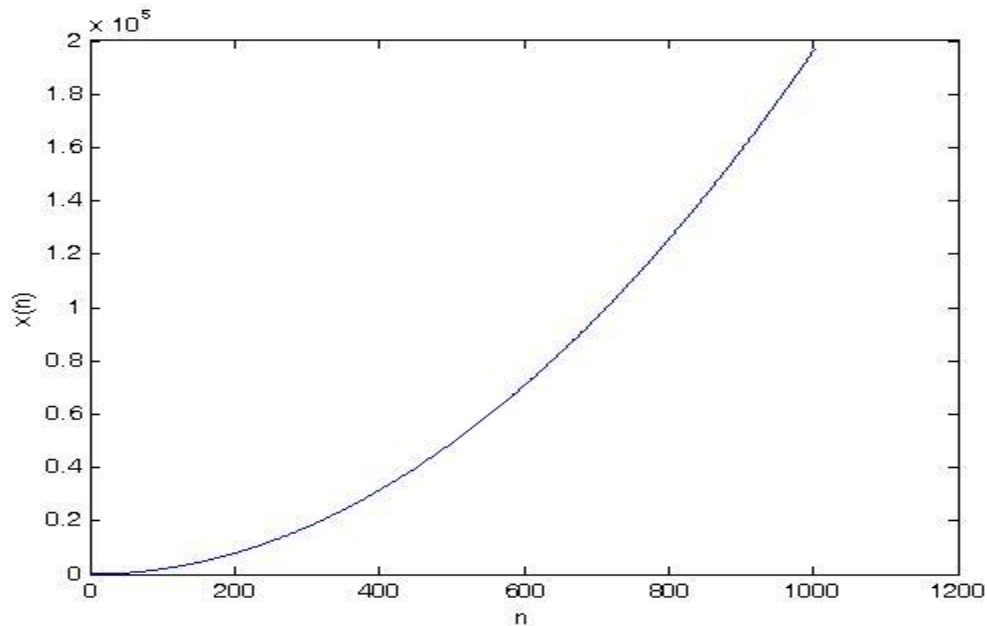


Figure 2

In Figure 2, the Nonoscillatory nature of equation (23) can be seen easily.

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